

Product datasheet

Specifications



variable speed drive ATV12 -
0.37kW - 0.55hp - 200..240V - 1ph -
with heat sink

ATV12H037M2

Main

| | |
|------------------------------|-------------------------|
| Range of product | Altivar 12 |
| Product or component type | Variable speed drive |
| Product specific application | Simple machine |
| Mounting mode | Cabinet mount |
| Communication port protocol | Modbus |
| Supply frequency | 50/60 Hz +/- 5 % |
| [Us] rated supply voltage | 200...240 V - 15...10 % |
| Nominal output current | 2.4 A |
| Motor power hp | 0.55 hp |
| Motor power kW | 0.37 kW 0.55 hp |
| EMC filter | Integrated |
| IP degree of protection | IP20 |

Complementary

| | |
|------------------------------|---|
| Discrete input number | 4 |
| Discrete output number | 2 |
| Analogue input number | 1 |
| Analogue output number | 1 |
| Relay output number | 1 |
| Physical interface | 2-wire RS 485 |
| Connector type | 1 RJ45 |
| Continuous output current | 2.4 A at 4 kHz |
| Method of access | Server Modbus serial |
| Speed drive output frequency | 0.5...400 Hz |
| Speed range | 1...20 |
| Sampling duration | 20 ms, tolerance +/- 1 ms for logic input 10 ms for analogue input |
| Linearity error | +/- 0.3 % of maximum value for analogue input |
| Frequency resolution | Analog input: converter A/D, 10 bits |

Display unit: 0.1 Hz

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|---|--|
| Time constant | 20 ms +/- 1 ms for reference change |
| Transmission rate | 9.6 kbit/s 19.2 kbit/s 38.4 kbit/s |
| Transmission frame | RTU |
| Number of addresses | 1...247 |
| Data format | 8 bits, configurable odd, even or no parity |
| Communication service | Read holding registers (03) 29 words Write single register (06) 29 words Write multiple registers (16) 27 words Read/write multiple registers (23) 4/4 words Read device identification (43) |
| Type of polarization | No impedance |
| 4 quadrant operation possible | False |
| Asynchronous motor control profile | Sensorless flux vector control Voltage/frequency ratio (V/f) Quadratic voltage/frequency ratio |
| Maximum output frequency | 4 kHz |
| Transient overtorque | 150...170 % of nominal motor torque depending on drive rating and type of motor |
| Acceleration and deceleration ramps | Linear from 0 to 999.9 s S U |
| Motor slip compensation | Adjustable Preset in factory |
| Switching frequency | 2...16 kHz adjustable 4...16 kHz with derating factor |
| Nominal switching frequency | 4 kHz |
| Braking to standstill | By DC injection |
| Brake chopper integrated | False |
| Line current | 5.9 A at 100 V (heavy duty) 4.9 A at 120 V (heavy duty) |
| Maximum input current | 4.9 A |
| Maximum output voltage | 240 V |
| Apparent power | 1.2 kVA at 240 V (heavy duty) |
| Maximum transient current | 3.6 A during 60 s (heavy duty) 4.0 A during 2 s (heavy duty) |
| Network frequency | 50...60 Hz |
| Relative symmetric network frequency tolerance | 5 % |
| Prospective line I_{sc} | 1 kA |
| Base load current at high overload | 2.4 A |
| Power dissipation in W | Natural: 27.0 W |
| With safety function Safely Limited Speed (SLS) | False |
| With safety function Safe brake management (SBC/SBT) | False |
| With safety function Safe Operating Stop (SOS) | False |
| With safety function Safe Position (SP) | False |
| With safety function Safe programmable logic | False |

| | |
|--|---|
| With safety function Safe Speed Monitor (SSM) | False |
| With safety function Safe Stop 1 (SS1) | False |
| With sft fct Safe Stop 2 (SS2) | False |
| With safety function Safe torque off (STO) | False |
| With safety function Safely Limited Position (SLP) | False |
| With safety function Safe Direction (SDI) | False |
| Protection type | Line supply overvoltage Line supply undervoltage Overcurrent between output phases and earth Overheating protection Short-circuit between motor phases Against input phase loss in three-phase Thermal motor protection via the drive by continuous calculation of I ² t |
| Tightening torque | 0.8 N.m |
| Insulation | Electrical between power and control |
| Quantity per set | Set of 1 |
| Width | 72 mm |
| Height | 143 mm |
| Depth | 121.2 mm |
| Net weight | 0.7 kg |

Environment

| | |
|--|--|
| Operating altitude | > 1000...2000 m with current derating 1 % per 100 m <= 1000 m without derating |
| Operating position | Vertical +/- 10 degree |
| Product certifications | NOM CSA C-Tick UL GOST RCM KC |
| Marking | CE |
| Standards | UL 508C UL 618000-5-1 EN/IEC 61800-5-1 EN/IEC 61800-3 |
| Assembly style | With heat sink |
| Electromagnetic compatibility | Electrical fast transient/burst immunity test level 4 conforming to EN/IEC 61000-4-4 Electrostatic discharge immunity test level 3 conforming to EN/IEC 61000-4-2 Immunity to conducted disturbances level 3 conforming to EN/IEC 61000-4-6 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to EN/IEC 61000-4-3 Surge immunity test level 3 conforming to EN/IEC 61000-4-5 Voltage dips and interruptions immunity test conforming to EN/IEC 61000-4-11 |
| Environmental class (during operation) | Class 3C3 according to IEC 60721-3-3 Class 3S2 according to IEC 60721-3-3 |
| Maximum acceleration under shock impact (during operation) | 150 m/s ² at 11 ms |
| Maximum acceleration under vibrational stress (during operation) | 10 m/s ² at 13...200 Hz |
| Maximum deflection under vibratory load (during operation) | 1.5 mm at 2...13 Hz |
| Overvoltage category | Class III |

| | |
|--|--|
| Regulation loop | Adjustable PID regulator |
| Electromagnetic emission | Radiated emissions environment 1 category C2 conforming to EN/IEC 61800-3 2...16 kHz shielded motor cable Conducted emissions with integrated EMC filter environment 1 category C1 conforming to EN/IEC 61800-3 2, 4, 8, 12 and 16 kHz shielded motor cable <5 m Conducted emissions with integrated EMC filter environment 1 category C2 conforming to EN/IEC 61800-3 2...12 kHz shielded motor cable <5 m Conducted emissions with integrated EMC filter environment 1 category C2 conforming to EN/IEC 61800-3 2, 4 and 16 kHz shielded motor cable <10 m Conducted emissions with additional EMC filter environment 1 category C1 conforming to EN/IEC 61800-3 4...12 kHz shielded motor cable <20 m Conducted emissions with additional EMC filter environment 1 category C2 conforming to EN/IEC 61800-3 4...12 kHz shielded motor cable <50 m Conducted emissions with additional EMC filter environment 2 category C3 conforming to EN/IEC 61800-3 4...12 kHz shielded motor cable <50 m |
| Vibration resistance | 1 gn (f = 13...200 Hz) conforming to EN/IEC 60068-2-6 1.5 mm peak to peak (f = 3...13 Hz) - drive unmounted on symmetrical DIN rail - conforming to EN/IEC 60068-2-6 |
| Shock resistance | 15 gn conforming to EN/IEC 60068-2-27 for 11 ms |
| Relative humidity | 5...95 % without condensation conforming to IEC 60068-2-3 5...95 % without dripping water conforming to IEC 60068-2-3 |
| Noise level | 0 dB |
| Pollution degree | 2 |
| Ambient air transport temperature | -25...70 °C |
| Ambient air temperature for operation | -10...40 °C without derating 40...60 °C with current derating 2.2 % per °C |
| Ambient air temperature for storage | -25...70 °C |

Packing Units

| | |
|-------------------------------------|-----------|
| Unit Type of Package 1 | PCE |
| Number of Units in Package 1 | 1 |
| Package 1 Height | 12.600 cm |
| Package 1 Width | 20.000 cm |
| Package 1 Length | 18.700 cm |
| Package 1 Weight | 1.035 kg |
| Unit Type of Package 2 | P06 |
| Number of Units in Package 2 | 45 |
| Package 2 Height | 75.000 cm |
| Package 2 Width | 60.000 cm |
| Package 2 Length | 80.000 cm |
| Package 2 Weight | 59.530 kg |

Offer Sustainability

| | |
|-----------------------------------|---|
| Sustainable offer status | Green Premium product |
| REACH Regulation | REACH Declaration |
| EU RoHS Directive | Pro-active compliance (Product out of EU RoHS legal scope) EU RoHS Declaration |
| Mercury free | Yes |
| China RoHS Regulation | China RoHS declaration |
| RoHS exemption information | Yes |
| Environmental Disclosure | Product Environmental Profile |
| Circularity Profile | End of Life Information |

WEEE

The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins

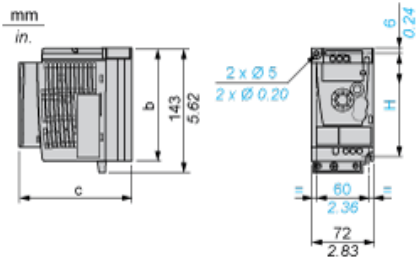
Contractual warranty

Warranty

18 months

Dimensions

Drive without EMC Conformity Kit



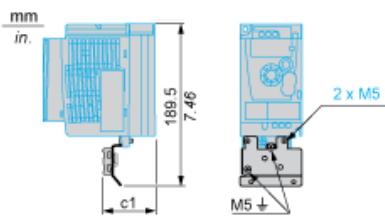
Dimensions in mm

| b | c | H |
|-----|-------|-----|
| 130 | 121.2 | 120 |

Dimensions in in.

| b | c | H |
|------|------|------|
| 5.12 | 4.77 | 4.72 |

Drive with EMC Conformity Kit



Dimensions in mm

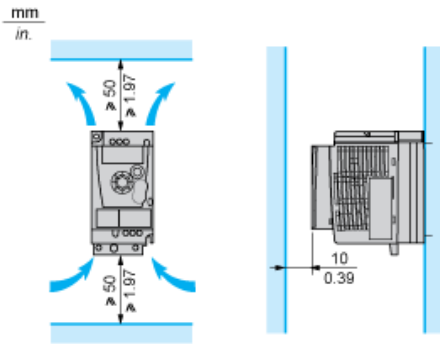
| c1 |
|----|
| 53 |

Dimensions in in.

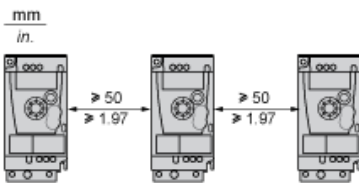
| c1 |
|------|
| 2.09 |

Mounting Recommendations

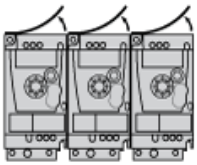
Clearance for Vertical Mounting



Mounting Type A

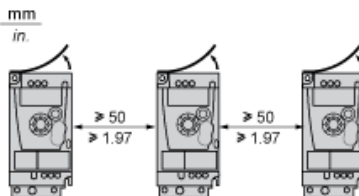


Mounting Type B



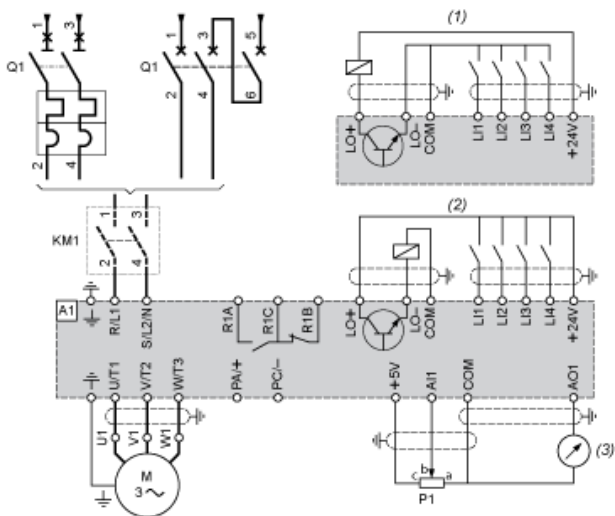
Remove the protective cover from the top of the drive.

Mounting Type C



Remove the protective cover from the top of the drive.

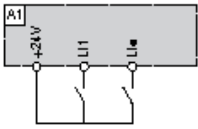
Single-Phase Power Supply Wiring Diagram



- A1** Drive
- KM1** Contactor (only if a control circuit is needed)
- P1** 2.2 kΩ reference potentiometer. This can be replaced by a 10 kΩ potentiometer (maximum).
- Q1** Circuit breaker
- (1)** Negative logic (Sink)
- (2)** Positive logic (Source) (factory set configuration)
- (3)** 0...10 V or 0...20 mA

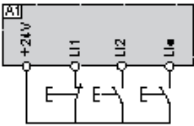
Recommended Schemes

2-Wire Control for Logic I/O with Internal Power Supply



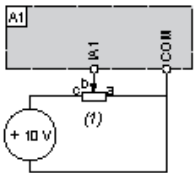
LI1 : Forward
LIe : Reverse
A1 : Drive

3-Wire Control for Logic I/O with Internal Power Supply



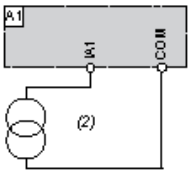
LI1 : Stop
LI2 : Forward
LIe : Reverse
A1 : Drive

Analog Input Configured for Voltage with Internal Power Supply



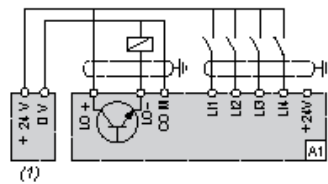
(1) 2.2 kΩ...10 kΩ reference potentiometer
A1 : Drive

Analog Input Configured for Current with Internal Power Supply



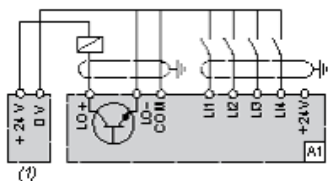
(2) 0-20 mA 4-20 mA supply
A1 : Drive

Connected as Positive Logic (Source) with External 24 vdc Supply



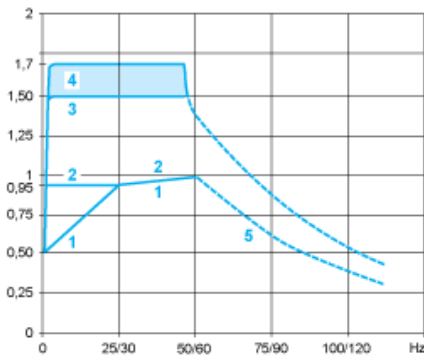
(1) 24 vdc supply
A1 : Drive

Connected as Negative Logic (Sink) with External 24 vdc supply



(1) 24 vdc supply
A1 : Drive

Torque Curves



- 1 : Self-cooled motor: continuous useful torque (1)
- 2 : Force-cooled motor: continuous useful torque
- 3 : Transient overtorque for 60 s
- 4 : Transient overtorque for 2 s
- 5 : Torque in overspeed at constant power (2)
- (1) For power ratings ≤ 250 W, derating is 20% instead of 50% at very low frequencies.
- (2) The nominal motor frequency and the maximum output frequency can be adjusted from 0.5 to 400 Hz. The mechanical overspeed capability of the motor is 150%.

Recommended replacement(s)