Specifications



① Discontinued - Service only

# ATV61 11 kW 15 HP 240 V 3 phases without EMC IP20

ATV61HD11M3X

- () Discontinued on: Jan 23, 2021 AD
- () To be end-of-service on: Jan 1, 2025 AD

## Main

| Range Of Product                     | Altivar 61   |
|--------------------------------------|--|
| Product Or Component Type            | Variable speed drive   |
| Product Specific Application         | Pumping and ventilation machine  |
| Component Name                       | ATV61  |
| Motor Power Kw                       | 11 kW, 3 phases at 200240 V  |
| Motor Power Hp                       | 15 hp, 3 phases at 200240 V  |
| Power Supply Voltage                 | 200240 V - 1510 %  |
| Supply Number Of Phases              | 3 phases   |
| Line Current                         | 45.8 A for 240 V 3 phases 11 kW / 15 hp<br>53.3 A for 200 V 3 phases 11 kW / 15 hp   |
| Emc Filter                           | Without EMC filter   |
| Assembly Style                       | With heat sink   |
| Apparent Power                       | 19 kVA at 240 V 3 phases 11 kW / 15 hp   |
| Maximum Prospective Line Isc         | 22 kA for 3 phases   |
| Maximum Transient Current            | 64.8 A for 60 s, 3 phases  |
| Nominal Switching Frequency          | 12 kHz   |
| Switching Frequency                  | 116 kHz adjustable<br>1216 kHz with derating factor  |
| Asynchronous Motor Control           | Voltage/frequency ratio, 2 points<br>Voltage/frequency ratio - Energy Saving, quadratic U/f<br>Voltage/frequency ratio, 5 points<br>Flux vector control without sensor, standard |
| Synchronous Motor Control<br>Profile | Vector control without sensor, standard  |
| Communication Port Protocol          | CANopen<br>Modbus  |
| Type Of Polarization                 | No impedance for Modbus  |

Type Of Polarization

No impedance for Modbus

#### Option Card

|   | Communication card for APOGEE FLN        |
|---|--|
|   | Communication card for BACnet            |
|   | Communication card for CC-Link           |
|   | Controller inside programmable card      |
|   | Communication card for DeviceNet         |
|   | Communication card for EtherNet/IP       |
|   | Communication card for Fipio             |
|   | I/O extension card                       |
| ( | Communication card for Interbus-S        |
|   | Communication card for LonWorks          |
|   | Communication card for METASYS N2        |
|   | Communication card for Modbus Plus       |
| ( | Communication card for Modbus TCP        |
| ( | Communication card for Modbus/Uni-Telway |
| l | Multi-pump card                          |
|   | Communication card for Profibus DP       |
| • | Communication card for Profibus DP V1    |

## Complementary

| Product Destination Power Supply Voltage Limits Power Supply Frequency Power Supply Frequency Limits Continuous Output Current Output Frequency Speed Range Speed Accuracy Torque Accuracy Transient Overtorque Braking Torque Regulation Loop Motor Slip Compensation Diagnostic Output Voltage Electrical Isolation Type Of Cable For Mounting In An Enclosure Electrical Connection | Asynchronous motors         Synchronous motors         170264 V         5060 Hz - 55 %         47.563 Hz         54 A at 12 kHz, 230 V - 3 phases         0.1599 Hz         1100 in open-loop mode, without speed feedback         +/- 10 % of nominal slip 0.2 Tn to Tn without speed feedback         +/- 15 % in open-loop mode, without speed feedback         130 % of nominal motor torque +/- 10 % for 60 s         <= 125 % with braking resistor         30 % without braking resistor         So % without braking resistor         Automatic whatever the load         Can be suppressed |
|--|---|
| Power Supply Frequency Power Supply Frequency Limits Continuous Output Current Output Frequency Speed Range Speed Accuracy Torque Accuracy Transient Overtorque Braking Torque Regulation Loop Motor Slip Compensation Diagnostic Output Voltage Electrical Isolation Type Of Cable For Mounting In An Enclosure   | 5060 Hz - 55 %         47.563 Hz         54 A at 12 kHz, 230 V - 3 phases         0.1599 Hz         1100 in open-loop mode, without speed feedback         +/- 10 % of nominal slip 0.2 Tn to Tn without speed feedback         +/- 15 % in open-loop mode, without speed feedback         130 % of nominal motor torque +/- 10 % for 60 s         <= 125 % with braking resistor   |
| Power Supply Frequency Limits<br>Continuous Output Current<br>Output Frequency<br>Speed Range<br>Speed Accuracy<br>Torque Accuracy<br>Transient Overtorque<br>Braking Torque<br>Regulation Loop<br>Motor Slip Compensation<br>Diagnostic<br>Output Voltage<br>Electrical Isolation<br>Type Of Cable For Mounting In An<br>Enclosure  | 47.563 Hz         54 A at 12 kHz, 230 V - 3 phases         0.1599 Hz         1100 in open-loop mode, without speed feedback         +/- 10 % of nominal slip 0.2 Tn to Tn without speed feedback         +/- 15 % in open-loop mode, without speed feedback         +/- 15 % in open-loop mode, without speed feedback         130 % of nominal motor torque +/- 10 % for 60 s         <= 125 % with braking resistor   |
| Continuous Output Current<br>Output Frequency<br>Speed Range<br>Speed Accuracy<br>Torque Accuracy<br>Transient Overtorque<br>Braking Torque<br>Regulation Loop<br>Motor Slip Compensation<br>Diagnostic<br>Output Voltage<br>Electrical Isolation<br>Type Of Cable For Mounting In An<br>Enclosure   | 54 A at 12 kHz, 230 V - 3 phases         0.1599 Hz         1100 in open-loop mode, without speed feedback         +/- 10 % of nominal slip 0.2 Tn to Tn without speed feedback         +/- 15 % in open-loop mode, without speed feedback         130 % of nominal motor torque +/- 10 % for 60 s         <= 125 % with braking resistor  |
| Output Frequency Speed Range Speed Accuracy Torque Accuracy Transient Overtorque Braking Torque Regulation Loop Motor Slip Compensation Diagnostic Output Voltage Electrical Isolation Type Of Cable For Mounting In An Enclosure  | 0.1599 Hz         1100 in open-loop mode, without speed feedback         +/- 10 % of nominal slip 0.2 Tn to Tn without speed feedback         +/- 15 % in open-loop mode, without speed feedback         130 % of nominal motor torque +/- 10 % for 60 s         <= 125 % with braking resistor   |
| Speed Range<br>Speed Accuracy<br>Torque Accuracy<br>Transient Overtorque<br>Braking Torque<br>Regulation Loop<br>Motor Slip Compensation<br>Diagnostic<br>Output Voltage<br>Electrical Isolation<br>Type Of Cable For Mounting In An<br>Enclosure  | 1100 in open-loop mode, without speed feedback         +/- 10 % of nominal slip 0.2 Tn to Tn without speed feedback         +/- 15 % in open-loop mode, without speed feedback         130 % of nominal motor torque +/- 10 % for 60 s         <= 125 % with braking resistor   |
| Speed Accuracy Torque Accuracy Transient Overtorque Braking Torque Regulation Loop Motor Slip Compensation Diagnostic Output Voltage Electrical Isolation Type Of Cable For Mounting In An Enclosure   | +/- 10 % of nominal slip 0.2 Tn to Tn without speed feedback<br>+/- 15 % in open-loop mode, without speed feedback<br>130 % of nominal motor torque +/- 10 % for 60 s<br><= 125 % with braking resistor<br>30 % without braking resistor<br>Frequency PI regulator<br>Not available in voltage/frequency ratio (2 or 5 points)<br>Automatic whatever the load   |
| Torque Accuracy Transient Overtorque Braking Torque Regulation Loop Motor Slip Compensation Diagnostic Output Voltage Electrical Isolation Type Of Cable For Mounting In An Enclosure  | +/- 15 % in open-loop mode, without speed feedback<br>130 % of nominal motor torque +/- 10 % for 60 s<br><= 125 % with braking resistor<br>30 % without braking resistor<br>Frequency PI regulator<br>Not available in voltage/frequency ratio (2 or 5 points)<br>Automatic whatever the load   |
| Transient Overtorque<br>Braking Torque<br>Regulation Loop<br>Motor Slip Compensation<br>Diagnostic<br>Output Voltage<br>Electrical Isolation<br>Type Of Cable For Mounting In An<br>Enclosure  | 130 % of nominal motor torque +/- 10 % for 60 s         <= 125 % with braking resistor  |
| Braking Torque<br>Regulation Loop<br>Motor Slip Compensation<br>Diagnostic<br>Output Voltage<br>Electrical Isolation<br>Type Of Cable For Mounting In An<br>Enclosure  | <= 125 % with braking resistor<br>30 % without braking resistor<br>Frequency PI regulator<br>Not available in voltage/frequency ratio (2 or 5 points)<br>Automatic whatever the load  |
| Regulation Loop<br>Motor Slip Compensation<br>Diagnostic<br>Output Voltage<br>Electrical Isolation<br>Type Of Cable For Mounting In An<br>Enclosure  | 30 % without braking resistor Frequency PI regulator Not available in voltage/frequency ratio (2 or 5 points) Automatic whatever the load   |
| Motor Slip Compensation<br>Diagnostic<br>Output Voltage<br>Electrical Isolation<br>Type Of Cable For Mounting In An<br>Enclosure   | Not available in voltage/frequency ratio (2 or 5 points)<br>Automatic whatever the load   |
| Diagnostic<br>Output Voltage<br>Electrical Isolation<br>Type Of Cable For Mounting In An<br>Enclosure  | Automatic whatever the load   |
| Output Voltage<br>Electrical Isolation<br>Type Of Cable For Mounting In An<br>Enclosure  | Adjustable  |
| Electrical Isolation<br>Type Of Cable For Mounting In An<br>Enclosure  | 1 LED (red) for drive voltage   |
| Type Of Cable For Mounting In An<br>Enclosure  | <= power supply voltage   |
| Enclosure  | Between power and control terminals   |
| Electrical Connection  | With an IP21 or an IP31 kit: 3 wire(s)IEC cable at 40 °C, copper 70 °C / PVC<br>With UL Type 1 kit: 3 wire(s)UL 508 cable at 40 °C, copper 75 °C / PVC<br>Without mounting kit: 1 wire(s)IEC cable at 45 °C, copper 70 °C / PVC<br>Without mounting kit: 1 wire(s)IEC cable at 45 °C, copper 90 °C / XLPE/EPR   |
|  | Terminal 2.5 mm² / AWG 14 (Al1-/Al1+, Al2, AO1, R1A, R1B, R1C, R2A, R2B,<br>Ll1Ll6, PWR)<br>Terminal 25 mm² / AWG 3 (L1/R, L2/S, L3/T, U/T1, V/T2, W/T3, PC/-, PO, PA/+, PA,<br>PB)   |
| Tightening Torque  | 0.6 N.m (Al1-/Al1+, Al2, AO1, R1A, R1B, R1C, R2A, R2B, L11L16, PWR)<br>5.4 N.m, 47.7 Ib.in (L1/R, L2/S, L3/T, U/T1, V/T2, W/T3, PC/-, PO, PA/+, PA, PB)   |
| Supply   |   |
| Analogue Input Number  | Internal supply for reference potentiometer (1 to 10 kOhm): 10.5 V DC, +/- 5 %, <10<br>mA with overload and short-circuit protection<br>Internal supply: 24 V DC (2127 V), <200 mA with overload and short-circuit<br>protection<br>External supply: 24 V DC (1930 V)   |

| Analogue Input Type                    | Al1-/Al1+ bipolar differential voltage: +/- 10 V DC 24 V max, resolution 11 bits + sign<br>Al2 software-configurable current: 020 mA, impedance: 242 Ohm, resolution 11<br>bits |
|--|---|
|  | Al2 software-configurable voltage: 010 V DC 24 V max, impedance: 30000 Ohm, resolution 11 bits  |
| Sampling Time                          | 2 ms +/- 0.5 ms (AI1-/AI1+) - analog input  |
|  | 2 ms +/- 0.5 ms (Al2) - analog input  |
|  | 2 ms +/- 0.5 ms (AO1) - analog output<br>2 ms +/- 0.5 ms (LI1LI5) - discrete input  |
|  | 2 ms +/- 0.5 ms (LI6)if configured as logic input - discrete input  |
| Absolute Accuracy Precision            | +/- 0.6 % (AI1-/AI1+) for a temperature variation 60 °C   |
|  | +/- 0.6 % (Al2) for a temperature variation 60 °C   |
|  | +/- 1 % (AO1) for a temperature variation 60 °C   |
| inearity Error                         | +/- 0.15 % of maximum value (AI1-/AI1+)   |
|  | +/- 0.15 % of maximum value (Al2)<br>+/- 0.2 % (AO1)  |
|  | +7- 0.2 /0 (AOT)  |
| Analogue Output Number                 | 1   |
| Analogue Output Type                   | AO1 software-configurable current, analogue output range 020 mA, impedance:   |
|  | 500 Ohm, resolution 10 bits<br>AO1 software-configurable voltage, analogue output range 010 V DC, impedance:  |
|  | 470 Ohm, resolution 10 bits   |
|  | AO1 software-configurable logic output 10 V, 20 mA  |
| Discrete Output Number                 | 2   |
| Discrete Output Type                   | Configurable relay logic: (R1A, R1B, R1C) NO/NC - 100000 cycles   |
|  | Configurable relay logic: (R2A, R2B) NO - 100000 cycles   |
| Aaximum Response Time                  | <= 100 ms in STO (Safe Torque Off)  |
|  | R1A, R1B, R1C <= 7 ms, tolerance +/- 0.5 ms   |
|  | R2A, R2B <= 7 ms, tolerance +/- 0.5 ms  |
| Iinimum Switching Current              | 3 mA at 24 V DC for configurable relay logic  |
| Maximum Switching Current              | R1, R2: 2 A at 250 V AC inductive load, cos phi = 0.4 and L/R = 7 ms  |
|  | R1, R2: 2 A at 30 V DC inductive load, cos phi = 0.4 and L/R = 7 ms<br>R1, R2: 5 A at 250 V AC resistive load, cos phi = 1 and L/R = 0 ms                                       |
|  | R1, R2: 5 A at 30 V DC resistive load, cos phi = 1 and $L/R = 0$ ms   |
| Discrete Input Number                  | 7   |
| Discrete Input Type                    | Programmable (LI1LI5)24 V DC (<= 30 V), with level 1 PLC - 3500 Ohm   |
|  | Switch-configurable (LI6)24 V DC (<= 30 V), with level 1 PLC - 3500 Ohm   |
|  | Switch-configurable PTC probe (LI6)06 probes - 1500 Ohm<br>Safety input (PWR)24 V DC (<= 30 V) - 1500 Ohm   |
| Discusts lumit Louis                   |   |
| Discrete Input Logic                   | Negative logic (sink) (LI1LI5), > 16 V (state 0), < 10 V (state 1)<br>Positive logic (source) (LI1LI5), < 5 V (state 0), > 11 V (state 1)                                       |
|  | Negative logic (sink) (LI6)if configured as logic input, > 16 V (state 0), < 10 V (state 1)   |
|  | Positive logic (source) (LI6)if configured as logic input, < 5 V (state 0), > 11 V (state   |
|  | 1)  |
| Acceleration And Deceleration          | Linear adjustable separately from 0.01 to 9000 s  |
| Ramps                                  | Automatic adaptation of ramp if braking capacity exceeded, by using resistor<br>S, U or customized  |
| Braking To Standstill                  | By DC injection   |
| Protection Type                        | Against exceeding limit speed: drive  |
| ······································ | Against exceeding infinitispeed, drive  |
|  | Break on the control circuit: drive   |
|  | Input phase breaks: drive<br>Line supply overvoltage: drive   |
|  | Line supply overvoltage: drive  |
|  | Overcurrent between output phases and earth: drive  |
|  | Overheating protection: drive   |
|  | Overvoltages on the DC bus: drive<br>Power removal: drive   |
|  | Short-circuit between motor phases: drive   |
|  | Thermal protection: drive   |
|  | Motor phase break: motor<br>Power removal: motor  |
|  | Thermal protection: motor   |
| nsulation Resistance                   | > 1 mOhm 500 V DC for 1 minute to earth   |
|  |   |

| Frequency Resolution | Analog input: 0.024/50 Hz  |  |  |  |  |
|----------------------|--|--|--|--|--|
|                      | Display unit: 0.1 Hz   |  |  |  |  |
| Connector Type       | 1 RJ45 (on front face) for Modbus                                  |  |  |  |  |
|                      | 1 RJ45 (on terminal) for Modbus                                    |  |  |  |  |
|                      | Male SUB-D 9 on RJ45 for CANopen                                   |  |  |  |  |
| Physical Interface   | 2-wire RS 485 for Modbus   |  |  |  |  |
| Transmission Frame   | RTU for Modbus   |  |  |  |  |
| Transmission Rate    | 4800 bps, 9600 bps, 19200 bps, 38.4 Kbps for Modbus on terminal    |  |  |  |  |
|                      | 9600 bps, 19200 bps for Modbus on front face                       |  |  |  |  |
|                      | 20 kbps, 50 kbps, 125 kbps, 250 kbps, 500 kbps, 1 Mbps for CANopen |  |  |  |  |
| Data Format          | 8 bits, 1 stop, even parity for Modbus on front face               |  |  |  |  |
|                      | 8 bits, odd even or no configurable parity for Modbus on terminal  |  |  |  |  |
| Number Of Addresses  | 1127 for CANopen   |  |  |  |  |
|                      | 1247 for Modbus  |  |  |  |  |
| Method Of Access     | Slave CANopen  |  |  |  |  |
| Marking              | CE   |  |  |  |  |
| Operating Position   | Vertical +/- 10 degree   |  |  |  |  |
| Net Weight           | 22 kg  |  |  |  |  |
| Width                | 230 mm   |  |  |  |  |
| Height               | 400 mm   |  |  |  |  |
| Depth                | 213 mm   |  |  |  |  |

## Environment

| 61000-4-6<br>61000-4-4<br>0-4-2<br>conforming to<br>0-4-11 |
|--|
| 61000-4-4<br>0-4-2<br>conforming to                        |
| 61000-4-4<br>0-4-2<br>conforming to                        |
|  |
|  |
|  |
|  |
| /IEC 60529<br>/IEC 61800-5-1                               |
|  |
|  |
|  |
|  |

| Ambient Air Temperature For<br>Operation | -1050 °C (without derating)<br>5060 °C (with derating factor)                |
|--|--|
| Ambient Air Temperature For<br>Storage   | -2570 °C   |
| Operating Altitude                       | <= 1000 m without derating<br>10003000 m with current derating 1 % per 100 m |

## **Packing Units**

| Unit Type Of Package 1       | PCE       |
|------------------------------|-----------|
| Number Of Units In Package 1 | 1         |
| Package 1 Height             | 37.5 cm   |
| Package 1 Width              | 60 cm     |
| Package 1 Length             | 40 cm     |
| Package 1 Weight             | 23.654 kg |
| Unit Type Of Package 2       | P06       |
| Number Of Units In Package 2 | 2         |
| Package 2 Height             | 77 cm     |
| Package 2 Width              | 80 cm     |
| Package 2 Length             | 60 cm     |
| Package 2 Weight             | 55.808 kg |
| Unit Type Of Package 3       | S06       |
| Number Of Units In Package 3 | 1         |
| Package 3 Height             | 73.5 cm   |
| Package 3 Width              | 80 cm     |
| Package 3 Length             | 60 cm     |
| Package 3 Weight             | 36.654 kg |
|                              |           |

## **Contractual warranty**

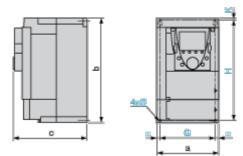
Warranty

18 months

## **Dimensions Drawings**

## UL Type 1/IP 20 Drives

## **Dimensions without Option Card**



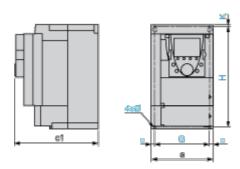
Dimensions in mm

| а   | b   | с   | G   | Н   | К | Ø |
|-----|-----|-----|-----|-----|---|---|
| 230 | 400 | 213 | 210 | 386 | 8 | 6 |

Dimensions in in.

| а    | b     | с    | G    | Н     | К    | Ø    |
|------|-------|------|------|-------|------|------|
| 9.05 | 15.75 | 8.38 | 8.26 | 15.20 | 0.31 | 0.23 |

## Dimensions with 1 Option Card (1)



Dimensions in mm

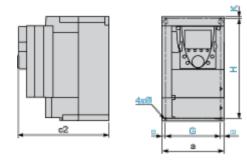
| а   | c1  | G   | Н   | Κ | Ø |
|-----|-----|-----|-----|---|---|
| 230 | 236 | 210 | 386 | 8 | 6 |

Dimensions in in.

| а    | c1   | G    | Н     | К    | Ø    |
|------|------|------|-------|------|------|
| 9.05 | 9.29 | 8.26 | 15.20 | 0.31 | 0.23 |

(1) Option cards: I/O extension cards, communication cards or "Controller Inside" programmable card.

## Dimensions with 2 Option Cards (1)



Dimensions in mm

| а   | c2  | G   | Н   | Κ | Ø |
|-----|-----|-----|-----|---|---|
| 230 | 259 | 210 | 386 | 8 | 6 |

Dimensions in in.

| а    | c2    | G    | Н     | K    | Ø    |
|------|-------|------|-------|------|------|
| 9.05 | 10.20 | 8.26 | 15.20 | 0.31 | 0.23 |

(1) Option cards: I/O extension cards, communication cards or "Controller Inside" programmable card.

## ATV61HD11M3X

## Mounting and Clearance

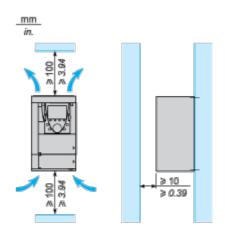
#### **Mounting Recommendations**

Depending on the conditions in which the drive is to be used, its installation will require certain precautions and the use of appropriate accessories.

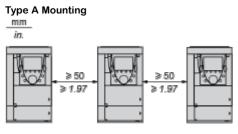
Install the unit vertically:

- Avoid placing it close to heating elements
- Leave sufficient free space to ensure that the air required for cooling purposes can circulate from the bottom to the top of the unit.

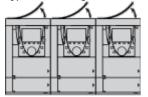
#### Clearance



#### **Mounting Types**

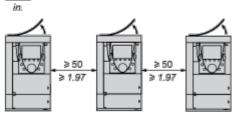


Type B Mounting



#### Type C Mounting

mm



By removing the protective blanking cover from the top of the drive, the degree of protection for the drive becomes IP 20.

The protective blanking cover may vary according to the drive model (refer to the user guide).

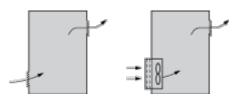
## ATV61HD11M3X

#### Specific Recommendations for Mounting the Drive in an Enclosure

#### Ventilation

To ensure proper air circulation in the drive:

- Fit ventilation grilles.
- Ensure that there is sufficient ventilation. If there is not, install a forced ventilation unit with a filter. The openings and/or fans must provide a flow rate at least equal to that of the drive fans (refer to the product characteristics).



- Use special filters with IP 54 protection.
- Remove the blanking cover from the top of the drive.

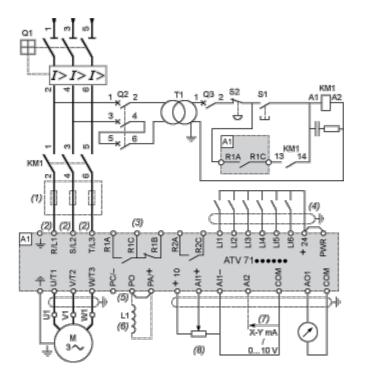
#### Dust and Damp Proof Metal Enclosure (IP 54)

The drive must be mounted in a dust and damp proof enclosure in certain environmental conditions: dust, corrosive gases, high humidity with risk of condensation and dripping water, splashing liquid, etc. This enables the drive to be used in an enclosure where the maximum internal temperature reaches 50°C.

### Connections and Schema

Wiring Diagram Conforming to Standards EN 954-1 Category 1, IEC/EN 61508 Capacity SIL1, in Stopping Category 0 According to IEC/EN 60204-1

#### Three-Phase Power Supply with Upstream Breaking via Contactor



A1 ATV61 drive

- L1 DC choke
- Q1 Circuit-breaker
- Q2 GV2 L rated at twice the nominal primary current of T1
- Q3 GB2CB05

S1, S2 XB4 B or XB5 A pushbuttons

T1 100 VA transformer 220 V secondary

(1) Line choke (three-phase); mandatory for ATV61HC11Y...HC80Y drives (except when a special transformer is used (12-pulse)).

(2) For ATV61HC50N4, ATV61HC63N4 and ATV61HC50Y...HC80Y drives, refer to the power terminal connections diagram.

(3) Fault relay contacts. Used for remote signalling of the drive status.

(4) Connection of the common for the logic inputs depends on the positioning of the SW1 switch. The above diagram shows the internal power supply switched to the "source" position (for other connection types, refer to the user guide).

(5) There is no PO terminal on ATV61HC11Y...HC80Y drives.

(6) Optional DC choke for ATV61H•••M3, ATV61HD11M3X...HD45M3X and ATV61H075N4...HD75N4 drives. Connected in place of the strap between the PO and PA/+ terminals. For ATV61HD55M3X...HD90M3X, ATV61HD90N4...HC63N4 drives, the choke is supplied with the drive; the customer is responsible for connecting it. For ATV61W•••N4 and ATV61W•••N4C drives, the DC choke is integrated.

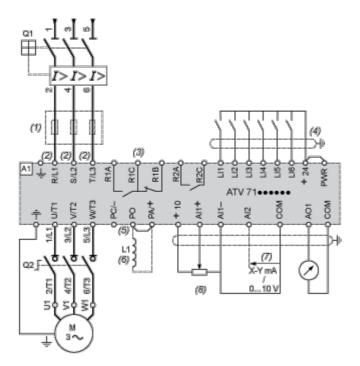
- (7) Software-configurable current (0...20 mA) or voltage (0...10 V) analog input.
- (8) Reference potentiometer.

KM1 Contactor

## ATV61HD11M3X

Wiring Diagram Conforming to Standards EN 954-1 Category 1, IEC/EN 61508 Capacity SIL1, in Stopping Category 0 According to IEC/EN 60204-1

Three-Phase Power Supply with Downstream Breaking via Switch Disconnector



- A1 ATV61 drive
- L1 DC choke
- Q1 Circuit-breaker
- Q2 Switch disconnector (Vario)

(1) Line choke (three-phase), mandatory for ATV61HC11Y...HC80Y drives (except when a special transformer is used (12-pulse)).

(2) For ATV61HC50N4, ATV61HC63N4 and ATV61HC50Y...HC80Y drives, refer to the power terminal connections diagram.

(3) Fault relay contacts. Used for remote signalling of the drive status.

(4) Connection of the common for the logic inputs depends on the positioning of the SW1 switch. The above diagram shows the internal power supply switched to the "source" position (for other connection types, refer to the user guide).

(5) There is no PO terminal on ATV61HC11Y...HC80Y drives.

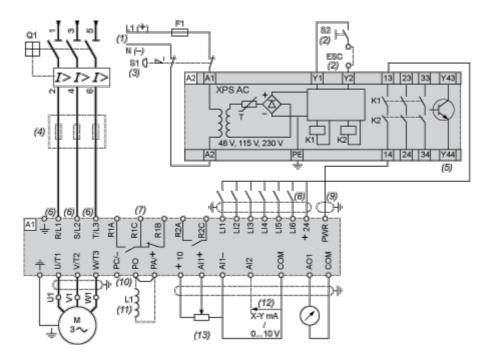
(6) Optional DC choke for ATV61H•••M3, ATV61HD11M3X...HD45M3X and ATV61H075N4...HD75N4 drives. Connected in place of the strap between the PO and PA/+ terminals. For ATV61HD55M3X...HD90M3X, ATV61HD90N4...HC63N4 drives, the choke is supplied with the drive; the customer is responsible for connecting it. For ATV61W•••N4 and ATV61W•••N4C drives, the DC choke is integrated.

(7) Software-configurable current (0...20 mA) or voltage (0...10 V) analog input.

(8) Reference potentiometer.

Wiring Diagram Conforming to Standards EN 954-1 Category 3, IEC/EN 61508 Capacity SIL2, in Stopping Category 0 According to IEC/EN 60204-1

#### Three-Phase Power Supply, Low Inertia Machine, Vertical Movement



#### A1 ATV61 drive

A2 Preventa XPS AC safety module for monitoring emergency stops and switches. One safety module can manage the "Power Removal" function for several drives on the same machine. In this case, each drive must connect its PWR terminal to its + 24 V via the safety contacts on the XPS AC module. These contacts are independent for each drive.

F1 Fuse

L1 DC choke

Q1 Circuit-breaker

S1 Emergency stop button with 2 contacts

S2 XB4 B or XB5 A pushbutton

(1) Power supply: 24 Vdc or Vac, 115 Vac, 230 Vac.

(2) S2: resets XPS AC module on power-up or after an emergency stop. ESC can be used to set external starting conditions.

(3) Requests freewheel stopping of the movement and activates the "Power Removal" safety function.

(4) Line choke (three-phase), mandatory for and ATV61HC11Y...HC80Y drives (except when a special transformer is used (12-pulse)).

(5) The logic output can be used to signal that the machine is in a safe stop state.

(6) For ATV61HC50N4, ATV61HC63N4 and ATV61HC50Y...HC80Y drives, refer to the power terminal connections diagram.

(7) Fault relay contacts. Used for remote signalling of the drive status.

(8) Connection of the common for the logic inputs depends on the positioning of the SW1 switch. The above diagram shows the internal power supply switched to the "source" position (for other connection types, refer to the user guide).

(9) Standardized coaxial cable, type RG174/U according to MIL-C17 or KX3B according to NF C 93-550, external diameter 2.54 mm /0.09 in., maximum length 15 m / 49.21 ft. The cable shielding must be earthed.

(10) There is no PO terminal on ATV61HC11Y...HC80Y drives.

(11) Optional DC choke for ATV61H•••M3, ATV61HD11M3X...HD45M3X and ATV61H075N4...HD75N4 drives. Connected in place of the strap between the PO and PA/+ terminals. For ATV61HD55M3X...HD90M3X,

## ATV61HD11M3X

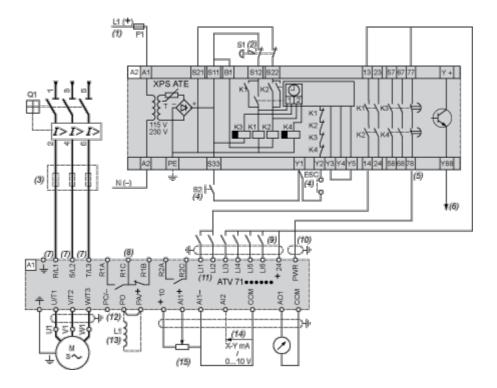
ATV61HD90N4...HC63N4 drives, the choke is supplied with the drive; the customer is responsible for connecting it. For ATV61W•••N4 and ATV61W•••N4C drives, the DC choke is integrated.

- (12) Software-configurable current (0...20 mA) or voltage (0...10 V) analog input.
- (13) Reference potentiometer.

## ATV61HD11M3X

Wiring Diagram Conforming to Standards EN 954-1 Category 3, IEC/EN 61508 Capacity SIL2, in Stopping Category 1 According to IEC/EN 60204-1

#### Three-Phase Power Supply, High Inertia Machine



#### A1 ATV61 drive

A2 (5) Preventa XPS ATE safety module for monitoring emergency stops and switches. One safety module can manage the "Power Removal" safety function for several drives on the same machine. In this case the time delay must be adjusted on the drive controlling the motor that requires the longest stopping time. In addition, each drive must connect its PWR terminal to its + 24 V via the safety contacts on the XPS ATE module. These contacts are independent for each drive.

- F1 Fuse
- L1 DC choke

Q1 Circuit-breaker

- S1 Emergency stop button with 2 contacts
- S2 XB4 B or XB5 A pushbutton
- (1) Power supply: 24 Vdc or Vac, 115 Vac, 230 Vac.

(2) Requests controlled stopping of the movement and activates the "Power Removal" safety function.

(3) Line choke (three-phase), mandatory for ATV61HC11Y...HC80Y drives (except when a special transformer is used (12-pulse)).

(4) S2: resets XPS ATE module on power-up or after an emergency stop. ESC can be used to set external starting conditions.

(5) The logic output can be used to signal that the machine is in a safe state.

(6) For stopping times requiring more than 30 seconds in category 1, use a Preventa XPS AV safety module which can provide a maximum time delay of 300 seconds.

(7) For ATV61HC50N4, ATV61HC63N4 and ATV61HC50Y...HC80Y drives, refer to the power terminal connections diagram.

(8) Fault relay contacts. Used for remote signalling of the drive status.

## ATV61HD11M3X

(9) Connection of the common for the logic inputs depends on the positioning of the SW1 switch. The above diagram shows the internal power supply switched to the "source" position (for other connection types, refer to the user guide).

(10) Standardized coaxial cable, type RG174/U according to MIL-C17 or KX3B according to NF C 93-550, external diameter 2.54 mm/0.09 in., maximum length 15 m/49.21 ft. The cable shielding must be earthed.

(11) Logic inputs LI1 and LI2 must be assigned to the direction of rotation: LI1 in the forward direction and LI2 in the reverse direction.

(12) There is no PO terminal on ATV61HC11Y...HC80Y drives.

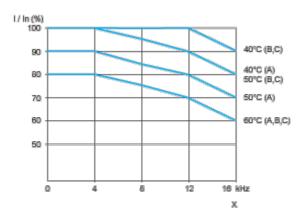
(13) Optional DC choke for ATV61H•••M3, ATV61HD11M3X...HD45M3X and ATV61H075N4...HD75N4 drives. Connected in place of the strap between the PO and PA/+ terminals. For ATV61HD55M3X...HD90M3X, ATV61HD90N4...HC63N4 drives, the choke is supplied with the drive; the customer is responsible for connecting it. For ATV61W•••N4 and ATV61W•••N4C drives, the DC choke is integrated.

- (14) Software-configurable current (0...20 mA) or voltage (0...10 V) analog input.
- (15) Reference potentiometer.

## Performance Curves

#### **Derating Curves**

The derating curves for the drive nominal current (In) depend on the temperature, the switching frequency and the mounting type (A, B or C). For intermediate temperatures (e.g. 55°C), interpolate between 2 curves.



X Switching frequency