Specifications



① Discontinued - Service only

ATV61 11 kW 15 HP 240 V 3 phases without EMC IP20

ATV61HD11M3X

- () Discontinued on: Jan 23, 2021 AD
- () To be end-of-service on: Jan 1, 2025 AD

Main

Range Of Product	Altivar 61
Product Or Component Type	Variable speed drive
Product Specific Application	Pumping and ventilation machine
Component Name	ATV61
Motor Power Kw	11 kW, 3 phases at 200240 V
Motor Power Hp	15 hp, 3 phases at 200240 V
Power Supply Voltage	200240 V - 1510 %
Supply Number Of Phases	3 phases
Line Current	45.8 A for 240 V 3 phases 11 kW / 15 hp 53.3 A for 200 V 3 phases 11 kW / 15 hp
Emc Filter	Without EMC filter
Assembly Style	With heat sink
Apparent Power	19 kVA at 240 V 3 phases 11 kW / 15 hp
Maximum Prospective Line Isc	22 kA for 3 phases
Maximum Transient Current	64.8 A for 60 s, 3 phases
Nominal Switching Frequency	12 kHz
Switching Frequency	116 kHz adjustable 1216 kHz with derating factor
Asynchronous Motor Control	Voltage/frequency ratio, 2 points Voltage/frequency ratio - Energy Saving, quadratic U/f Voltage/frequency ratio, 5 points Flux vector control without sensor, standard
Synchronous Motor Control Profile	Vector control without sensor, standard
Communication Port Protocol	CANopen Modbus
Type Of Polarization	No impedance for Modbus

Type Of Polarization

No impedance for Modbus

Option Card

	Communication card for APOGEE FLN
	Communication card for BACnet
	Communication card for CC-Link
	Controller inside programmable card
	Communication card for DeviceNet
	Communication card for EtherNet/IP
	Communication card for Fipio
	I/O extension card
(Communication card for Interbus-S
	Communication card for LonWorks
	Communication card for METASYS N2
	Communication card for Modbus Plus
(Communication card for Modbus TCP
(Communication card for Modbus/Uni-Telway
l	Multi-pump card
	Communication card for Profibus DP
•	Communication card for Profibus DP V1

Complementary

Product Destination Power Supply Voltage Limits Power Supply Frequency Power Supply Frequency Limits Continuous Output Current Output Frequency Speed Range Speed Accuracy Torque Accuracy Transient Overtorque Braking Torque Regulation Loop Motor Slip Compensation Diagnostic Output Voltage Electrical Isolation Type Of Cable For Mounting In An Enclosure Electrical Connection	Asynchronous motors Synchronous motors 170264 V 5060 Hz - 55 % 47.563 Hz 54 A at 12 kHz, 230 V - 3 phases 0.1599 Hz 1100 in open-loop mode, without speed feedback +/- 10 % of nominal slip 0.2 Tn to Tn without speed feedback +/- 15 % in open-loop mode, without speed feedback 130 % of nominal motor torque +/- 10 % for 60 s <= 125 % with braking resistor 30 % without braking resistor So % without braking resistor Automatic whatever the load Can be suppressed
Power Supply Frequency Power Supply Frequency Limits Continuous Output Current Output Frequency Speed Range Speed Accuracy Torque Accuracy Transient Overtorque Braking Torque Regulation Loop Motor Slip Compensation Diagnostic Output Voltage Electrical Isolation Type Of Cable For Mounting In An Enclosure	5060 Hz - 55 % 47.563 Hz 54 A at 12 kHz, 230 V - 3 phases 0.1599 Hz 1100 in open-loop mode, without speed feedback +/- 10 % of nominal slip 0.2 Tn to Tn without speed feedback +/- 15 % in open-loop mode, without speed feedback 130 % of nominal motor torque +/- 10 % for 60 s <= 125 % with braking resistor
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Continuous Output Current Output Frequency Speed Range Speed Accuracy Torque Accuracy Transient Overtorque Braking Torque Regulation Loop Motor Slip Compensation Diagnostic Output Voltage Electrical Isolation Type Of Cable For Mounting In An Enclosure	54 A at 12 kHz, 230 V - 3 phases 0.1599 Hz 1100 in open-loop mode, without speed feedback +/- 10 % of nominal slip 0.2 Tn to Tn without speed feedback +/- 15 % in open-loop mode, without speed feedback 130 % of nominal motor torque +/- 10 % for 60 s <= 125 % with braking resistor
Output Frequency Speed Range Speed Accuracy Torque Accuracy Transient Overtorque Braking Torque Regulation Loop Motor Slip Compensation Diagnostic Output Voltage Electrical Isolation Type Of Cable For Mounting In An Enclosure	0.1599 Hz 1100 in open-loop mode, without speed feedback +/- 10 % of nominal slip 0.2 Tn to Tn without speed feedback +/- 15 % in open-loop mode, without speed feedback 130 % of nominal motor torque +/- 10 % for 60 s <= 125 % with braking resistor
Speed Range Speed Accuracy Torque Accuracy Transient Overtorque Braking Torque Regulation Loop Motor Slip Compensation Diagnostic Output Voltage Electrical Isolation Type Of Cable For Mounting In An Enclosure	1100 in open-loop mode, without speed feedback +/- 10 % of nominal slip 0.2 Tn to Tn without speed feedback +/- 15 % in open-loop mode, without speed feedback 130 % of nominal motor torque +/- 10 % for 60 s <= 125 % with braking resistor
Speed Accuracy Torque Accuracy Transient Overtorque Braking Torque Regulation Loop Motor Slip Compensation Diagnostic Output Voltage Electrical Isolation Type Of Cable For Mounting In An Enclosure	+/- 10 % of nominal slip 0.2 Tn to Tn without speed feedback +/- 15 % in open-loop mode, without speed feedback 130 % of nominal motor torque +/- 10 % for 60 s <= 125 % with braking resistor 30 % without braking resistor Frequency PI regulator Not available in voltage/frequency ratio (2 or 5 points) Automatic whatever the load
Torque Accuracy Transient Overtorque Braking Torque Regulation Loop Motor Slip Compensation Diagnostic Output Voltage Electrical Isolation Type Of Cable For Mounting In An Enclosure	+/- 15 % in open-loop mode, without speed feedback 130 % of nominal motor torque +/- 10 % for 60 s <= 125 % with braking resistor 30 % without braking resistor Frequency PI regulator Not available in voltage/frequency ratio (2 or 5 points) Automatic whatever the load
Transient Overtorque Braking Torque Regulation Loop Motor Slip Compensation Diagnostic Output Voltage Electrical Isolation Type Of Cable For Mounting In An Enclosure	130 % of nominal motor torque +/- 10 % for 60 s <= 125 % with braking resistor
Braking Torque Regulation Loop Motor Slip Compensation Diagnostic Output Voltage Electrical Isolation Type Of Cable For Mounting In An Enclosure	<= 125 % with braking resistor 30 % without braking resistor Frequency PI regulator Not available in voltage/frequency ratio (2 or 5 points) Automatic whatever the load
Regulation Loop Motor Slip Compensation Diagnostic Output Voltage Electrical Isolation Type Of Cable For Mounting In An Enclosure	30 % without braking resistor Frequency PI regulator Not available in voltage/frequency ratio (2 or 5 points) Automatic whatever the load
Motor Slip Compensation Diagnostic Output Voltage Electrical Isolation Type Of Cable For Mounting In An Enclosure	Not available in voltage/frequency ratio (2 or 5 points) Automatic whatever the load
Diagnostic Output Voltage Electrical Isolation Type Of Cable For Mounting In An Enclosure	Automatic whatever the load
Output Voltage Electrical Isolation Type Of Cable For Mounting In An Enclosure	Adjustable
Electrical Isolation Type Of Cable For Mounting In An Enclosure	1 LED (red) for drive voltage
Type Of Cable For Mounting In An Enclosure	<= power supply voltage
Enclosure	Between power and control terminals
Electrical Connection	With an IP21 or an IP31 kit: 3 wire(s)IEC cable at 40 °C, copper 70 °C / PVC With UL Type 1 kit: 3 wire(s)UL 508 cable at 40 °C, copper 75 °C / PVC Without mounting kit: 1 wire(s)IEC cable at 45 °C, copper 70 °C / PVC Without mounting kit: 1 wire(s)IEC cable at 45 °C, copper 90 °C / XLPE/EPR
	Terminal 2.5 mm² / AWG 14 (Al1-/Al1+, Al2, AO1, R1A, R1B, R1C, R2A, R2B, Ll1Ll6, PWR) Terminal 25 mm² / AWG 3 (L1/R, L2/S, L3/T, U/T1, V/T2, W/T3, PC/-, PO, PA/+, PA, PB)
Tightening Torque	0.6 N.m (Al1-/Al1+, Al2, AO1, R1A, R1B, R1C, R2A, R2B, L11L16, PWR) 5.4 N.m, 47.7 Ib.in (L1/R, L2/S, L3/T, U/T1, V/T2, W/T3, PC/-, PO, PA/+, PA, PB)
Supply	
Analogue Input Number	Internal supply for reference potentiometer (1 to 10 kOhm): 10.5 V DC, +/- 5 %, <10 mA with overload and short-circuit protection Internal supply: 24 V DC (2127 V), <200 mA with overload and short-circuit protection External supply: 24 V DC (1930 V)

Analogue Input Type	Al1-/Al1+ bipolar differential voltage: +/- 10 V DC 24 V max, resolution 11 bits + sign Al2 software-configurable current: 020 mA, impedance: 242 Ohm, resolution 11 bits
	Al2 software-configurable voltage: 010 V DC 24 V max, impedance: 30000 Ohm, resolution 11 bits
Sampling Time	2 ms +/- 0.5 ms (AI1-/AI1+) - analog input
	2 ms +/- 0.5 ms (Al2) - analog input
	2 ms +/- 0.5 ms (AO1) - analog output 2 ms +/- 0.5 ms (LI1LI5) - discrete input
	2 ms +/- 0.5 ms (LI6)if configured as logic input - discrete input
Absolute Accuracy Precision	+/- 0.6 % (AI1-/AI1+) for a temperature variation 60 °C
	+/- 0.6 % (Al2) for a temperature variation 60 °C
	+/- 1 % (AO1) for a temperature variation 60 °C
inearity Error	+/- 0.15 % of maximum value (AI1-/AI1+)
	+/- 0.15 % of maximum value (Al2) +/- 0.2 % (AO1)
	+7- 0.2 /0 (AOT)
Analogue Output Number	1
Analogue Output Type	AO1 software-configurable current, analogue output range 020 mA, impedance:
	500 Ohm, resolution 10 bits AO1 software-configurable voltage, analogue output range 010 V DC, impedance:
	470 Ohm, resolution 10 bits
	AO1 software-configurable logic output 10 V, 20 mA
Discrete Output Number	2
Discrete Output Type	Configurable relay logic: (R1A, R1B, R1C) NO/NC - 100000 cycles
	Configurable relay logic: (R2A, R2B) NO - 100000 cycles
Aaximum Response Time	<= 100 ms in STO (Safe Torque Off)
	R1A, R1B, R1C <= 7 ms, tolerance +/- 0.5 ms
	R2A, R2B <= 7 ms, tolerance +/- 0.5 ms
Iinimum Switching Current	3 mA at 24 V DC for configurable relay logic
Maximum Switching Current	R1, R2: 2 A at 250 V AC inductive load, cos phi = 0.4 and L/R = 7 ms
	R1, R2: 2 A at 30 V DC inductive load, cos phi = 0.4 and L/R = 7 ms R1, R2: 5 A at 250 V AC resistive load, cos phi = 1 and L/R = 0 ms
	R1, R2: 5 A at 30 V DC resistive load, cos phi = 1 and $L/R = 0$ ms
Discrete Input Number	7
Discrete Input Type	Programmable (LI1LI5)24 V DC (<= 30 V), with level 1 PLC - 3500 Ohm
	Switch-configurable (LI6)24 V DC (<= 30 V), with level 1 PLC - 3500 Ohm
	Switch-configurable PTC probe (LI6)06 probes - 1500 Ohm Safety input (PWR)24 V DC (<= 30 V) - 1500 Ohm
Discusts lumit Louis	
Discrete Input Logic	Negative logic (sink) (LI1LI5), > 16 V (state 0), < 10 V (state 1) Positive logic (source) (LI1LI5), < 5 V (state 0), > 11 V (state 1)
	Negative logic (sink) (LI6)if configured as logic input, > 16 V (state 0), < 10 V (state 1)
	Positive logic (source) (LI6)if configured as logic input, < 5 V (state 0), > 11 V (state
	1)
Acceleration And Deceleration	Linear adjustable separately from 0.01 to 9000 s
Ramps	Automatic adaptation of ramp if braking capacity exceeded, by using resistor S, U or customized
Braking To Standstill	By DC injection
Protection Type	Against exceeding limit speed: drive
······································	Against exceeding infinitispeed, drive
	Break on the control circuit: drive
	Input phase breaks: drive Line supply overvoltage: drive
	Line supply overvoltage: drive
	Overcurrent between output phases and earth: drive
	Overheating protection: drive
	Overvoltages on the DC bus: drive Power removal: drive
	Short-circuit between motor phases: drive
	Thermal protection: drive
	Motor phase break: motor Power removal: motor
	Thermal protection: motor
nsulation Resistance	> 1 mOhm 500 V DC for 1 minute to earth

Frequency Resolution	Analog input: 0.024/50 Hz				
	Display unit: 0.1 Hz				
Connector Type	1 RJ45 (on front face) for Modbus				
	1 RJ45 (on terminal) for Modbus				
	Male SUB-D 9 on RJ45 for CANopen				
Physical Interface	2-wire RS 485 for Modbus				
Transmission Frame	RTU for Modbus				
Transmission Rate	4800 bps, 9600 bps, 19200 bps, 38.4 Kbps for Modbus on terminal				
	9600 bps, 19200 bps for Modbus on front face				
	20 kbps, 50 kbps, 125 kbps, 250 kbps, 500 kbps, 1 Mbps for CANopen				
Data Format	8 bits, 1 stop, even parity for Modbus on front face				
	8 bits, odd even or no configurable parity for Modbus on terminal				
Number Of Addresses	1127 for CANopen				
	1247 for Modbus				
Method Of Access	Slave CANopen				
Marking	CE				
Operating Position	Vertical +/- 10 degree				
Net Weight	22 kg				
Width	230 mm				
Height	400 mm				
Depth	213 mm				

Environment

61000-4-6 61000-4-4 0-4-2 conforming to 0-4-11
61000-4-4 0-4-2 conforming to
61000-4-4 0-4-2 conforming to
/IEC 60529 /IEC 61800-5-1

Ambient Air Temperature For Operation	-1050 °C (without derating) 5060 °C (with derating factor)
Ambient Air Temperature For Storage	-2570 °C
Operating Altitude	<= 1000 m without derating 10003000 m with current derating 1 % per 100 m

Packing Units

Unit Type Of Package 1	PCE
Number Of Units In Package 1	1
Package 1 Height	37.5 cm
Package 1 Width	60 cm
Package 1 Length	40 cm
Package 1 Weight	23.654 kg
Unit Type Of Package 2	P06
Number Of Units In Package 2	2
Package 2 Height	77 cm
Package 2 Width	80 cm
Package 2 Length	60 cm
Package 2 Weight	55.808 kg
Unit Type Of Package 3	S06
Number Of Units In Package 3	1
Package 3 Height	73.5 cm
Package 3 Width	80 cm
Package 3 Length	60 cm
Package 3 Weight	36.654 kg

Contractual warranty

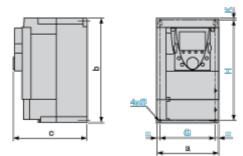
Warranty

18 months

Dimensions Drawings

UL Type 1/IP 20 Drives

Dimensions without Option Card



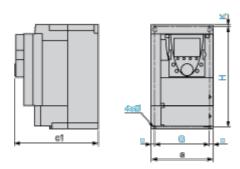
Dimensions in mm

а	b	с	G	Н	К	Ø
230	400	213	210	386	8	6

Dimensions in in.

а	b	с	G	Н	К	Ø
9.05	15.75	8.38	8.26	15.20	0.31	0.23

Dimensions with 1 Option Card (1)



Dimensions in mm

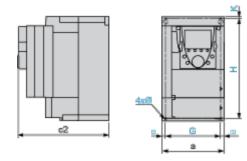
а	c1	G	Н	Κ	Ø
230	236	210	386	8	6

Dimensions in in.

а	c1	G	Н	К	Ø
9.05	9.29	8.26	15.20	0.31	0.23

(1) Option cards: I/O extension cards, communication cards or "Controller Inside" programmable card.

Dimensions with 2 Option Cards (1)



Dimensions in mm

а	c2	G	Н	Κ	Ø
230	259	210	386	8	6

Dimensions in in.

а	c2	G	Н	K	Ø
9.05	10.20	8.26	15.20	0.31	0.23

(1) Option cards: I/O extension cards, communication cards or "Controller Inside" programmable card.

ATV61HD11M3X

Mounting and Clearance

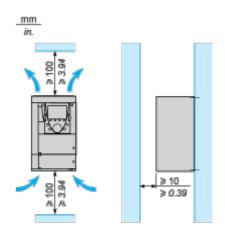
Mounting Recommendations

Depending on the conditions in which the drive is to be used, its installation will require certain precautions and the use of appropriate accessories.

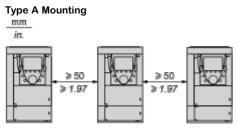
Install the unit vertically:

- Avoid placing it close to heating elements
- Leave sufficient free space to ensure that the air required for cooling purposes can circulate from the bottom to the top of the unit.

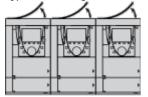
Clearance



Mounting Types

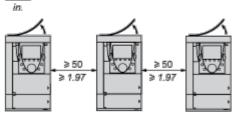


Type B Mounting



Type C Mounting

mm



By removing the protective blanking cover from the top of the drive, the degree of protection for the drive becomes IP 20.

The protective blanking cover may vary according to the drive model (refer to the user guide).

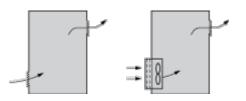
ATV61HD11M3X

Specific Recommendations for Mounting the Drive in an Enclosure

Ventilation

To ensure proper air circulation in the drive:

- Fit ventilation grilles.
- Ensure that there is sufficient ventilation. If there is not, install a forced ventilation unit with a filter. The openings and/or fans must provide a flow rate at least equal to that of the drive fans (refer to the product characteristics).



- Use special filters with IP 54 protection.
- Remove the blanking cover from the top of the drive.

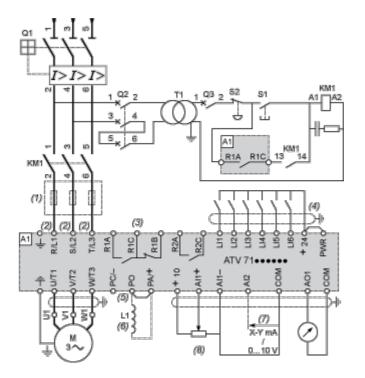
Dust and Damp Proof Metal Enclosure (IP 54)

The drive must be mounted in a dust and damp proof enclosure in certain environmental conditions: dust, corrosive gases, high humidity with risk of condensation and dripping water, splashing liquid, etc. This enables the drive to be used in an enclosure where the maximum internal temperature reaches 50°C.

Connections and Schema

Wiring Diagram Conforming to Standards EN 954-1 Category 1, IEC/EN 61508 Capacity SIL1, in Stopping Category 0 According to IEC/EN 60204-1

Three-Phase Power Supply with Upstream Breaking via Contactor



A1 ATV61 drive

- L1 DC choke
- Q1 Circuit-breaker
- Q2 GV2 L rated at twice the nominal primary current of T1
- Q3 GB2CB05

S1, S2 XB4 B or XB5 A pushbuttons

T1 100 VA transformer 220 V secondary

(1) Line choke (three-phase); mandatory for ATV61HC11Y...HC80Y drives (except when a special transformer is used (12-pulse)).

(2) For ATV61HC50N4, ATV61HC63N4 and ATV61HC50Y...HC80Y drives, refer to the power terminal connections diagram.

(3) Fault relay contacts. Used for remote signalling of the drive status.

(4) Connection of the common for the logic inputs depends on the positioning of the SW1 switch. The above diagram shows the internal power supply switched to the "source" position (for other connection types, refer to the user guide).

(5) There is no PO terminal on ATV61HC11Y...HC80Y drives.

(6) Optional DC choke for ATV61H•••M3, ATV61HD11M3X...HD45M3X and ATV61H075N4...HD75N4 drives. Connected in place of the strap between the PO and PA/+ terminals. For ATV61HD55M3X...HD90M3X, ATV61HD90N4...HC63N4 drives, the choke is supplied with the drive; the customer is responsible for connecting it. For ATV61W•••N4 and ATV61W•••N4C drives, the DC choke is integrated.

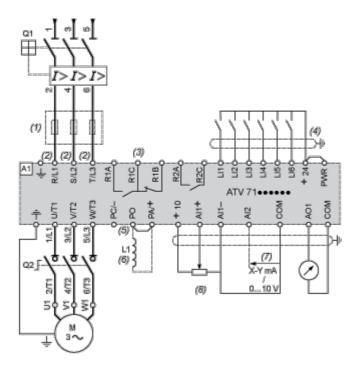
- (7) Software-configurable current (0...20 mA) or voltage (0...10 V) analog input.
- (8) Reference potentiometer.

KM1 Contactor

ATV61HD11M3X

Wiring Diagram Conforming to Standards EN 954-1 Category 1, IEC/EN 61508 Capacity SIL1, in Stopping Category 0 According to IEC/EN 60204-1

Three-Phase Power Supply with Downstream Breaking via Switch Disconnector



- A1 ATV61 drive
- L1 DC choke
- Q1 Circuit-breaker
- Q2 Switch disconnector (Vario)

(1) Line choke (three-phase), mandatory for ATV61HC11Y...HC80Y drives (except when a special transformer is used (12-pulse)).

(2) For ATV61HC50N4, ATV61HC63N4 and ATV61HC50Y...HC80Y drives, refer to the power terminal connections diagram.

(3) Fault relay contacts. Used for remote signalling of the drive status.

(4) Connection of the common for the logic inputs depends on the positioning of the SW1 switch. The above diagram shows the internal power supply switched to the "source" position (for other connection types, refer to the user guide).

(5) There is no PO terminal on ATV61HC11Y...HC80Y drives.

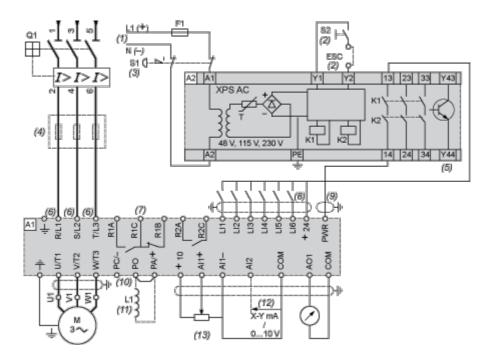
(6) Optional DC choke for ATV61H•••M3, ATV61HD11M3X...HD45M3X and ATV61H075N4...HD75N4 drives. Connected in place of the strap between the PO and PA/+ terminals. For ATV61HD55M3X...HD90M3X, ATV61HD90N4...HC63N4 drives, the choke is supplied with the drive; the customer is responsible for connecting it. For ATV61W•••N4 and ATV61W•••N4C drives, the DC choke is integrated.

(7) Software-configurable current (0...20 mA) or voltage (0...10 V) analog input.

(8) Reference potentiometer.

Wiring Diagram Conforming to Standards EN 954-1 Category 3, IEC/EN 61508 Capacity SIL2, in Stopping Category 0 According to IEC/EN 60204-1

Three-Phase Power Supply, Low Inertia Machine, Vertical Movement



A1 ATV61 drive

A2 Preventa XPS AC safety module for monitoring emergency stops and switches. One safety module can manage the "Power Removal" function for several drives on the same machine. In this case, each drive must connect its PWR terminal to its + 24 V via the safety contacts on the XPS AC module. These contacts are independent for each drive.

F1 Fuse

L1 DC choke

Q1 Circuit-breaker

S1 Emergency stop button with 2 contacts

S2 XB4 B or XB5 A pushbutton

(1) Power supply: 24 Vdc or Vac, 115 Vac, 230 Vac.

(2) S2: resets XPS AC module on power-up or after an emergency stop. ESC can be used to set external starting conditions.

(3) Requests freewheel stopping of the movement and activates the "Power Removal" safety function.

(4) Line choke (three-phase), mandatory for and ATV61HC11Y...HC80Y drives (except when a special transformer is used (12-pulse)).

(5) The logic output can be used to signal that the machine is in a safe stop state.

(6) For ATV61HC50N4, ATV61HC63N4 and ATV61HC50Y...HC80Y drives, refer to the power terminal connections diagram.

(7) Fault relay contacts. Used for remote signalling of the drive status.

(8) Connection of the common for the logic inputs depends on the positioning of the SW1 switch. The above diagram shows the internal power supply switched to the "source" position (for other connection types, refer to the user guide).

(9) Standardized coaxial cable, type RG174/U according to MIL-C17 or KX3B according to NF C 93-550, external diameter 2.54 mm /0.09 in., maximum length 15 m / 49.21 ft. The cable shielding must be earthed.

(10) There is no PO terminal on ATV61HC11Y...HC80Y drives.

(11) Optional DC choke for ATV61H•••M3, ATV61HD11M3X...HD45M3X and ATV61H075N4...HD75N4 drives. Connected in place of the strap between the PO and PA/+ terminals. For ATV61HD55M3X...HD90M3X,

ATV61HD11M3X

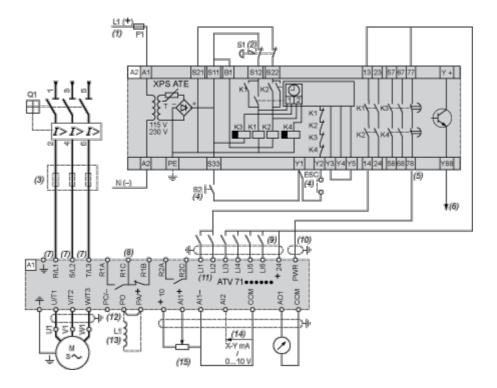
ATV61HD90N4...HC63N4 drives, the choke is supplied with the drive; the customer is responsible for connecting it. For ATV61W•••N4 and ATV61W•••N4C drives, the DC choke is integrated.

- (12) Software-configurable current (0...20 mA) or voltage (0...10 V) analog input.
- (13) Reference potentiometer.

ATV61HD11M3X

Wiring Diagram Conforming to Standards EN 954-1 Category 3, IEC/EN 61508 Capacity SIL2, in Stopping Category 1 According to IEC/EN 60204-1

Three-Phase Power Supply, High Inertia Machine



A1 ATV61 drive

A2 (5) Preventa XPS ATE safety module for monitoring emergency stops and switches. One safety module can manage the "Power Removal" safety function for several drives on the same machine. In this case the time delay must be adjusted on the drive controlling the motor that requires the longest stopping time. In addition, each drive must connect its PWR terminal to its + 24 V via the safety contacts on the XPS ATE module. These contacts are independent for each drive.

- F1 Fuse
- L1 DC choke

Q1 Circuit-breaker

- S1 Emergency stop button with 2 contacts
- S2 XB4 B or XB5 A pushbutton
- (1) Power supply: 24 Vdc or Vac, 115 Vac, 230 Vac.

(2) Requests controlled stopping of the movement and activates the "Power Removal" safety function.

(3) Line choke (three-phase), mandatory for ATV61HC11Y...HC80Y drives (except when a special transformer is used (12-pulse)).

(4) S2: resets XPS ATE module on power-up or after an emergency stop. ESC can be used to set external starting conditions.

(5) The logic output can be used to signal that the machine is in a safe state.

(6) For stopping times requiring more than 30 seconds in category 1, use a Preventa XPS AV safety module which can provide a maximum time delay of 300 seconds.

(7) For ATV61HC50N4, ATV61HC63N4 and ATV61HC50Y...HC80Y drives, refer to the power terminal connections diagram.

(8) Fault relay contacts. Used for remote signalling of the drive status.

ATV61HD11M3X

(9) Connection of the common for the logic inputs depends on the positioning of the SW1 switch. The above diagram shows the internal power supply switched to the "source" position (for other connection types, refer to the user guide).

(10) Standardized coaxial cable, type RG174/U according to MIL-C17 or KX3B according to NF C 93-550, external diameter 2.54 mm/0.09 in., maximum length 15 m/49.21 ft. The cable shielding must be earthed.

(11) Logic inputs LI1 and LI2 must be assigned to the direction of rotation: LI1 in the forward direction and LI2 in the reverse direction.

(12) There is no PO terminal on ATV61HC11Y...HC80Y drives.

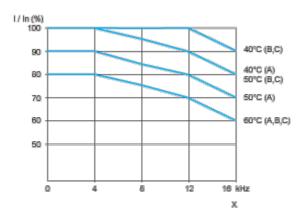
(13) Optional DC choke for ATV61H•••M3, ATV61HD11M3X...HD45M3X and ATV61H075N4...HD75N4 drives. Connected in place of the strap between the PO and PA/+ terminals. For ATV61HD55M3X...HD90M3X, ATV61HD90N4...HC63N4 drives, the choke is supplied with the drive; the customer is responsible for connecting it. For ATV61W•••N4 and ATV61W•••N4C drives, the DC choke is integrated.

- (14) Software-configurable current (0...20 mA) or voltage (0...10 V) analog input.
- (15) Reference potentiometer.

Performance Curves

Derating Curves

The derating curves for the drive nominal current (In) depend on the temperature, the switching frequency and the mounting type (A, B or C). For intermediate temperatures (e.g. 55°C), interpolate between 2 curves.



X Switching frequency