Specifications





variable speed drive - 22kW- 400V - 3 phases - ATV340

Local distributor code: 408900812

ATV340D22N4

EAN Code: 3606480966972

Main

Range Of Product	Altivar Machine ATV340
Product Or Component Type	Variable speed drive
Product Specific Application	Machine
Variant	Standard version
Mounting Mode	Cabinet mount
Communication Port Protocol	Modbus serial
Option Card	Communication module, Profibus DP V1 Communication module, PROFINET Communication module, DeviceNet Communication module, CANopen Communication module, EtherCAT
Network Number Of Phases	3 phases
Supply Frequency	5060 Hz +/- 5 %
[Us] Rated Supply Voltage	380480 V - 1510 %
Nominal Output Current	46.0 A
Motor Power Kw	30 kW for normal duty 22 kW for heavy duty
Motor Power Hp	40 hp for normal duty 30 hp for heavy duty
Emc Filter	Class C3 EMC filter integrated
Ip Degree Of Protection	IP20

Complementary

Discrete Input Number	5	
Discrete Input Type	PTI programmable as pulse input: 030 kHz, 24 V DC (30 V) DI1DI5 safe torque off, 24 V DC (30 V), impedance: 3.5 kOhm programmable	
Number Of Preset Speeds	16 preset speeds	
Discrete Output Number	2.0	
Discrete Output Type	Programmable output DQ1, DQ2 30 V DC 100 mA	
Analogue Input Number	2	
Analogue Input Type Al1 software-configurable current: 020 mA, impedance: 250 Ohm, respits Al1 software-configurable temperature probe or water level sensor Al1 software-configurable temperature probe or water level sensor Al1 software-configurable voltage: 010 V DC, impedance: 31.5 kOhm bits Al2 software-configurable voltage: - 1010 V DC, impedance: 31.5 kOhm bits Al2 software-configurable voltage: - 1010 V DC, impedance: 31.5 kOhm bits Al2 software-configurable voltage: - 1010 V DC, impedance: 31.5 kOhm bits		

Analogue Output Number	2	
Analogue Output Type	Software-configurable voltage AQ1: 010 V DC impedance 470 Ohm, resolution 10	
	bits Software-configurable current AQ1: 020 mA impedance 500 Ohm, resolution 10 bits	
Relay Output Number	2	
Output Voltage	<= power supply voltage	
Relay Output Type	Relay outputs R1A Relay outputs R1C electrical durability 100000 cycles Relay outputs R2A Relay outputs R2C electrical durability 100000 cycles	
Maximum Switching Current	Relay output R1C on resistive load, cos phi = 1: 3 A at 250 V AC Relay output R1C on resistive load, cos phi = 1: 3 A at 30 V DC Relay output R1C on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 250 V AC Relay output R1C on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 30 V DC Relay output R2C on resistive load, cos phi = 1: 5 A at 250 V AC Relay output R2C on resistive load, cos phi = 1: 5 A at 250 V AC Relay output R2C on resistive load, cos phi = 1: 5 A at 30 V DC Relay output R2C on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 250 V AC Relay output R2C on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 250 V AC Relay output R2C on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 30 V DC	
Minimum Switching Current	Relay output R1B: 5 mA at 24 V DC Relay output R2C: 5 mA at 24 V DC	
Physical Interface	2-wire RS 485	
Connector Type	1 RJ45	
Method Of Access	Slave Modbus RTU	
Transmission Rate	4.8 kbit/s 9.6 kbit/s 19.2 kbit/s 38.4 kbit/s	
Transmission Frame	RTU	
Number Of Addresses	1247	
Data Format	8 bits, configurable odd, even or no parity	
Type Of Polarization	No impedance	
4 Quadrant Operation Possible	True	
Asynchronous Motor Control Profile	Variable torque standard Constant torque standard Optimized torque mode	
Synchronous Motor Control Profile	Permanent magnet motor Reluctance motor	
Pollution Degree	2 conforming to IEC 61800-5-1	
Maximum Output Frequency	0.599 kHz	
Acceleration And Deceleration Ramps	Linear adjustable separately from 0.019999 s S, U or customized	
Motor Slip Compensation	Adjustable Can be suppressed Automatic whatever the load Not available in permanent magnet motor law	
Switching Frequency	216 kHz adjustable 616 kHz with derating factor	
Nominal Switching Frequency	4 kHz	
Braking To Standstill	By DC injection	
Brake Chopper Integrated	True	

Line Current	60.1 A at 380 V (normal duty)	
	48.6 A at 480 V (normal duty)	
	63.5 A at 380 V (heavy duty)	
	50.6 A at 480 V (heavy duty)	
Line Current	63.5 A at 380 V without line choke (heavy duty)	
	50.5 A at 480 V without line choke (heavy duty)	
	67.9 A at 480 V with external line choke (normal duty)	
	54.4 A at 380 V with external line choke (heavy duty)	
	64.1 A at 480 V with external line choke (heavy duty)	
	50.8 A at 380 V with external line choke (normal duty)	
Maximum Input Current	63.5 A	
Maximum Output Voltage	480 V	
Apparent Power	45.1 kVA at 480 V (normal duty)	
	42.1 kVA at 480 V (heavy duty)	
Maximum Transient Current	68.2 A during 60 s (normal duty)	
	69 A during 60 s (heavy duty)	
	83.7 A during 2 s (normal duty)	
	83 A during 2 s (heavy duty)	
	00 A daming 2 5 (neavy duty)	
Electrical Connection	Screw terminal, clamping capacity: 0.22.5 mm ² for control	
	Screw terminal, clamping capacity: 625 mm ² for motor	
	Screw terminal, clamping capacity: 1025 mm ² for line side	
	Screw terminal, clamping capacity: 1025 mm ² for DC bus	
Prospective Line Isc	22 kA	
Base Load Current At High Overload	46.0 A	
Base Load Current At Low Overload	62.0 A	
Power Dissipation In W	Natural convection: 28 W at 380 V, switching frequency 4 kHz (heavy duty)	
	Forced convection: 486 W at 380 V, switching frequency 4 kHz (heavy duty)	
	Natural convection: 39 W at 380 V, switching frequency 4 kHz (normal duty)	
	Forced convection: 631 W at 380 V, switching frequency 4 kHz (normal duty)	
Electrical Connection	Control: screw terminal 0.22.5 mm ² /AWG 24AWG 12	
	Motor: screw terminal 625 mm²/AWG 8AWG 3	
	Line side: screw terminal 1025 mm²/AWG 6AWG 3	
	DC bus: screw terminal 1025 mm²/AWG 6AWG 3	
	-	
With Safety Function Safely Limited Speed (SIs)	True	
With Safety Function Safe Brake Management (Sbc/Sbt)	True	
With Safety Function Safe Operating Stop (Sos)	False	
With Safety Function Safe Position (Sp)	False	
With Safety Function Safe Programmable Logic	False	
With Safety Function Safe Speed Monitor (Ssm)	False	
With Safety Function Safe Stop 1 (Ss1)	True	
With Sft Fct Safe Stop 2 (Ss2)	False	
With Safety Function Safe Torque	True	
Off (Sto) With Safety Function Safely Limited Position (Slp)	False	
With Safety Function Safe	Falso	
Direction (Sdi)	False	

Protection Type	Thermal protection: motor			
	Safe torque off: motor			
	Motor phase loss: motor			
	Thermal protection: drive			
	Safe torque off: drive			
	Overheating: drive			
	Overcurrent: drive			
	Output overcurrent between motor phase and earth: drive			
	Output overcurrent between motor phases: drive			
	Short-circuit between motor phase and earth: drive Short-circuit between motor phases: drive Motor phase loss: drive			
	DC Bus overvoltage: drive			
	Line supply overvoltage: drive			
	Line supply undervoltage: drive			
	Input supply loss: drive			
	Exceeding limit speed: drive			
	Break on the control circuit: drive			
Width	180.0 mm			

	100.0 mm
Height	385.0 mm
Depth	249.0 mm
Net Weight	10.2 kg
Continuous Output Current	62 A at 4 kHz for normal duty 46 A at 4 kHz for heavy duty

Environment

Operating Altitude	<= 3000 m with current derating above 1000m	
Operating Position	Vertical +/- 10 degree	
Product Certifications	UL CSA TÜV EAC CTick	
Marking	CE	
Standards	IEC 61800-3 IEC 61800-5-1 IEC 60721-3 IEC 61508 IEC 13849-1 UL 618000-5-1 UL 508C	
Assembly Style	With heat sink	
Electromagnetic Compatibility	Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3 Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4 1.2/50 µs - 8/20 µs surge immunity test level 3 conforming to IEC 61000-4-5 Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6	
Environmental Class (During Operation)	Class 3C3 according to IEC 60721-3-3 Class 3S3 according to IEC 60721-3-3	
Maximum Acceleration Under Shock Impact (During Operation)	70 m/s² at 22 ms	
Maximum Acceleration Under Vibrational Stress (During Operation)	5 m/s² at 9200 Hz	
Maximum Deflection Under Vibratory Load (During Operation)	1.5 mm at 29 Hz	
Permitted Relative Humidity (During Operation)	Class 3K5 according to EN 60721-3	
Volume Of Cooling Air	128.0 m3/h	
Type Of Cooling	Forced convection	
Overvoltage Category	Class III	

Regulation Loop	Adjustable PID regulator
Noise Level	56.7 dB
Pollution Degree	2
Ambient Air Transport Temperature	-4070 °C
Ambient Air Temperature For Operation	-1550 °C without derating (vertical position) 5060 °C with derating factor (vertical position)
Ambient Air Temperature For Storage	-4070 °C
Isolation	Between power and control terminals

Packing Units

•	
Unit Type Of Package 1	PCE
Number Of Units In Package 1	1
Package 1 Height	30.000 cm
Package 1 Width	56.000 cm
Package 1 Length	34.000 cm
Package 1 Weight	11.900 kg
Unit Type Of Package 2	P06
Number Of Units In Package 2	2
Package 2 Height	75.000 cm
Package 2 Width	60.000 cm
Package 2 Length	80.000 cm
Package 2 Weight	36.800 kg

Contractual warranty

Warranty

18 months

Sustainability Screen Premium

Green PremiumTM label is Schneider Electric's commitment to delivering products with best-inclass environmental performance. Green Premium promises compliance with the latest regulations, transparency on environmental impacts, as well as circular and low-CO₂ products.

Guide to assessing product sustainability is a white paper that clarifies global eco-label standards and how to interpret environmental declarations.

Learn more about Green Premium >

Guide to assess a product's sustainability >



Transparency RoHS/REACh

Resource performance

Upgraded Components Available

Well-being performance

Mercury Free

Rohs Exemption Information Yes

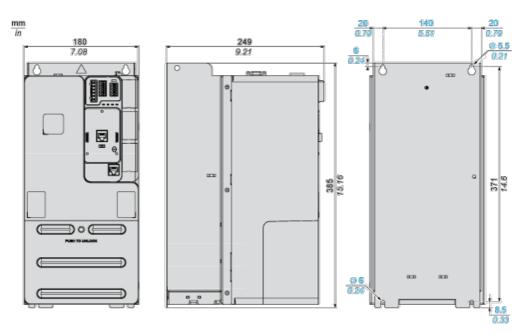
Certifications & Standards

Reach Regulation	REACh Declaration	
Eu Rohs Directive	Pro-active compliance (Product out of EU RoHS legal scope)	
China Rohs Regulation	China RoHS declaration	
Environmental Disclosure	Product Environmental Profile	
Weee	The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins	
Circularity Profile	End of Life Information	

Dimensions Drawings

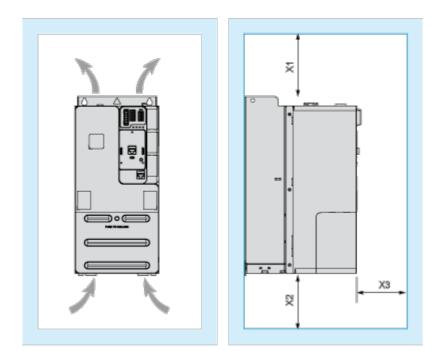
Dimensions

Views: Front - Left - Rear



Mounting and Clearance

Clearance



Dimensions in mm

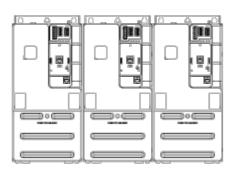
X1	X2	X3
≥ ₁₀₀	≥ ₁₀₀	≥ ₆₀

Dimensions in in.

X1	X2	Х3
≥ _{3.94}	≥ _{3.94}	≥ _{2.36}

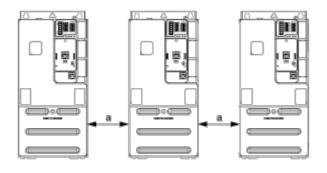
Mounting Types

Mounting Type A: Side by Side IP20



Possible, at ambient temperature ≤ 50 °C (122 °F)

Mounting Type B: Individual IP20



a [≥] 50 mm (1.97 in.) from 50...60°C, no restriction below 50°C

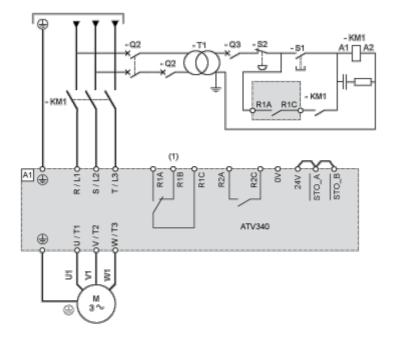
ATV340D22N4

Connections and Schema

Connections and Schema

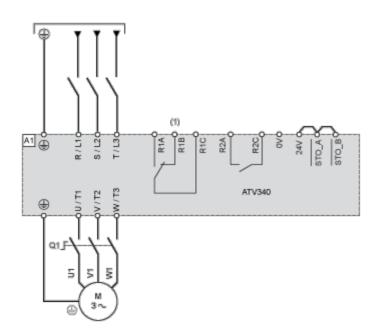
Three-phase Power Supply with Upstream Breaking via Line Contactor Without Safety Function STO

Connection diagrams conforming to standards ISO13849 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1.



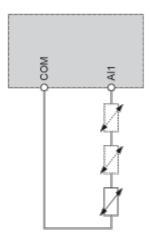
- (1) Use relay output R1 set to operating state Fault to switch Off the product once an error is detected.
- A1: Drive
- KM1 : Line Contactor
- Q2, Q3 : Circuit breakers
- S1: Pushbutton
- S2 : Emergency stop
- T1: Transformer for control part

Three-phase Power Supply With Downstream Breaking via Switch Disconnector



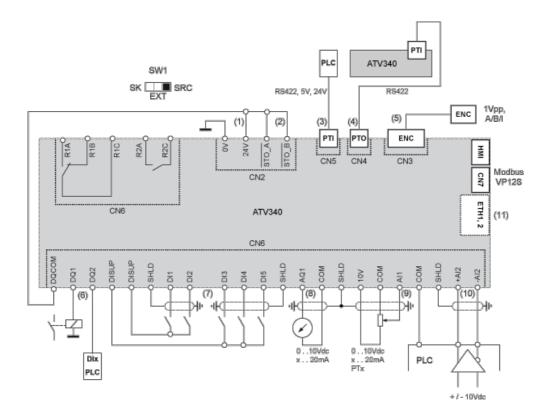
- (1) Use relay output R1 set to operating state Fault to switch Off the product once an error is detected.
- A1: Drive
- Q1 : Switch disconnector

Sensor Connection



It is possible to connect either 1 or 3 sensors on terminals Al1.

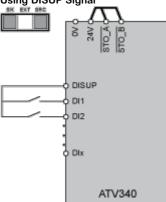
Control Block Wiring Diagram



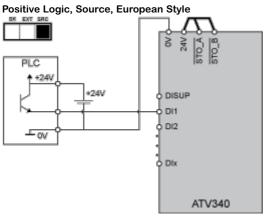
- (1) 24V supply (STO)
- (2) STO Safe Torque Off
- (3) PTI Pulse Train In
- (4) PTO Pulse Train Out
- (5) Motor Encoder connection
- (6) Digital outputs
- (7) Digital inputs
- (8) Analog output
- (9) Analog input
- (10) Differential Analog Input
- (11) Ethernet port (only on Ethernet drive version)
- SW1 : Sink/Source switch
- R1A, R1B, R1C : Fault relay
- R2A, R2C : Sequence relay

Digital Inputs Wiring

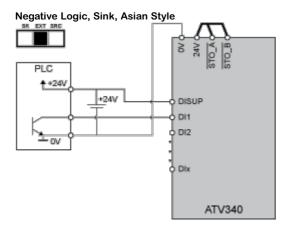
Digital Inputs: Internal Supply Using DISUP Signal



In SRC position DISUP outputs 24 V. In SK position DISUP is connected to 0 V.

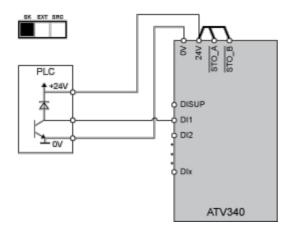


Digital Inputs: External Supply



Digital Inputs: Internal supply Negative Logic, Sink, Asian Style

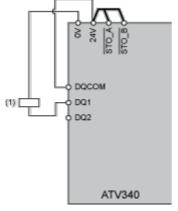
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Digital Outputs Wiring

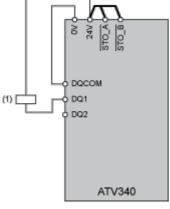
Digital Outputs: Internal Supply

Positive Logic, Source, European Style, DQCOM to +24V



(1) Relay or valve

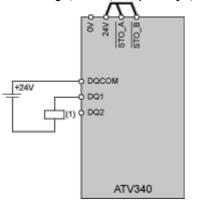
Negative Logic, Sink, Asian Style, DQCOM to 0V



(1) Relay or valve

Digital Outputs: External Supply

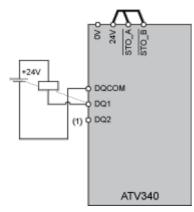
Positive Logic, Source, European Style, DQCOM to +24V



(1) Relay or valve

Negative Logic, Sink, Asian Style, DQCOM to 0V

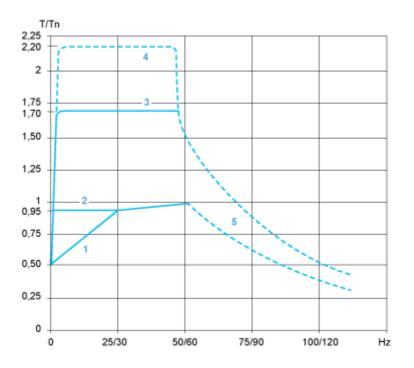
ATV340D22N4



(1) Relay or valve

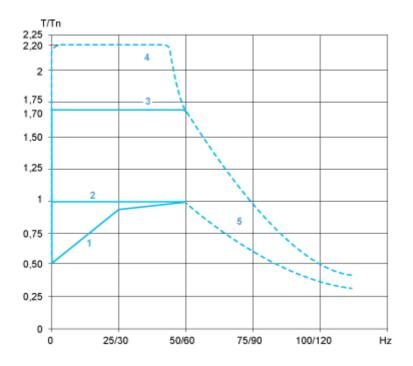
Performance Curves

Open Loop Applications



- 1: Self-cooled motor: continuous useful torque
- 2: Force-cooled motor: continuous useful torque
- 3: Overtorque for 60 s maximum
- 4: Transient overtorque for 2 s maximum
- 5: Torque in overspeed at constant power

Closed Loop Applications



- 1: Self-cooled motor: continuous useful torque
- 2: Force-cooled motor: continuous useful torque
- 3: Overtorque for 60 s maximum
- 4: Transient overtorque for 2 s maximum
- 5: Torque in overspeed at constant power