# **Product datasheet**

Specification





# variable speed drive, ATV930, 4kW, 200/240V, with braking unit, IP21

Local distributor code:

402706724 ATV930U40M3

EAN Code: 3606480883583

# Main

Range Of Product	Altivar Process ATV900	
Device Application	Industrial application	
Product Or Component Type	Variable speed drive	
Product Destination	Asynchronous motors Synchronous motors	
Product Specific Application	Process for industrial	
Variant	Standard version With braking chopper	
Network Number Of Phases	3 phases	
Mounting Mode	Wall mount	
Communication Port Protocol	Modbus serial Modbus TCP EtherNet/IP	
[Us] Rated Supply Voltage	200240 V - 1510 %	
Motor Power Kw	4.0 kW for normal duty 3.0 kW for heavy duty	
Continuous Output Current	18.7 A at 4 kHz for normal duty 13.7 A at 4 kHz for heavy duty	
Emc Filter	Integrated With EMC plate option	
Ip Degree Of Protection	IP21	
Degree Of Protection	UL type 1	
Option Module	Slot A: communication module for Profibus DP V1 Slot A: communication module for PROFINET Slot A: communication module for DeviceNet Slot A: communication module for EtherCAT Slot A: communication module for CANopen daisy chain RJ45 Slot A: communication module for CANopen SUB-D 9 Slot A: communication module for CANopen screw terminals Slot A/slot B/slot C: digital and analog I/O extension module Slot A/slot B/slot C: output relay extension module Slot B: 5/12 V digital encoder interface module Slot B: analog encoder interface module Slot B: resolver encoder interface module communication module for Ethernet Powerlink	
Discrete Input Logic	16 preset speeds	
Asynchronous Motor Control Profile	Optimized torque mode Constant torque standard Variable torque standard	
Synchronous Motor Control Profile	Permanent magnet motor Synchronous reluctance motor	
Maximum Output Frequency	599 Hz	

Switching Frequency	216 kHz adjustable 416 kHz with derating factor
Nominal Switching Frequency	4 kHz
Line Current	15.1 A at 200 V (normal duty)
	11.7 A at 200 V (heavy duty)
	12.9 A at 240 V (normal duty)
	10.2 A at 240 V (heavy duty)
Apparent Power	5.4 kVA at 240 V (normal duty)
	4.2 kVA at 240 V (heavy duty)
Maximum Transient Current	22.4 A during 60 s (normal duty)
	20.6 A during 60 s (heavy duty)
Network Frequency	5060 Hz
Prospective Line Isc	50 kA

# Complementary

Complemental y		
Discrete Input Number	10	
Discrete Input Type	DI1DI8 programmable, 24 V DC (<= 30 V), impedance: 3.5 kOhm DI7, DI8 programmable as pulse input: 030 kHz, 24 V DC (<= 30 V) STOA, STOB safe torque off, 24 V DC (<= 30 V), impedance: > 2.2 kOhm	
Discrete Output Number	2	
Discrete Output Type	Logic output DQ+ 01 kHz <= 30 V DC 100 mA  Programmable as pulse output DQ+ 030 kHz <= 30 V DC 20 mA  Logic output DQ- 01 kHz <= 30 V DC 100 mA	
Analogue Input Number	3	
Analogue Input Type	AI1, AI2, AI3 software-configurable voltage: 010 V DC, impedance: 30 kOhm, resolution 12 bits AI1, AI2, AI3 software-configurable current: 020 mA/420 mA, impedance: 250 Ohm, resolution 12 bits	
Analogue Output Number	2	
Analogue Output Type	Software-configurable voltage AQ1, AQ2: 010 V DC impedance 470 Ohm, resolution 10 bits Software-configurable current AQ1, AQ2: 020 mA impedance 500 Ohm, resolution 10 bits	
Relay Output Number	3	
Relay Output Type	Configurable relay logic R1: fault relay NO/NC electrical durability 100000 cycles Configurable relay logic R2: sequence relay NO electrical durability 1000000 cycles Configurable relay logic R3: sequence relay NO electrical durability 1000000 cycles	
Maximum Switching Current	Relay output R1 on resistive load, cos phi = 1: 3 A at 250 V AC Relay output R1 on resistive load, cos phi = 1: 3 A at 30 V DC Relay output R1 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 250 V AC Relay output R1 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 30 V DC Relay output R2, R3 on resistive load, cos phi = 1: 5 A at 250 V AC Relay output R2, R3 on resistive load, cos phi = 1: 5 A at 30 V DC Relay output R2, R3 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 250 V AC Relay output R2, R3 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 30 V DC	
Minimum Switching Current	Relay output R1, R2, R3: 5 mA at 24 V DC	
Physical Interface	Ethernet 2-wire RS 485	
Connector Type	2 RJ45 1 RJ45	
Method Of Access	Slave Modbus TCP	
Transmission Rate	10, 100 Mbits 4.8 kbps 9600 bit/s 19200 bit/s	

Transmission Frame  RTU  Number Of Addresses  1247  Type Of Polarization  No impedance  4 Quadrant Operation Possible  True  Acceleration And Deceleration Remps  Motor Silp Compensation  Automatic whatever the load Not available in permanent ringnet motor law Can be suppressed  Braking To Standstill  By DC injection  Brake Chopper Integrated  True  Maximum loput Current  15.1 A  Maximum Output Voltage  240 0 V  Relative Symmetric Network Frequency Tolerance  Base Load Current At High  13.7 A  Overload  Base Load Current At Low  Power Dissipation in W  Natural convection: 38 W at 200 V, switching frequency 4 kHz  Forced convection: 141 W at 200 V, switching frequency 4 kHz  With Safely Function Safely  Limited Speed (Sis)  With Safely Function Safely  With Safely Function Safely  With Safely Function Safely  Coparating Slop (Sos)  With Safely Function Safe Pose  With Safely Funct		
Data Format  8 bits, configurable odd, even or no parity  Type Of Polarization  No impedance  4 Quadrant Operation Possible  True  Acceleration And Deceleration Ramps  Motor Silp Compensation  Automatic whatever the load Not available in permanent magnet motor law Aquisable Can be suppressed  Braking To Standstill  By DC injection  Brake Chopper Integrated  True  Maximum Input Current  16:1 A  Maximum Input Voltage  240.0 V  Relative Symmetric Network Frequency Iolizanace  Sase Load Current At High Overfload  Sase Load Current At High Overfload  Power Dissipation in W  Natural convection: 38 W at 200 V, switching frequency 4 kHz Forced convection: 14! W at 200 V, switching frequency 4 kHz Forced convection: 14! W at 200 V, switching frequency 4 kHz Forced convection: 14! W at 200 V, switching frequency 4 kHz Forced convection: 14! W at 200 V, switching frequency 4 kHz Forced convection: 14! W at 200 V, switching frequency 4 kHz Forced convection: 14! W at 200 V, switching frequency 4 kHz Forced convection: 14! W at 200 V, switching frequency 4 kHz Forced convection: 14! W at 200 V, switching frequency 4 kHz Forced convection: 14! W at 200 V, switching frequency 4 kHz Forced convection: 14! W at 200 V, switching frequency 4 kHz Forced convection: 14! W at 200 V, switching frequency 4 kHz Forced convection: 14! W at 200 V, switching frequency 4 kHz Forced convection: 14! W at 200 V, switching frequency 4 kHz Forced convection: 14! W at 200 V, switching frequency 4 kHz Forced convection: 14! W at 200 V, switching frequency 4 kHz Forced convection: 15! True  With Safety Function Safe False  Posterion (Saf)  With Safety Function Safe False  With Safety Function Safe False  True  True  True  The Maximum Maximum Maximum Maximum Maximum Maximum Maximum Maximum  The Safe Sorque of finity  Overload of output of the Safe Sorque of finity  Overload of output of the Safe Sorque of finity  Overload of output of the Safe Sorque of finity  Overload of output of the Current of the Current of the Safe Sorque of finity  Overload	Transmission Frame	RTU
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4 Quadrant Operation Possible True Acceleration And Deceleration Ramps Motor Slip Compensation Motor Slip Compensation Automatic whatever the load Not available in permanent magnet motor law Adjustable Can be suppressed Braking To Standstill By DC injection Brake Chopper Integrated True Maximum Input Current 15.1 A Maximum Output Voltage 240.0 V Rolative Symmetric Network Frequency Tolerance Base Load Current At High Overload Base Load Current At Low Overload  Not available in your provided in the State of Stat	Data Format	8 bits, configurable odd, even or no parity
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Relative Symmetric Network Frequency Tolerance  Base Load Current At High Overload  Base Load Current At Low Overload  Base Load Current At Low Overload  Base Load Current At Low Overload  Natural convection: 38 W at 200 V, switching frequency 4 kHz Forced convection: 141 W at 200 V, switching frequency 4 kHz Forced convection: 141 W at 200 V, switching frequency 4 kHz  With Safety Function Safely Limited Speed (Sis)  True  With Safety Function Safe Brake Management (Skor/Sbt) With Safety Function Safe Position (Sp)  With Safety Function Safe False Position (Sp)  With Safety Function Safe False Monitor (Ssm)  With Safety Function Safe Speed Monitor (Ssm)  With Safety Function Safe Stop 1 (Ssf) With Safety Function Safe Stop 2 With Safety Function Safe Stop 2 False  With Safety Function Safe Torque Off (Sto)  With Safety Function Safe Torque Off (Sto)  With Safety Function Safe Torque Off (Sto)  True  True  True  True  Thermal protection: motor Safe torque off: motor Motor phase break: motor Thermal protection: drive Safe torque off: drive Overheading: drive Overcurrent between output phases and earth: drive Overcurrent between output phases and earth: drive Overcurrent between output phases and earth: drive Overcurrent between output phases horak: drive Overcurrent between output phases and earth: drive Overcurrent between output phases horak: drive Overcurrent between output phases and earth: drive Overcurrent between output phases and earth: drive Overcurrent between output phases horak: drive Overcurrent between output phases horak: drive Overcurrent between output phases horak: drive Overcurrent between output phases and earth: drive Overcurrent between output phases horak: drive Overcurrent between output phases horak: drive Overcurrent between output phases horak: drive Overcurrent drive Overcurrent drive Overcurrent drive Overcurrent drive Overcurrent drive Overcurr	Maximum Input Current	15.1 A
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Forced convection: 141 W at 200 V, switching frequency 4 kHz  With Safety Function Safe Brake Management (Sbc/Sbt)  With Safety Function Safe Operating Stop (Sos)  With Safety Function Safe Position (Sp)  With Safety Function Safe Programmable Logic  With Safety Function Safe Programmable Logic  With Safety Function Safe Speed Monitor (Ssm)  With Safety Function Safe Speed With Safety Function Safe Speed With Safety Function Safe Speed With Safety Function Safe Stop 1 (Ss1)  With Safety Function Safe Stop 1 (Ss1)  With Safety Function Safe Torque Off (Sto)  With Safety Function Safe Income Off (Sto)  With Safety Function Safe Inco		18.7 A
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Monitor (Ssm)  With Safety Function Safe Stop 1 (Ss1)  With Safety Function Safe Torque Off (Sto)  With Safety Function Safely  Limited Position (Slp)  With Safety Function Safe Direction (Slp)  With Safety Function Safe Direction (Slp)  False  True  True  True  True  True  With Safety Function Safely  Limited Position (Slp)  False  False  Direction Type  Thermal protection: motor  Safe torque off: motor  Motor phase break: motor  Thermal protection: drive  Safe torque off: drive  Overcurrent between output phases and earth: drive  Overcurrent between output voltage: drive  Notor phase break: drive  Overvoltages on the DC bus: drive  Line supply overvoltage: drive  Line supply undervoltage: drive  Line supply phase loss: drive  Overspeed: drive  Break on the control circuit: drive  Overspeed: drive  Break on the control circuit: drive		False
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With Safety Function Safe Direction (Sdi)  Protection Type  Thermal protection: motor Safe torque off: motor Motor phase break: motor Thermal protection: drive Safe torque off: drive Overheating: drive Overload of output voltage: drive Short-circuit protection: drive Motor phase break: drive Overvoltages on the DC bus: drive Line supply overvoltage: drive Line supply phase loss: drive Overspeed: drive Break on the control circuit: drive  Quantity Per Set  Thermal protection: motor Safe torque off: motor Motor phase break: motor Thermal protection: drive Safe torque off: drive Overcurrent between output phases and earth: drive Overvoltage: drive Short-circuit protection: drive Une supply overvoltage: drive Line supply undervoltage: drive Line supply phase loss: drive Overspeed: drive Break on the control circuit: drive		True
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Safe torque off: motor Motor phase break: motor Thermal protection: drive Safe torque off: drive Overheating: drive Overcurrent between output phases and earth: drive Overload of output voltage: drive Short-circuit protection: drive Motor phase break: drive Overvoltages on the DC bus: drive Line supply overvoltage: drive Line supply undervoltage: drive Line supply phase loss: drive Overspeed: drive Break on the control circuit: drive		False
Quantity Per Set 1	Protection Type	Safe torque off: motor Motor phase break: motor Thermal protection: drive Safe torque off: drive Overheating: drive Overcurrent between output phases and earth: drive Overload of output voltage: drive Short-circuit protection: drive Motor phase break: drive Overvoltages on the DC bus: drive Line supply overvoltage: drive Line supply undervoltage: drive Line supply phase loss: drive Overspeed: drive
	Quantity Per Set	

Height	350 mm	
Depth	206 mm	
Net Weight	4.6 kg	
<b>Electrical Connection</b>	Control: screw terminal 0.51.5 mm²/AWG 20AWG 16 Line side: screw terminal 46 mm²/AWG 12AWG 10 DC bus: screw terminal 46 mm²/AWG 12AWG 10 Motor: screw terminal 6 mm²/AWG 10	
Transmission Rate	10/100 Mbit/s for Ethernet IP/Modbus TCP 4.8, 9.6, 19.2, 38.4 kbit/s for Modbus serial	
Exchange Mode	Half duplex, full duplex, autonegotiation Ethernet IP/Modbus TCP	
Data Format	8 bits, configurable odd, even or no parity for Modbus serial	
Type Of Polarization	No impedance for Modbus serial	
Number Of Addresses	1247 for Modbus serial	
Supply	External supply for digital inputs: 24 V DC (1930 V), <1.25 mA, protection type: overload and short-circuit protection Internal supply for reference potentiometer (1 to 10 kOhm): 10.5 V DC +/- 5 %, <10 mA, protection type: overload and short-circuit protection Internal supply for digital inputs and STO: 24 V DC (2127 V), <200 mA, protection type: overload and short-circuit protection	
Local Signalling	Local diagnostic: 3 LED (mono/dual colour) Embedded communication status: 5 LED (dual colour) Communication module status: 2 LED (dual colour) Presence of voltage: 1 LED (red)	
Input Compatibility	DI1DI8: discrete input level 1 PLC conforming to IEC 61131-2 DI7, DI8: pulse input level 1 PLC conforming to IEC 65A-68 STOA, STOB: discrete input level 1 PLC conforming to IEC 61131-2	
Discrete Input Logic	Positive logic (source) (DI1DI8), < 5 V (state 0), > 11 V (state 1) Negative logic (sink) (DI1DI8), > 16 V (state 0), < 10 V (state 1) Positive logic (source) (DI7, DI8), < 0.6 V (state 0), > 2.5 V (state 1) Positive logic (source) (STOA, STOB), < 5 V (state 0), > 11 V (state 1)	
Sampling Duration	2 ms +/- 0.5 ms (DI1DI8) - discrete input 5 ms +/- 1 ms (DI7, DI8) - pulse input 1 ms +/- 1 ms (AI1, AI2, AI3) - analog input 5 ms +/- 1 ms (AQ1, AQ2) - analog output	
Accuracy	+/- 0.6 % Al1, Al2, Al3 for a temperature variation 60 °C analog input +/- 1 % AQ1, AQ2 for a temperature variation 60 °C analog output	
Linearity Error	Al1, Al2, Al3: +/- 0.15 % of maximum value for analog input AQ1, AQ2: +/- 0.2 % for analog output	
Refresh Time	Relay output (R1, R2, R3): 5 ms (+/- 0.5 ms)	
Isolation	Between power and control terminals	
Environment		
Operating Altitude	<= 1000 m without derating 10004800 m with current derating 1 % per 100 m	
Operating Position	Vertical +/- 10 degree	
Product Certifications	UL CSA TÜV	
Marking	CE	
Standards	UL 508C IEC 61800-3 IEC 61800-5-1 IEC 61000-3-12 IEC 60721-3 IEC 61508 IEC 13849-1	

<48 % full load conforming to IEC 61000-3-12	
Enclosed	
Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3 Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4 1.2/50 µs - 8/20 µs surge immunity test level 3 conforming to IEC 61000-4-5 Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6	
Class 3C3 according to IEC 60721-3-3 Class 3S3 according to IEC 60721-3-3	
150 m/s² at 11 ms	
10 m/s² at 13200 Hz	
1.5 mm at 213 Hz	
Class 3K5 according to EN 60721-3	
38 m3/h	
III	
Adjustable PID regulator	
> 1 MOhm 500 V DC for 1 minute to earth	
54.5 dB conforming to 86/188/EEC	
1.5 mm peak to peak (f= 213 Hz) conforming to IEC 60068-2-6 1 gn (f= 13200 Hz) conforming to IEC 60068-2-6	
15 gn for 11 ms conforming to IEC 60068-2-27	
Chemical pollution resistance class 3C3 conforming to IEC 60721-3-3  Dust pollution resistance class 3S3 conforming to IEC 60721-3-3	
595 % without condensation conforming to IEC 60068-2-3	
-1550 °C (without derating) 5060 °C (with derating factor)	
54.5 dB	
2	
-4070 °C	
-4070 °C	
PCE	
1	
31.000 cm	
19.000 cm	
41.000 cm	
6.086 kg	
P06	
6	
75.000 cm	
60.000 cm	
80.000 cm	

Package 2 Weight

49.516 kg

# **Contractual warranty**

Warranty

18 months



**Green Premium**<sup>TM</sup> **label** is Schneider Electric's commitment to delivering products with best-inclass environmental performance. Green Premium promises compliance with the latest regulations, transparency on environmental impacts, as well as circular and low-CO<sub>2</sub> products.

**Guide to assessing product sustainability** is a white paper that clarifies global eco-label standards and how to interpret environmental declarations.

Learn more about Green Premium >

Guide to assess a product's sustainability >





Transparency RoHS/REACh

# Resource performance



Upgraded Components Available

# Well-being performance



Mercury Free



Rohs Exemption Information

Yes

#### **Certifications & Standards**

Reach Regulation	REACh Declaration	
Eu Rohs Directive	Pro-active compliance (Product out of EU RoHS legal scope)	
China Rohs Regulation	China RoHS declaration	
Environmental Disclosure	Product Environmental Profile	
Weee	The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins	
Circularity Profile	End of Life Information	

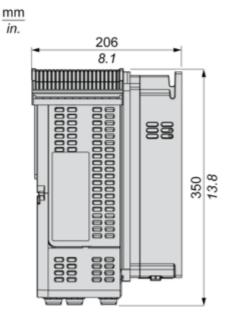
mm

in.

# **Dimensions Drawings**

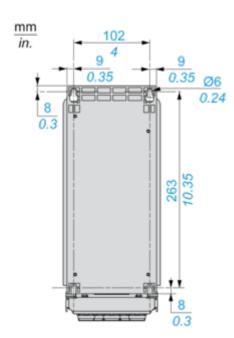
#### **Dimensions**

Right, Front and Rear View



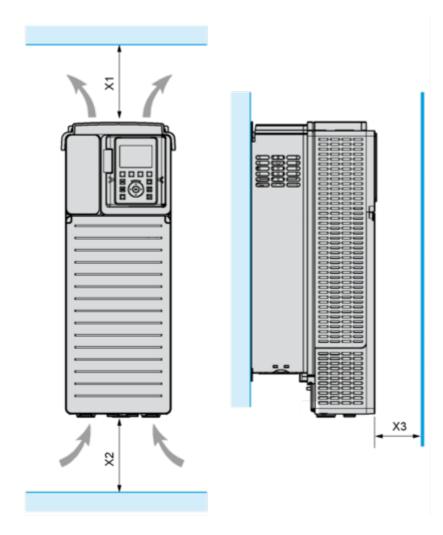


130 5.12



# Mounting and Clearance

#### Clearances

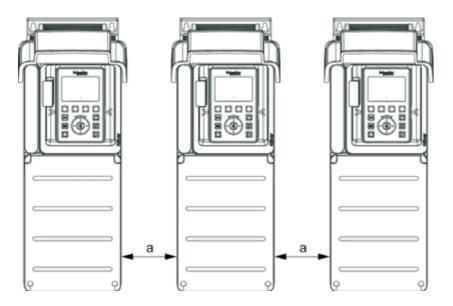


X1	X2	X3
≥ 100 mm (3.94 in.)	≥ 100 mm (3.94 in.)	≥ 10 mm (0.39 in.)

- $_{\bullet}$  Mount the device in a vertical position (±10°). This is required for cooling the device.
- Do not mount the device close to heat sources.
- Leave sufficient free space so that the air required for cooling purposes can circulate from the bottom to the top of the drive.

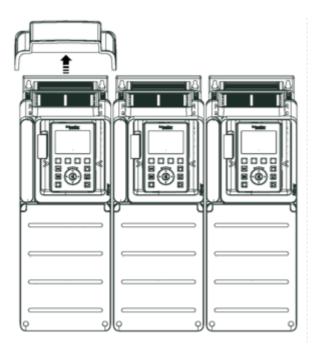
# **Mounting Types**

#### Mounting Type A: Individual IP21

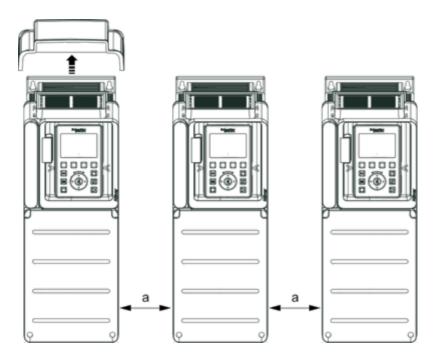


a ≥ 100 mm (3.94 in.)

# Mounting Type B: Side by Side IP20



# Mounting Type C: Individual IP20

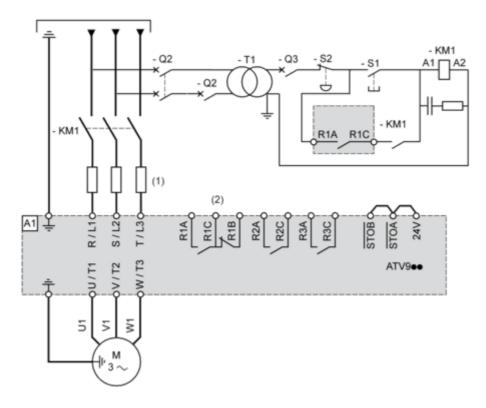


a ≥ 0

#### Connections and Schema

#### Three-Phase Power Supply with Upstream Breaking via Line Contactor

Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1



(1) Line choke if used

(2) Use relay R1 set to operating state Fault to switch Off the product once an error is detected.

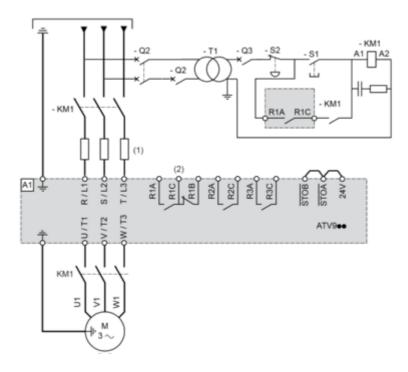
A1 : Drive

KM1 : Line Contactor Q2, Q3 : Circuit breakers S1, S2 : Pushbuttons

T1: Transformer for control part

# Three-Phase Power Supply with Downstream Breaking via Contactor

Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1



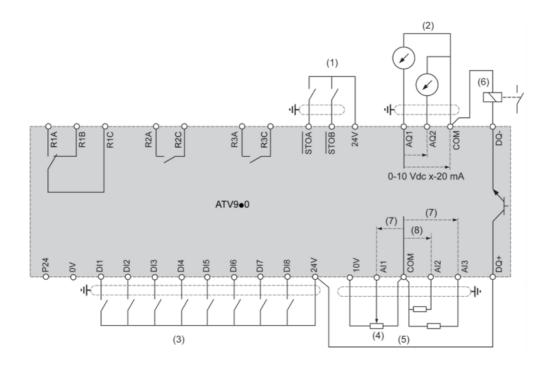
(1) Line choke if used

(2) Use relay R1 set to operating state Fault to switch Off the product once an error is detected.

A1 : Drive KM1 : Contactor

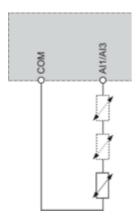
13

# **Control Block Wiring Diagram**



- (1) Safe Torque Off
- (2) Analog Output
- (3) Digital Input
- (4) Reference potentiometer
- (5) Analog Input
- (6) Digital Output
- (7) 0-10 Vdc, x-20 mA
- (8) 0-10 Vdc, -10 Vdc...+10 Vdc R1A, R1B, R1C: Fault relay R2A, R2C: Sequence relay R3A, R3C: Sequence relay

# **Sensor Connection**



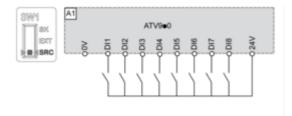
It is possible to connect either 1 or 3 sensors on terminals Al1 or Al3

#### Sink / Source Switch Configuration

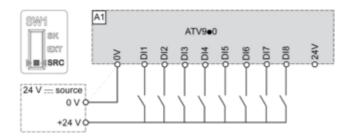
The switch is used to adapt the operation of the logic inputs to the technology of the programmable controller outputs.

- Set the switch to Source (factory setting) if using PLC outputs with PNP transistors.
- Set the switch to Ext if using PLC outputs with NPN transistors.

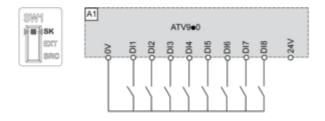
#### Switch Set to SRC (Source) Position Using the Output Power Supply for the Digital Inputs



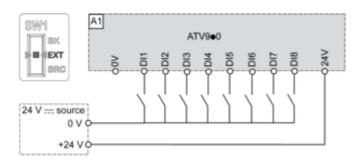
#### Switch Set to SRC (Source) Position and Use of an External Power Supply for the DIs



#### Switch Set to SK (Sink) Position Using the Output Power Supply for the Digital Inputs

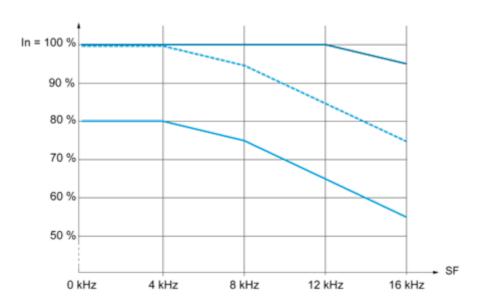


#### Switch Set to EXT Position Using an External Power Supply for the DIs



#### Performance Curves

#### **Derating Curves**



40 °C (104 °F) - Mounting type A, B and C 50 °C (122 °F) - Mounting type A, B and C 60 °C (140 °F) - Mounting type B and C

In: Nominal Drive Current SF: Switching Frequency