## Product datasheet

Specifications

enclosed variable speed drive ATV61 Plus-LH 400 KW 400V IP23 - low harmonic

ATV61EXC2C40N4H
(!) Discontinued on: Jan 23, 2021
(!) Discontinued
Main

| Range Of Product | Altivar 61 Plus-LH |
| :---: | :---: |
| Product Or Component Type | Variable speed drive |
| Device Short Name | ATV61 |
| Product Destination | Asynchronous motors Synchronous motors |
| Assembly Style | In floor-standing enclosure compact version |
| Kit Composition | A switch and fast-acting fuses <br> A line choke <br> A wired ready-assembled Schneider Spacial SF enclosure <br> Clean power filter with integrated EMC filter <br> Control transformer 230 V AC <br> Terminals/bars for motor connection <br> Active infeed converter <br> ATV61HC40N4D standard drive IP00 <br> An IP65 remote mounting kit for graphic display terminal Power supply 24 V DC |
| Emc Filter | Integrated |
| Network Number Of Phases | 3 phases |
| Rated Supply Voltage | $380 . .415 \mathrm{~V}+/-10 \%$ |
| Supply Voltage Limits | $342 . .457 \mathrm{~V}$ |
| Supply Frequency | $50 \ldots 60 \mathrm{~Hz}-5 . .5$ \% |
| Network Frequency Limits | 47.5 ... 63 Hz |
| Motor Power Kw | $400 \mathrm{~kW}, 3$ phases at $380 \ldots 415 \mathrm{~V}$ |
| Line Current | 628 A at 400 V 3 phases / 400 kW |
| Ip Degree Of Protection | IP23 |

Complementary

| Apparent Power | 435 kVA for $400 \mathrm{~V}, 3$ phases 400 kW |
| :--- | :--- |
| Prospective Line Isc | 100 kA with external fuses |
| 35 kA without external fuses |  |
| 70 kA with option circuit breaker |  |, | Continuous Output Current | $759 \mathrm{~A}, 2.5 \mathrm{kHz}$ at 400 V 3 phases |
| :--- | :--- |
| Maximum Transient Current | 911 A (duration $=60 \mathrm{~s})$ at 400 V 3 phases |
| Speed Drive Output Frequency | $0.1 \ldots .500 \mathrm{~Hz}$ |
| Nominal Switching Frequency | 2.5 kHz |
| Switching Frequency | $2 \ldots . .8 \mathrm{kHz}$ adjustable |
|  | $2.5 \ldots 8 \mathrm{kHz}$ with derating factor |


| Speed Range | 1... 100 in open-loop mode, without speed feedback |
| :---: | :---: |
| Speed Accuracy | +/-10\% of nominal slip 0.2 Tn to Tn without speed feedback |
| Torque Accuracy | +/-15\% in open-loop mode, without speed feedback |
| Transient Overtorque | $120 \%$ of nominal motor torque for 60 s |
| Braking Torque | 100 \% continuous <br> 120 \% for 60 seconds |
| Asynchronous Motor Control Profile | Flux vector control without sensor, standard Energy saving ratio <br> Voltage/frequency ratio (2 or 5 points) |
| Synchronous Motor Control Profile | Vector control without sensor, standard |
| Regulation Loop | Adjustable PI regulator |
| Motor Slip Compensation | Not available in voltage/frequency ratio (2 or 5 points) <br> Can be suppressed <br> Adjustable <br> Automatic whatever the load |
| Overvoltage Category | Class 3 conforming to EN 50178 |
| Local Signalling | LCD display unit for operation function, status and configuration - mounted in the front door |
| Output Voltage | <= power supply voltage |
| Isolation | Between power and control terminals |
| Type Of Cable | IEC cable at $40^{\circ} \mathrm{C}$, copper $70^{\circ} \mathrm{C} / \mathrm{PVC}$ |
| Electrical Connection | Terminal - $2.5 \mathrm{~mm}^{2}$ / AWG 14 (Al1-/Al1+, Al2, AO1, R1A, R1B, R1C, R2A, R2B, <br> LI1...LI6, PWR) entry from the bottom <br> Bar M12-4 x $300 \mathrm{~mm}^{2}$ (L1/R, L2/S, L3/T) entry from the bottom <br> Bar M12-4 $\times 240 \mathrm{~mm}^{2}$ (U/T1, V/T2, W/T3) entry from the bottom |
| Motor Recommanded Cable Cross Section | $3(3 \times 185) \mathrm{mm}^{2}$ |
| Short-Circuit Protection | 500 A 2 fuses type gl-power supply upstream |
| Supply | External supply: $24 \mathrm{~V}(19 \ldots 30 \mathrm{~V}) \mathrm{DC},<1 \mathrm{~A}, 30 \mathrm{~W}$ Internal supply for reference potentiometer: $10 \mathrm{~V}(10 \ldots 11 \mathrm{~V}) \mathrm{DC},<10 \mathrm{~mA}$ Internal supply: $24 \mathrm{~V}(21 \ldots 27 \mathrm{~V}) \mathrm{DC},<100 \mathrm{~mA}$ |
| Analogue Input Number | 2 |
| Analogue Input Type | Al2 software-configurable voltage: $0 \ldots 10 \mathrm{~V} D \mathrm{CC}, 24 \mathrm{~V}$ max, impedance: 30 kOhm , sampling time: $1.5 \ldots 2.5 \mathrm{~ms}$, resolution: 11 bits <br> Al1-/Al1+ bipolar differential voltage: +/- 10 V DC, 24 V max, sampling time: $1.5 \ldots 2.5$ ms , resolution: 11 bits + sign <br> Al2 software-configurable current: $0 \ldots . .20 \mathrm{~mA} / 4 \ldots 20 \mathrm{~mA}$, impedance: 250 Ohm, sampling time: $1.5 \ldots 2.5 \mathrm{~ms}$, resolution: 11 bits |
| Analogue Output Number | 1 |
| Analogue Output Type | Software-configurable voltage: (AO1) $0 \ldots 10 \mathrm{~V}$ DC - 470 Ohm - sampling time: $1.5 \ldots$ 2.5 ms - resolution: 10 bits <br> Software-configurable current: (AO1) $0 . . .20 \mathrm{~mA} / 4 \ldots 20 \mathrm{~mA}$ - 500 Ohm - sampling time: 1.5 ... 2.5 ms - resolution: 10 bits |
| Discrete Output Number | 1 |
| Discrete Output Type | Configurable relay logic: (R1A, R1B, R1C)NO/NC - 6.5 ...7.5 ms - 100000 cycles |
| Minimum Switching Current | 3 mA at 24 V DC (configurable relay logic) |
| Maximum Switching Current | 5 A at 250 VAC on resistive load $-\cos \mathrm{phi}=1$ for configurable relay logic 5 A at 30 V DC on resistive load $-\mathrm{L} / \mathrm{R}=0 \mathrm{~ms}$ for configurable relay logic 2 A at 250 VAC on inductive load $-\cos \mathrm{phi}=0.4$ for configurable relay logic 2 A at 30 V DC on inductive load $-\mathrm{L} / \mathrm{R}=7 \mathrm{~ms}$ for configurable relay logic |
| Discrete Input Number | 6 |


| Discrete Input Type | ```Programmable (LI1...LI4) at 24 V DC <= 30 V level 1 PLC 3.5 kOhm (duration=1.5.. 2.5 ms) Switch-configurable (LI6) at 24 V DC <= 30 V level 1 PLC 1.5 kOhm (duration=1.5... 2.5 ms) Safety input (PWR) at 24 V DC <= 30 V 1.5 kOhm``` |
| :---: | :---: |
| Discrete Input Logic | Positive logic (source) (LI1...LI6), $0 . . .5 \mathrm{~V}$ (state 0), $11 . . .30 \mathrm{~V}$ (state 1) Negative logic (sink) (LI1...LI6), 16... 30 V (state 0), $0 . . .10 \mathrm{~V}$ (state 1) Positive logic (source) (PWR), $0 . .2 \mathrm{~V}$ (state 0), 17... 30 V (state 1) |
| Acceleration And Deceleration Ramps | Linear adjustable separately from 0.01 to 9000 s S, U or customized |
| Braking To Standstill | By regenerative braking with active front end |
| Protection Type | Against exceeding limit speed: drive <br> Against input phase loss: drive <br> Line supply overvoltage: drive <br> Line supply undervoltage: drive <br> Overcurrent between output phases and earth: drive <br> Overheating protection: drive <br> Overvoltages on the DC bus: drive <br> Power removal: drive <br> Short-circuit between motor phases: drive <br> Thermal protection: motor <br> Motor phase break: motor |
| Dielectric Strength | 3535 V DC between earth and power terminals 5092 V DC between control and power terminals |
| Insulation Resistance | $>1 \mathrm{mOhm} 500 \mathrm{~V}$ DC for 1 minute to earth |
| Frequency Resolution | Analog input: $0.024 / 50 \mathrm{~Hz}$ Display unit: 0.1 Hz |
| Communication Port Protocol | Modbus CANopen |
| Connector Type | 1 RJ45 (on front face) for Modbus 1 RJ45 (on terminal) for Modbus Male SUB-D 9 on RJ45 for CANopen |
| Physical Interface | 2-wire RS 485 for Modbus |
| Transmission Frame | RTU for Modbus |
| Transmission Rate | 4800 bps, 9600 bps, 19200 bps, 38.4 Kbps for Modbus on terminal $9600 \mathrm{bps}, 19200$ bps for Modbus on front face $20 \mathrm{kbps}, 50 \mathrm{kbps}, 125 \mathrm{kbps}, 250 \mathrm{kbps}, 500 \mathrm{kbps}, 1 \mathrm{Mbps}$ for CANopen |
| Data Format | 8 bits, 1 stop, even parity for Modbus on front face 8 bits, odd even or no configurable parity for Modbus on terminal |
| Type Of Polarization | No impedance for Modbus |
| Number Of Addresses | 1... 127 for CANopen <br> 1... 247 for Modbus |
| Method Of Access | Slave CANopen |


| Function Available | Safe standstill for power circuit <br> PTC relay for power circuit <br> Pt100 relay for power circuit <br> Insulation monitoring for power circuit <br> Design for IT networks for power circuit <br> External 230 V supply terminals for power circuit <br> Buffer voltage 24 V DC power supply for power circuit <br> Enclosure lighting for power circuit <br> Key switch (local/remote) for power circuit <br> Motor heating for power circuit <br> External motor fan for power circuit <br> Voltmeter for power circuit <br> Door handle for main switch for power circuit <br> Ammeter for power circuit <br> Enclosure heating for power circuit <br> Motor choke for power circuit <br> Cable entry via the top for power circuit <br> Enclosure plinth for power circuit <br> Relay output C/O for control circuit <br> External 24 V DC supply terminals for power circuit <br> Control terminals for control circuit <br> Adaptor for 115 V logic inputs for control circuit <br> Isolated amplifier for control circuit |
| :---: | :---: |
| Option Card | Communication card for APOGEE FLN <br> Communication card for BACnet <br> Communication card for CC-Link <br> Communication card for DeviceNet <br> Communication card for EtherNet/IP <br> Communication card for Fipio <br> Communication card for Interbus-S <br> Communication card for LonWorks <br> Communication card for METASYS N2 <br> Communication card for Modbus Plus <br> Communication card for Modbus TCP <br> Communication card for Modbus/Uni-Telway <br> Communication card for Profibus DP <br> Communication card for Profibus DP V1 <br> Controller inside programmable card <br> Multi-pump card <br> Basic I/O extension card <br> Extended I/O extension card <br> Encoder interface cards |
| Operating Position | Vertical +/-10 degree |
| Colour Of Enclosure | Light grey (RAL 7035) |
| Width | 2000 mm |
| Height | 2157 mm |
| Depth | 642 mm |
| Net Weight | 1455 kg |
| Environment |  |
| Standards | EN 60204-1 <br> EN 61800-3 environments 2 category C3 <br> EN 61800-5-1 <br> EN 61800-2 |
| Product Certifications | $\begin{aligned} & \text { GOST } \\ & \text { C-Tick } \end{aligned}$ ATEX |
| Marking | CE |
| Noise Level | 71 dB |
| Pollution Degree | 2 conforming to EN/IEC 61800-5-1 |
| Vibration Resistance | 0.6 gn ( $\mathrm{f}=10 \ldots 200 \mathrm{~Hz}$ ) conforming to EN/IEC 60068-2-6 <br> 1.5 mm peak to peak ( $\mathrm{f}=3 \ldots . .10 \mathrm{~Hz}$ ) conforming to EN/IEC 60068-2-6 3M3 conforming to EN/IEC 60721-3-3 |


| Shock Resistance | 4 gn for 11 ms conforming to EN/IEC 60068-2-27 3M2 conforming to EN/IEC 60721-3-3 |
| :---: | :---: |
| Environmental Characteristic | 3 K 3 without condensation conforming to IEC 60721-3-3 |
| Relative Humidity | 0... 95 \% |
| Ambient Air Temperature For Operation | $0 . .40^{\circ} \mathrm{C}$ (without derating) <br> $40 \ldots 50^{\circ} \mathrm{C}$ (with current derating of $1.8 \%$ per ${ }^{\circ} \mathrm{C}$ ) |
| Ambient Air Temperature For Storage | $-25 . .70^{\circ} \mathrm{C}$ |
| Volume Of Cooling Air | $3600 \mathrm{~m} 3 / \mathrm{h}$ |
| Operating Altitude | < $=1000 \mathrm{~m}$ without derating $1000 \ldots 3000 \mathrm{~m}$ with current derating $1 \%$ per 100 m |
| Packing Units |  |
| Unit Type Of Package 1 | PCE |
| Number Of Units In Package 1 | 1 |
| Package 1 Height | 216.0 cm |
| Package 1 Width | 64.0 cm |
| Package 1 Length | 20.0 cm |
| Package 1 Weight | 1454.0 kg |
| Contractual warranty |  |
| Warranty | 18 months |

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Dimensions Drawings

Dimensions


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Connections and Schema

Wiring Diagram


A1 Drive
A2 Enclosure
AIC Active Infeed Converter
M Motor
Q1 Main switch built-in as standard
Q2 Optional circuit breaker
F1 Main fuses
KM1 Line contactor
EMC EMC filter
LFC Line Filter Choke
(1) Control
(2) Relay control
(3) Reference potentiometer
(4) Option motor choke

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Performance Curves

Derating Curves

The derating curves for the drive nominal current (In) are dependent on the temperature and switching frequency. For intermediate temperatures, interpolate between 2 curves.

NOTE: The drive will reduce the switching frequency automatically in the event of excessive temperature rise.


X Switching frequency (kHz)

NOTE: The temperatures shown correspond to the temperature of the air entering the enclosure.

