## Product data sheet

Specifications
(1) Discontinued - Service only

# enclosed variable speed drive ATV61 Plus - 1100 kW - 400V IP23 

ATV61EXA2M11N4
(!) Discontinued on: Dec 31, 2023
(!) To be end-of-service on: Dec 31, 2031

Main

| Range Of Product | Altivar 61 Plus |
| :---: | :---: |
| Product Or Component Type | Variable speed drive |
| Product Destination | Asynchronous motors Synchronous motors |
| Product Specific Application | Pumping and ventilation machine |
| Assembly Style | In floor-standing enclosure with separate air flows |
| Product Composition | A switch and fast-acting fuses <br> A wired ready-assembled Sarel Spacial 6000 enclosure A plinth <br> An IP65 remote mounting kit for graphic display terminal Integrated drive system ATV61EM11N4E1 |
| Emc Filter | Integrated |
| Network Number Of Phases | 3 phases |
| Rated Supply Voltage | 380... $415 \mathrm{~V}+/-10$ \% |
| Supply Frequency | $50 \ldots 60 \mathrm{~Hz}$ |
| Motor Power Kw | $1100 \mathrm{~kW}, 3$ phases at $380 \ldots 415 \mathrm{~V}$ |
| Line Current | 1872 A at 400 V 3 phases / 1100 kW |
| Ip Degree Of Protection | IP23 |

Complementary

| Apparent Power | 1297 kVA for 400 V 3 phases / 1100 kW |
| :--- | :--- |
| Prospective Line Isc | 100 kA with external fuses |
| Continuous Output Current | 1860 A at $2.5 \mathrm{kHz}, 400 \mathrm{~V} 3$ phases |
| Maximum Transient Current | 2232 A for 60 s 3 phases |
| Speed Drive Output Frequency | $0.1 \ldots .500 \mathrm{~Hz}$ |
| Nominal Switching Frequency | 2.5 kHz |
| Switching Frequency | $2 \ldots 4.9 \mathrm{kHz}$ adjustable |
| $2.5 \ldots 4.9 \mathrm{kHz}$ with derating factor |  |
| Speed Range | $1 \ldots .100$ in open-loop mode, without speed feedback |
| Speed Accuracy | $+/-10 \%$ of nominal slip 0.2 Tn to Tn without speed feedback |
| Torque Accuracy | $+/-15 \%$ in open-loop mode, without speed feedback |
| Transient Overtorque | $120 \%$ of nominal motor torque for 60 s |
| $135 \%$ of nominal motor torque for 2 s |  |


| Braking Torque | 30 \% without braking resistor <= $125 \%$ with braking resistor |
| :---: | :---: |
| Asynchronous Motor Control Profile | Voltage/frequency ratio, 5 points <br> Voltage/frequency ratio - Energy Saving, quadratic U/f Flux vector control without sensor, standard Voltage/frequency ratio, 2 points |
| Synchronous Motor Control Profile | Vector control without sensor, standard |
| Regulation Loop | Adjustable PI regulator |
| Motor Slip Compensation | Adjustable <br> Not available in voltage/frequency ratio (2 or 5 points) <br> Suppressable <br> Automatic whatever the load |
| Supply Voltage Limits | $342 \ldots 457 \mathrm{~V}$ |
| Network Frequency Limits | $47.5 \ldots 63 \mathrm{~Hz}$ |
| Overvoltage Category | Class 3 conforming to EN 50178 |
| Local Signalling | LCD display unit for operation function, status and configuration |
| Output Voltage | <= supply voltage |
| Isolation | Electrical between power and control |
| Type Of Cable For External Connection | IEC cable at $40^{\circ} \mathrm{C}$, copper $70{ }^{\circ} \mathrm{C} / \mathrm{PVC}$ |
| Electrical Connection | Terminal - $2.5 \mathrm{~mm}^{2}$ / AWG 140.6 N.m (R1A, R1B, R1C, R2A, R2B) entry from the bottom <br> Screw clamp terminals - $1.5 \mathrm{~mm}^{2} 0.25$ N.m (Al1-/AI1+, Al2, AO1, LI1 ...LI6, PWR) entry from the bottom |
| Motor Recommanded Cable Cross Section | $\begin{aligned} & 9(3 \times 185) \mathrm{mm}^{2} \\ & 7(3 \times 240) \mathrm{mm}^{2} \end{aligned}$ |
| Supply | External supply: $24 \mathrm{~V}(19 \ldots 30 \mathrm{~V}) \mathrm{DC},<1 \mathrm{~A}$ Internal supply for reference potentiometer: $10 \mathrm{~V}(10 . . .11 \mathrm{~V}) \mathrm{DC},<10 \mathrm{~A}$ Internal supply: $24 \mathrm{~V}(21 \ldots 27 \mathrm{~V}) \mathrm{DC},<100 \mathrm{~A}$ |
| Analogue Input Number | 2 |
| Analogue Input Type | Al2 software-configurable voltage: $0 \ldots 10 \mathrm{~V}$ DC, 24 V max, impedance: 30 kOhm , sampling time: $1.5 . . .2 .5 \mathrm{~ms}$, resolution: 11 bits <br> Al1-/Al1+ bipolar differential voltage: +/- 10 V DC, 24 V max, sampling time: $1.5 \ldots . .2 .5$ ms , resolution: 11 bits + sign <br> Al2 software-configurable current: $0 . . .20 \mathrm{~mA} / 4 . . .20 \mathrm{~mA}$, impedance: 250 Ohm, sampling time: $1.5 \ldots 2.5 \mathrm{~ms}$, resolution: 11 bits |
| Analogue Output Number | 1 |
| Analogue Output Type | Software-configurable voltage: (AO1) 0... 10 V DC - 500 Ohm - sampling time: 1.5... 2.5 ms - resolution: 10 bits <br> Software-configurable current: (AO1) $0 \ldots 20 \mathrm{~mA} / 4 \ldots 20 \mathrm{~mA}$ - 500 Ohm - sampling time: $1.5 \ldots 2.5 \mathrm{~ms}$ - resolution: 10 bits |
| Discrete Output Number | 2 |
| Discrete Output Type | Configurable relay logic: (R1A, R1B, R1C)NO/NC - 6.5 ... $7.5 \mathrm{~ms}-100000$ cycles Configurable relay logic: (R2A, R2B)NO - 6.5... $7.5 \mathrm{~ms}-100000$ cycles |
| Minimum Switching Current | 3 mA at 24 V DC (configurable relay logic) |
| Maximum Switching Current | 5 A at 250 VAC on resistive load $-\cos$ phi $=1$ for configurable relay logic 5 A at $30 \mathrm{~V} D C$ on inductive load $-L / R=7 \mathrm{~ms}$ for configurable relay logic 5 A at $30 \mathrm{~V} D C$ on resistive load $-\mathrm{L} / \mathrm{R}=0 \mathrm{~ms}$ for configurable relay logic 5 A at 250 VAC on inductive load $-\cos \mathrm{phi}=0.4$ for configurable relay logic |
| Discrete Input Number | 7 |
| Discrete Input Type | ```Programmable (LI1...LI5) at 24 V DC <= 30 V level 1 PLC 3.5 kOhm (duration=1.5... 2.5 ms) Switch-configurable (LI6) at 24 V DC <= 30 V level 1 PLC 1.5 kOhm (duration=1.5... 2.5 ms) Safety input (PWR) at 24 V DC <= 30 V 1.5 kOhm``` |


| Discrete Input Logic | Positive (LI1...LI6), $0 . . .5 \mathrm{~V}$ (state 0 ), $11 \ldots 30 \mathrm{~V}$ (state 1 ) Negative (LI1...LI6), 16... 30 V (state 0), $0 . .10 \mathrm{~V}$ (state 1) Positive (PWR), $0 . . .2 \mathrm{~V}$ (state 0), 17... 30 V (state 1) |
| :---: | :---: |
| Acceleration And Deceleration Ramps | Linear adjustable separately from 0.01 to 9000 s S, U or customized |
| Braking To Standstill | By DC injection, <60 s |
| Protection Type | Overheating protection: drive <br> Thermal protection: drive <br> Short-circuit between motor phases: drive <br> Input phase breaks: drive <br> Overcurrent between output phases and earth: drive <br> Overvoltages on the DC bus: drive <br> Break on the control circuit: drive <br> Against exceeding limit speed: drive <br> Line supply undervoltage: drive <br> Line supply overvoltage: drive <br> Against input phase loss: drive <br> Thermal protection: motor <br> Motor phase break: motor <br> Power removal: drive <br> Power removal: motor |
| Dielectric Strength | 3535 V DC between earth and power terminals 5092 V DC between control and power terminals |
| Insulation Resistance | $>1$ mohm 500 VDC for 1 minute |
| Frequency Resolution | Display unit: 0.1 Hz <br> Analog input: $0.024 / 50 \mathrm{~Hz}$ |
| Communication Port Protocol | Modbus CANopen |
| Connector Type | 1 RJ45 (on front face) for Modbus 1 RJ45 (on terminal) for Modbus Male SUB-D 9 on RJ45 for CANopen |
| Physical Interface | 2-wire RS 485 for Modbus |
| Transmission Frame | RTU for Modbus |
| Transmission Rate | 9600 bps, 19200 bps for Modbus on front face $4800 \mathrm{bps}, 9600 \mathrm{bps}, 19200 \mathrm{bps}, 38.4 \mathrm{Kbps}$ for Modbus on terminal $20 \mathrm{kbps}, 50 \mathrm{kbps}, 125 \mathrm{kbps}, 250 \mathrm{kbps}, 500 \mathrm{kbps}, 1 \mathrm{Mbps}$ for CANopen |
| Data Format | 8 bits, 1 stop, even parity for Modbus on front face 8 bits, odd even or no configurable parity for Modbus on terminal |
| Type Of Polarization | No impedance for Modbus |
| Number Of Addresses | 1... 247 for Modbus <br> 1... 127 for CANopen |
| Method Of Access | Slave CANopen |
| Options For Enclosure Configuration | Safe standstill for power circuit <br> PTC relay for power circuit Pt100 relay for power circuit Insulation monitoring for power circuit Design for IT networks for power circuit External 230 V supply terminals for power circuit Buffer voltage 24 V DC power supply for power circuit Enclosure lighting for power circuit <br> Key switch (local/remote) for power circuit <br> Motor heating for power circuit <br> External motor fan for power circuit <br> Voltmeter for power circuit <br> Door handle for main switch for power circuit <br> Line contactor for power circuit 12-pulse supply for power circuit Ammeter for power circuit Enclosure heating for power circuit Motor choke for power circuit Cable entry via the top for power circuit Enclosure plinth for power circuit Relay output C/O for control circuit |


| Option Card | Communication card for Modbus TCP/IP <br> Communication card for Fipio <br> Communication card for Modbus/Uni-Telway <br> Communication card for Modbus Plus <br> Communication card for EtherNet/IP <br> Communication card for DeviceNet <br> Communication card for Profibus DP <br> Communication card for Profibus DP V1 <br> Communication card for Interbus-S <br> Communication card for CC-Link <br> Communication card for LonWorks <br> Communication card for METASYS N2 <br> Communication card for APOGEE FLN <br> Communication card for BACnet <br> Basic I/O extension card <br> Extended I/O extension card <br> Controller inside programmable card <br> Multi-pump card <br> Encoder interface cards |
| :---: | :---: |
| Operating Position | Vertical +/-10 degree |
| Colour Of Enclosure | Light grey (RAL 7035) |
| Colour Of Base Of Enclosure | Dark grey (RAL 7022) |
| Width | 3400 mm |
| Height | 2009 mm |
| Depth | 642 mm |
| Net Weight | 1925 kg |
| Environment |  |
| Electromagnetic Compatibility | Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3 <br> Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4 Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6 Voltage dips and interruptions immunity test conforming to IEC 61000-4-11 |
| Standards | EN/IEC 61800-5-1 <br> EN 61800-3 environments 1 category C3 <br> EN/IEC 61800-3 <br> EN 55011 class A group 2 <br> EN 61800-3 environments 2 category C3 |
| Product Certifications | $\begin{aligned} & \text { GOST } \\ & \text { ATEX } \end{aligned}$ |
| Marking | CE |
| Pollution Degree | 2 conforming to EN/IEC 61800-5-1 |
| Noise Level | 79 dB |
| Vibration Resistance | 1.5 mm ( $\mathrm{f}=3 \ldots 10 \mathrm{~Hz}$ ) conforming to EN/IEC 60068-2-6 0.6 gn ( $\mathrm{f}=10 \ldots 200 \mathrm{~Hz}$ ) conforming to EN/IEC 60068-2-6 3M3 conforming to EN/IEC 60721-3-3 |
| Shock Resistance | 4 gn for 11 ms conforming to EN/IEC 60068-2-27 3M2 conforming to EN/IEC 60721-3-3 |
| Environmental Characteristic | 3C2 without condensation conforming to IEC 60721-3-3 3 S2 without condensation conforming to IEC 60721-3-3 3K3 without condensation conforming to IEC 60721-3-3 |
| Relative Humidity | 0... $95 \%$ |
| Ambient Air Temperature For Operation | $0 . .40^{\circ} \mathrm{C}$ (without derating) $40 \ldots 50^{\circ} \mathrm{C}$ (with current derating $1.5 \%$ per ${ }^{\circ} \mathrm{C}$ ) |
| Ambient Air Temperature For Storage | $-25 \ldots 70^{\circ} \mathrm{C}$ |
| Volume Of Cooling Air | $11000 \mathrm{~m} 3 / \mathrm{h}$ |


| Operating Altitude | $<=1000 \mathrm{~m}$ without derating |
| :--- | :--- |
|  | $1000 \ldots 3000 \mathrm{~m} 1 \%$ per 100 m |

## Packing Units

| Unit Type Of Package 1 | PCE |
| :--- | :--- |
| Number Of Units In Package 1 | 1 |
| Package 1 Height | 200.0 cm |
| Package 1 Width | 66.0 cm |
| Package 1 Length | 344.0 cm |
| Package 1 Weight | 1920.0 kg |

## Contractual warranty

## Product data sheet

ATV61EXA2M11N4

Dimensions Drawings

IP 23 Floor-Standing Enclosure with Separate Air Flows

Dimensions


NOTE: For each floor-standing enclosure added, allow a $4 \mathrm{~mm} / 0.15 \mathrm{in}$. space for the seal.

Connections and Schema

Floor-Standing Enclosure with Separate Air Flows

## Standard 6-pulse Design



A1 Drive
A2 Enclosure
F1 Fuses
IL1 Optional line choke
KM1 Optional line contactor

M Motor
Q1 Switch
(1) Filter
(2) Control
(3) Relay control
(4) Reference potentiometer
(5) PLC
(6) Optional motor choke

Optional 12-pulse Design


A1 Drive
A2 Enclosure
F1 Fuses
IL1 Optional line choke
KM1 Optional line contactor
M Motor
Q1 Switch
(1) Filter
(2) Control
(3) Relay control
(4) Reference potentiometer
(5) PLC
(6) Optional motor choke

## Product data sheet

Performance Curves

## IP 23 Floor-Standing Enclosure with Separate Air Flows

## Derating Curves

The derating curves for the drive nominal current (In) are dependent on the temperature and switching frequency. For intermediate temperatures, interpolate between 2 curves.

NOTE: The drive will reduce the switching frequency automatically in the event of excessive temperature rise.


X Switching frequency ( kHz )

NOTE: The temperatures shown correspond to the temperature of the air entering the enclosure.

