## Product data sheet

Specifications


> variable speed drive, Altivar Process
> ATV600, ATV650, $160 \mathrm{~kW}, 400$ to 480 V , floor standing

ATV650C16N4F

| Range Of Product | Altivar Process ATV600 |
| :---: | :---: |
| Product Or Component Type | Variable speed drive |
| Product Specific Application | Process and utilities |
| Device Short Name | ATV650 |
| Variant | With disconnect switch |
| Product Destination | Asynchronous motors Synchronous motors |
| Emc Filter | Integrated with 150 m conforming to IEC 61800-3 category C3 |
| Ip Degree Of Protection | IP54 conforming to IEC 60529 IP54 conforming to IEC 61800-5-1 |
| [Us] Rated Supply Voltage | $380 . .440 \mathrm{~V}$ |
| Type Of Cooling | Forced convection |
| Supply Frequency | $50 \ldots . .60 \mathrm{~Hz}-5 . . .5$ \% |
| [Us] Rated Supply Voltage | $380 . . .440$ V - 15... 10 \% |
| Motor Power Kw | 160 kW (normal duty) <br> 132 kW (heavy duty) |
| Line Current | 251 A at 400 V (heavy duty) <br> 210 A at 380 V (normal duty) <br> 291 A at 380 V (heavy duty) <br> 244 A at 400 V (normal duty) |
| Prospective Line Isc | 50 kA |
| Apparent Power | 191 kVA at 440 V (normal duty) 160 kVA at 440 V (heavy duty) |
| Continuous Output Current | 302 A at 2.5 kHz for normal duty 250 A at 2.5 kHz for heavy duty |
| Asynchronous Motor Control Profile | Optimized torque mode Variable torque standard Variable torque standard |
| Synchronous Motor Control Profile | Synchronous reluctance motor <br> Permanent magnet motor |
| Speed Drive Output Frequency | $0.1 \ldots . .500 \mathrm{~Hz}$ |
| Nominal Switching Frequency | 2.5 kHz |
| Switching Frequency | 2... 8 kHz adjustable <br> $2.5 . . .8 \mathrm{kHz}$ with derating factor |
| Safety Function | STO (safe torque off) SIL 3 |
| Discrete Input Logic | 16 preset speeds |


| Communication Port Protocol | Modbus TCP <br> Modbus serial <br> Modbus serial |
| :--- | :--- |
| Option Card | Slot A: communication module, PROFINET |
|  | Slot A: communication module, DeviceNet |
|  | Slot A: communication module, Modbus TCP/EtherNet/IP |
|  | Slot A: communication module, CANopen daisy chain RJ45 |
|  | Slot A: communication module, CANopen SUB-D 9 |
|  | Slot A: communication module, CANopen screw terminals |
|  | Slot A/slot B: digital and analog I/O extension module |
|  | Slot A/slot B: output relay extension module |
|  | Slot A: communication module, Ethernet IP/Modbus TCP/MD-Link |
|  | Communication module, BACnet MS/TP |
|  | Communication module, Ethernet Powerlink |
|  | Slot A: communication module, Profibus DP V1 |

Complementary

| Mounting Mode | Floor-standing |
| :---: | :---: |
| Maximum Transient Current | 332 A during 60 s (normal duty) <br> 375 A during 60 s (heavy duty) |
| Network Number Of Phases | 3 phases |
| Discrete Output Number | 0 |
| Discrete Output Type | Relay outputs R1A, R1B, R1C 250 V AC 3000 mA Relay outputs R1A, R1B, R1C 30 V DC 3000 mA Relay outputs R2A, R2C 250 V AC 5000 mA Relay outputs R2A, R2C 30 V DC 5000 mA Relay outputs R3A, R3C 250 V AC 5000 mA Relay outputs R3A, R3C 30 V DC 5000 mA |
| Output Voltage | <= power supply voltage |
| Permissible Temporary Current Boost | $1.5 \mathrm{x} \ln$ during 60 s (heavy duty) <br> 1.1 x In during 60 s (normal duty) |
| Motor Slip Compensation | Not available in permanent magnet motor law Automatic whatever the load <br> Adjustable <br> Adjustable |
| Acceleration And Deceleration Ramps | Linear adjustable separately from 0.01...9999 s |
| Physical Interface | Ethernet <br> 2-wire RS 485 |
| Braking To Standstill | By DC injection |
| Protection Type | Safe torque off: motor <br> Motor phase break: motor <br> Thermal protection: drive <br> Safe torque off: drive <br> Overheating: drive <br> Overcurrent between output phases and earth: drive <br> Overload of output voltage: drive <br> Short-circuit protection: drive <br> Motor phase break: drive <br> Overvoltages on the DC bus: drive <br> Line supply overvoltage: drive <br> Line supply undervoltage: drive <br> Line supply phase loss: drive <br> Overspeed: drive <br> Break on the control circuit: drive <br> Thermal protection: motor |
| Transmission Rate | 10, 100 Mbits 4800 bps, 9600 bps, 19200 bps, 38.4 Kbps |
| Frequency Resolution | Analog input: $0.012 / 50 \mathrm{~Hz}$ Display unit: 0.1 Hz |
| ssmission Frame | RTU |


| Electrical Connection | Line side: M12 bar -2 cables $3 \times 70 \mathrm{~mm}^{2}$ minimum per phase (normal duty) Line side: M12 bar - 1 cables $3 \times 185 \mathrm{~mm}^{2}$ maximum per phase (normal duty) Line side: M12 bar -2 cables $3 \times 120 \mathrm{~mm}^{2}$ maximum per phase (normal duty) Motor: M12 bar - 2 cables $3 \times 185 \mathrm{~mm}^{2}$ maximum per phase (normal duty) Line side: M12 bar -2 cables $3 \times 70 \mathrm{~mm}^{2}$ minimum per phase (heavy duty) Line side: M12 bar - 1 cables $3 \times 185 \mathrm{~mm}^{2}$ maximum per phase (heavy duty) Line side: M12 bar - 2 cables $3 \times 120 \mathrm{~mm}^{2}$ maximum per phase (heavy duty) Motor: M12 bar - 2 cables $3 \times 185 \mathrm{~mm}^{2}$ maximum per phase (heavy duty) Line side: M12 bar - 1 cables $3 \times 185 \mathrm{~mm}^{2}$ minimum per phase (normal duty) Motor: M12 bar - 1 cables $3 \times 150 \mathrm{~mm}^{2}$ minimum per phase (normal duty) Motor: M12 bar - 2 cables $3 \times 70 \mathrm{~mm}^{2}$ minimum per phase (normal duty) Line side: M12 bar - 1 cables $3 \times 185 \mathrm{~mm}^{2}$ minimum per phase (heavy duty) Motor: M12 bar - 1 cables $3 \times 120 \mathrm{~mm}^{2}$ minimum per phase (heavy duty) Motor: M12 bar -2 cables $3 \times 50 \mathrm{~mm}^{2}$ minimum per phase (heavy duty) Control: removable screw terminals 0.5 ... $1.5 \mathrm{~mm}^{2}$ |
| :---: | :---: |
| Connector Type | RJ45 (on the remote graphic terminal) for Modbus serial RJ45 (on the remote graphic terminal) for Ethernet/Modbus TCP |
| Data Format | 8 bits, configurable odd, even or no parity |
| Type Of Polarization | No impedance |
| Exchange Mode | Half duplex, full duplex, autonegotiation Ethernet/Modbus TCP |
| Number Of Addresses | 1... 247 for Modbus serial |
| Method Of Access | Slave Modbus TCP |
| Supply | Internal supply for reference potentiometer (1 to 10 kOhm ): $10.5 \mathrm{~V} \mathrm{DC}+/-5 \%,<10$ mA , protection type: overload and short-circuit protection <br> Internal supply for digital inputs and STO: 24 V DC ( $21 \ldots 27 \mathrm{~V}$ ), <200 mA, protection type: overload and short-circuit protection <br> External supply for digital inputs: 24 V DC ( $19 \ldots 30 \mathrm{~V}$ ), $<1.25 \mathrm{~mA}$, protection type: overload and short-circuit protection |
| Local Signalling | 3 LEDs (dual colour) for embedded communication status 4 LEDs (dual colour) for communication module status 1 LED (red) for presence of voltage <br> 3 LEDs for local diagnostic |
| Width | 400 mm |
| Height | 2350 mm |
| Depth | 669 mm |
| Net Weight | 330 kg |
| Analogue Input Number | 3 |
| Analogue Input Type | Al1, Al2, Al3 software-configurable voltage: $0 . . .10 \mathrm{~V}$ DC, impedance: 31.5 kOhm , resolution 12 bits <br> Al1, Al2, Al3 software-configurable current: $0 . . .20 \mathrm{~mA}$, impedance: 250 Ohm, resolution 12 bits AI2 voltage analog input: - $10 \ldots 10 \mathrm{~V}$ DC, impedance: 31.5 kOhm , resolution 12 bits |
| Discrete Input Number | 8 |
| Discrete Input Type | DI7, DI8 programmable as pulse input: $0 \ldots 30 \mathrm{kHz}, 24 \mathrm{~V} \mathrm{DC}(<=30 \mathrm{~V})$ |
| Input Compatibility | DI5, DI6: discrete input level 1 PLC conforming to IEC 65A-68 STOA, STOB: discrete input level 1 PLC conforming to IEC 61131-2 DI1...DI6: discrete input level 1 PLC conforming to IEC 61131-2 |
| Discrete Input Logic | Positive logic (source) (DI1...DI8), < 5 V (state 0), > 11 V (state 1) Negative logic (sink) (DI1...DI8), > 16 V (state 0), < 10 V (state 1) |
| Analogue Output Number | 2 |
| Analogue Output Type | Software-configurable voltage AQ1, AQ2: $0 . . .10 \mathrm{~V}$ DC impedance 470 Ohm, resolution 10 bits <br> Software-configurable current AQ1, AQ2: $0 \ldots 20 \mathrm{~mA}$, resolution 10 bits <br> Software-configurable current DQ-, DQ+: 30 V DC <br> Software-configurable current DQ-, DQ+: 100 mA |
| Sampling Duration | $\begin{aligned} & 5 \mathrm{~ms}+/-1 \mathrm{~ms} \text { (DI5, DI6) - discrete input } \\ & 5 \mathrm{~ms}+/-0.1 \mathrm{~ms} \text { (AI1, Al2, Al3) - analog input } \\ & 10 \mathrm{~ms}+/-1 \mathrm{~ms} \text { (AO1) - analog output } \\ & 2 \mathrm{~ms}+/-0.5 \mathrm{~ms} \text { (DI1...DI4) - discrete input } \end{aligned}$ |


| Accuracy | +/- $1 \% \mathrm{AO} 1, \mathrm{AO} 2$ for a temperature variation $60^{\circ} \mathrm{C}$ analog output <br> $+/-0.6 \% \mathrm{Al1}, \mathrm{Al2}, \mathrm{Al} 3$ for a temperature variation $60^{\circ} \mathrm{C}$ analog input |
| :---: | :---: |
| Linearity Error | AO1, AO2: +/- 0.2 \% for analog output <br> Al1, Al2, Al3: +/- $0.15 \%$ of maximum value for analog input |
| Relay Output Number | 3 |
| Relay Output Type | Configurable relay logic R2: sequence relay NO electrical durability 100000 cycles Configurable relay logic R3: sequence relay NO electrical durability 100000 cycles Configurable relay logic R1: fault relay NO/NC electrical durability 100000 cycles |
| Refresh Time | Relay output (R1, R2, R3): $5 \mathrm{~ms}(+/-0.5 \mathrm{~ms})$ |
| Minimum Switching Current | Relay output R1, R2, R3: 5 mA at 24 V DC |
| Maximum Switching Current | Relay output R1, R2, R3 on resistive load, cos phi $=1: 3 \mathrm{~A}$ at 30 VDC <br> Relay output R1, R2, R3 on inductive load, cos phi $=0.4$ and $L / R=7 \mathrm{~ms}: 2 \mathrm{~A}$ at 250 <br> V AC <br> Relay output R1, R2, R3 on inductive load, cos phi $=0.4$ and $\mathrm{L} / \mathrm{R}=7 \mathrm{~ms}$ : 2 A at 30 V DC <br> Relay output R1, R2, R3 on resistive load, $\cos$ phi $=1: 3 \mathrm{~A}$ at 250 V AC |
| Isolation | Between power and control terminals |
| Maximum Output Frequency | 500 kHz |
| Maximum Input Current | 291.0 A |
| Variable Speed Drive Application Selection | Food and beverage processing other application <br> Mining mineral and metal fan <br> Mining mineral and metal pump <br> Oil and gas fan <br> Water and waste water other application <br> Building - HVAC screw compressor <br> Food and beverage processing pump <br> Food and beverage processing fan <br> Food and beverage processing atomization <br> Oil and gas electro submersible pump (ESP) <br> Oil and gas water injection pump <br> Oil and gas jet fuel pump <br> Oil and gas compressor for refinery <br> Water and waste water centrifuge pump <br> Water and waste water positive displacement pump <br> Water and waste water electro submersible pump (ESP) <br> Water and waste water screw pump <br> Water and waste water lobe compressor <br> Water and waste water screw compressor <br> Water and waste water compressor centrifugal <br> Water and waste water fan <br> Water and waste water conveyor <br> Water and waste water mixer <br> Building - HVAC compressor centrifugal |
| Motor Power Range Ac-3 | 110... 220 kW at $480 . . .500 \mathrm{~V} 3$ phases 110... 220 kW at $380 . . .440 \mathrm{~V} 3$ phases |
| Quantity Per Set | 1 |
| Enclosure Mounting | Floor-standing |
| Environment |  |
| Insulation Resistance | > 1 MOhm 500 V DC for 1 minute to earth |
| Noise Level | 69 dB conforming to 86/188/EEC |
| Power Dissipation In W | 2520 W , switching frequency 2.5 kHz (heavy duty) 3120 W , switching frequency 2.5 kHz (normal duty) |
| Volume Of Cooling Air | $720 \mathrm{~m} 3 / \mathrm{h}$ |
| Operating Position | Vertical +/-10 degree |
| Maximum Thdi | <48 \% full load conforming to IEC 61000-3-12 |


| Electromagnetic Compatibility | Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3 <br> Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4 $1.2 / 50 \mu \mathrm{~s}-8 / 20 \mu \mathrm{~s}$ surge immunity test level 3 conforming to IEC 61000-4-5 Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6 Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2 |
| :---: | :---: |
| Pollution Degree | 2 conforming to IEC 61800-5-1 |
| Vibration Resistance | 1 gn ( $\mathrm{f}=13 \ldots 200 \mathrm{~Hz}$ ) conforming to IEC 60068-2-6 1.5 mm peak to peak ( $\mathrm{f}=2 \ldots . .13 \mathrm{~Hz}$ ) conforming to IEC $60068-2-6$ |
| Shock Resistance | 15 gn for 11 ms conforming to IEC 60068-2-27 |
| Relative Humidity | $5 . . .95 \%$ without condensation conforming to IEC 60068-2-3 |
| Ambient Air Temperature For Operation | $40 . . .50^{\circ} \mathrm{C}$ (with derating factor) <br> $-15 . .40^{\circ} \mathrm{C}$ (without derating) |
| Ambient Air Temperature For Storage | $-40 . .70^{\circ} \mathrm{C}$ |
| Operating Altitude | $1000 \ldots 4800 \mathrm{~m}$ with current derating $1 \%$ per 100 m <= 1000 m without derating |
| Product Certifications | ATEX EAC C-Tick |
| Marking | CE |
| Standards | IEC 60204-1 <br> IEC 61800-2 <br> IEC 61800-3 <br> IEC 61800-5-1 |
| Overvoltage Category | III |
| Regulation Loop | Adjustable PID regulator |
| Noise Level | 69 dB |
| Pollution Degree | 3 |
| Packing Units |  |
| Unit Type Of Package 1 | PCE |
| Number Of Units In Package 1 | 1 |
| Package 1 Height | 229 cm |
| Package 1 Width | 111 cm |
| Package 1 Length | 120 cm |
| Package 1 Weight | 370.0 kg |

## Sustainability

Green Premium ${ }^{\text {TM }}$ label is Schneider Electric's commitment to delivering products with best-inclass environmental performance. Green Premium promises compliance with the latest regulations, transparency on environmental impacts, as well as circular and low- $\mathrm{CO}_{2}$ products.
Guide to assessing product sustainability is a white paper that clarifies global eco-label standards and how to interpret environmental declarations.
Learn more about Green Premium >
Guide to assess a product's sustainability >

Take-back

## Resource performance

Take-Back Program Available

## Well-being performance

(V) Mercury Free
( Rohs Exemption Information Yes

| Reach Regulation | REACh Declaration |
| :--- | :--- |
| Eu Rohs Directive | Pro-active compliance (Product out of EU RoHS legal scope) |
| China Rohs Regulation | China RoHS declaration |
| Weee | The product must be disposed on European Union markets following specific waste <br> collection and never end up in rubbish bins |

Product data sheet

Dimensions Drawings

Dimensions

Right and Front Views



Product data sheet
ATV650C16N4F

Mounting and Clearance
Clearances


Connections and Schema

Floor Standing Drive Circuit Diagram


F1 External pre-fuse or circuit breaker
MS Built-in main switch (only available on IP54 drives)
T01 Control transformer 400 / 230 V AC
MF aR fuses
RFI Built-in RFI filter
LC Line reactor choke
REC Rectifier module
INV Inverter module
FC dv/dt filter (from 355 kW the dv/dt filter choke 150 m is built-in as standard)
CTRL Control panel
M11 Fan in enclosure door

## Control Block Wiring Diagram


(1) Safe Torque Off
(2) Analog Output
(3) Digital Input
(4) Reference potentiometer
(5) Analog Input

R1A, R1B, R1C : Fault relay
R2A, R2C : Sequence relay
R3A, R3C : Sequence relay

## Sensor Connection

It is possible to connect either 1 or 3 sensors on terminals Al 2 or Al 3 .


## Product data sheet

The switch is used to adapt the operation of the logic inputs to the technology of the programmable controller outputs.

- Set the switch to Source (factory setting) if using PLC outputs with PNP transistors.
- Set the switch to Ext if using PLC outputs with NPN transistors.

Switch Set to SRC (Source) Position Using the Output Power Supply for the Digital Inputs


Switch Set to SRC (Source) Position and Use of an External Power Supply for the DIs


Switch Set to SK (Sink) Position Using the Output Power Supply for the Digital Inputs


Switch Set to EXT Position Using an External Power Supply for the DIs


## Performance Curves

Derating Curves

Normal Duty


- ாாாாำ $30^{\circ} \mathrm{C}\left(86^{\circ} \mathrm{F}\right)$
$-40^{\circ} \mathrm{C}\left(104{ }^{\circ} \mathrm{F}\right)$

$-50^{\circ} \mathrm{C}\left(140^{\circ} \mathrm{F}\right) \mathrm{C}$
In : Nominal Drive Current
SF: Switching Frequency


## Heavy Duty



-     -         -             -                 - $=30^{\circ} \mathrm{C}\left(86^{\circ} \mathrm{F}\right)$
$-40^{\circ} \mathrm{C}\left(104{ }^{\circ} \mathrm{F}\right)$

$-50^{\circ} \mathrm{C}\left(140^{\circ} \mathrm{F}\right) \mathrm{C}$
In : Nominal Drive Current
SF: Switching Frequency

