## Product data sheet

Specifications
variable speed drive, Altivar Process
ATV600, ATV650, 18.5kW, 400 to
480 V, IP55

ATV650D18N4

| Main |  |
| :---: | :---: |
| Range Of Product | Altivar Process ATV600 |
| Product Or Component Type | Variable speed drive |
| Product Specific Application | Process and utilities |
| Device Short Name | ATV650 |
| Variant | Standard version |
| Product Destination | Asynchronous motors Synchronous motors |
| Emc Filter | Integrated with 50 m conforming to IEC 61800-3 category C2 Integrated with 150 m conforming to IEC 61800-3 category C3 |
| Ip Degree Of Protection | IP55 conforming to IEC 60529 IP55 conforming to IEC 61800-5-1 |
| [Us] Rated Supply Voltage | $380 . .480 \mathrm{~V}$ |
| Type Of Cooling | Forced convection |
| Supply Frequency | $50 \ldots . .60 \mathrm{~Hz}-5 . .5$ \% |
| [Us] Rated Supply Voltage | 380... 480 V - 15... 10 \% |
| Motor Power Kw | 15.0 kW (heavy duty) 18.5 kW (normal duty) |
| Motor Power Hp | 15 hp heavy duty 25 hp normal duty |
| Line Current | 23.3 A at 480 V (normal duty) 20.6 A at 380 V (heavy duty) 18.1 A at 480 V (heavy duty) 33.4 A at 380 V (normal duty) |
| Prospective Line Isc | 50 kA |
| Apparent Power | 15 kVA at 480 V (heavy duty) 24 kVA at 480 V (normal duty) |
| Continuous Output Current | 23.5 A at 4 kHz for heavy duty 39.2 A at 4 kHz for normal duty |
| Asynchronous Motor Control Profile | Optimized torque mode Variable torque standard Variable torque standard |
| Synchronous Motor Control Profile | Synchronous reluctance motor Permanent magnet motor |
| Speed Drive Output Frequency | $0.1 \ldots 500 \mathrm{~Hz}$ |
| Nominal Switching Frequency | 4 kHz |
| Switching Frequency | $4 . . .12 \mathrm{kHz}$ with derating factor <br> 2... 12 kHz adjustable |
| Safety Function | STO (safe torque off) SIL 3 |


| Discrete Input Logic | 16 preset speeds |
| :--- | :--- |
| Communication Port Protocol | Modbus TCP <br> Modbus serial <br>  <br>  <br>  <br> Modbus TCP |
| Option Card | Slot A: communication module, PROFINET |
|  | Slot A: communication module, DeviceNet |
|  | Slot A: communication module, Modbus TCP/EtherNet/IP |
|  | Slot A: communication module, CANopen daisy chain RJ45 |
|  | Slot A: communication module, CANopen SUB-D 9 |
|  | SSot A: communication module, CANopen screw terminals |
|  | Slot A/slot B: digital and analog I/O extension module |
|  | Slot A/slot B: output relay extension module |
|  | Slot A: communication module, Ethernet IP/Modbus TCP/MD-Link |
|  | Communication module, BACnet MS/TP |
|  | Communication module, Ethernet Powerlink |
|  | Slot A: communication module, Profibus DP V1 |

Complementary

| Mounting Mode | Wall mount |
| :---: | :---: |
| Maximum Transient Current | 35.3 A during 60 s (heavy duty) <br> 43.1 A during 60 s (normal duty) |
| Network Number Of Phases | 3 phases |
| Discrete Output Number | 0 |
| Discrete Output Type | Relay outputs R1A, R1B, R1C 250 V AC 3000 mA Relay outputs R1A, R1B, R1C 30 V DC 3000 mA Relay outputs R2A, R2C 250 V AC 5000 mA Relay outputs R2A, R2C 30 V DC 5000 mA Relay outputs R3A, R3C 250 V AC 5000 mA Relay outputs R3A, R3C 30 V DC 5000 mA |
| Output Voltage | <= power supply voltage |
| Permissible Temporary Current Boost | $1.5 \mathrm{x} \ln$ during 60 s (heavy duty) <br> 1.1 x In during 60 s (normal duty) |
| Motor Slip Compensation | Adjustable <br> Not available in permanent magnet motor law Automatic whatever the load Automatic whatever the load |
| Acceleration And Deceleration Ramps | Linear adjustable separately from 0.01...9999 s |
| Physical Interface | Ethernet <br> 2-wire RS 485 |
| Braking To Standstill | By DC injection |
| Protection Type | Safe torque off: motor <br> Motor phase break: motor <br> Thermal protection: drive <br> Safe torque off: drive <br> Overheating: drive <br> Overcurrent between output phases and earth: drive <br> Overload of output voltage: drive <br> Short-circuit protection: drive <br> Motor phase break: drive <br> Overvoltages on the DC bus: drive <br> Line supply overvoltage: drive <br> Line supply undervoltage: drive <br> Line supply phase loss: drive <br> Overspeed: drive <br> Break on the control circuit: drive <br> Thermal protection: motor |
| Transmission Rate | 10, 100 Mbits <br> 4800 bps, 9600 bps, 19200 bps, 38.4 Kbps |
| Frequency Resolution | Analog input: $0.012 / 50 \mathrm{~Hz}$ Display unit: 0.1 Hz |
| Transmission Frame RTU |  |


| Electrical Connection | Line side: screw terminal $10 \ldots 16 \mathrm{~mm}^{2} /$ AWG $8 . .$. AWG 6 <br> Motor: screw terminal $10 \ldots 16 \mathrm{~mm}^{2} /$ AWG $8 . . . A W G 6$ <br> Control: removable screw terminals 0.5 ... $1.5 \mathrm{~mm}^{2} /$ AWG 20...AWG 16 |
| :---: | :---: |
| Connector Type | RJ45 (on the remote graphic terminal) for Modbus serial RJ45 (on the remote graphic terminal) for Ethernet/Modbus TCP |
| Data Format | 8 bits, configurable odd, even or no parity |
| Type Of Polarization | No impedance |
| Exchange Mode | Half duplex, full duplex, autonegotiation Ethernet/Modbus TCP |
| Number Of Addresses | 1... 247 for Modbus serial |
| Method Of Access | Slave Modbus TCP |
| Supply | Internal supply for reference potentiometer ( 1 to 10 kOhm ): 10.5 V DC $+/-5 \%,<10$ mA , protection type: overload and short-circuit protection <br> Internal supply for digital inputs and STO: 24 V DC ( $21 \ldots 27$ V), $<200 \mathrm{~mA}$, protection type: overload and short-circuit protection <br> External supply for digital inputs: 24 V DC ( $19 \ldots 30 \mathrm{~V}$ ),$<1.25 \mathrm{~mA}$, protection type: overload and short-circuit protection |
| Local Signalling | 3 LEDs (dual colour) for embedded communication status 4 LEDs (dual colour) for communication module status 1 LED (red) for presence of voltage 3 LEDs for local diagnostic |
| Width | 264 mm |
| Height | 678 mm |
| Depth | 299 mm |
| Net Weight | 20.6 kg |
| Analogue Input Number | 3 |
| Analogue Input Type | Al1, Al2, Al3 software-configurable voltage: $0 . . .10 \mathrm{~V}$ DC, impedance: 31.5 kOhm , resolution 12 bits <br> Al1, Al2, Al3 software-configurable current: $0 . . .20 \mathrm{~mA}$, impedance: 250 Ohm, resolution 12 bits Al2 voltage analog input: - $10 \ldots 10 \mathrm{~V}$ DC, impedance: 31.5 kOhm , resolution 12 bits |
| Discrete Input Number | 8 |
| Discrete Input Type | DI7, DI8 programmable as pulse input: $0 \ldots .30 \mathrm{kHz}, 24 \mathrm{~V}$ DC (<= 30 V ) |
| Input Compatibility | DI5, DI6: discrete input level 1 PLC conforming to IEC 65A-68 STOA, STOB: discrete input level 1 PLC conforming to IEC 61131-2 DI1...DI6: discrete input level 1 PLC conforming to IEC 61131-2 |
| Discrete Input Logic | Positive logic (source) (DI1...DI8), < 5 V (state 0 ), > 11 V (state 1 ) Negative logic (sink) (DI1...DI8), > 16 V (state 0 ), < 10 V (state 1) |
| Analogue Output Number | 2 |
| Analogue Output Type | Software-configurable voltage AQ1, AQ2: $0 . .10 \mathrm{~V}$ DC impedance 470 Ohm, resolution 10 bits <br> Software-configurable current AQ1, AQ2: $0 \ldots 20 \mathrm{~mA}$, resolution 10 bits <br> Software-configurable current DQ-, DQ+: 30 V DC <br> Software-configurable current DQ-, DQ+: 100 mA |
| Sampling Duration | $\begin{aligned} & 5 \mathrm{~ms}+/-1 \mathrm{~ms}(\text { DI5, DI6) - discrete input } \\ & 5 \mathrm{~ms}+/-0.1 \mathrm{~ms}(\text { AI1, AI2, Al3) - analog input } \\ & 10 \mathrm{~ms}+/-1 \mathrm{~ms} \text { (AO1) - analog output } \\ & 2 \mathrm{~ms}+/-0.5 \mathrm{~ms} \text { (DI1...DI4) - discrete input } \end{aligned}$ |
| Accuracy | +/- $1 \%$ AO1, AO2 for a temperature variation $60^{\circ} \mathrm{C}$ analog output <br> $+/-0.6 \% \mathrm{Al1}, \mathrm{Al} 2, \mathrm{Al} 3$ for a temperature variation $60^{\circ} \mathrm{C}$ analog input |
| Linearity Error | AO1, AO2: +/- 0.2 \% for analog output <br> Al1, Al2, Al3: +/- $0.15 \%$ of maximum value for analog input |
| Relay Output Number | 3 |
| Relay Output Type | Configurable relay logic R2: sequence relay NO electrical durability 100000 cycles Configurable relay logic R3: sequence relay NO electrical durability 100000 cycles Configurable relay logic R1: fault relay NO/NC electrical durability 100000 cycles |


| Refresh Time | Relay output (R1, R2, R3): 5 ms ( $+/-0.5 \mathrm{~ms}$ ) |
| :---: | :---: |
| Minimum Switching Current | Relay output R1, R2, R3: 5 mA at 24 V DC |
| Maximum Switching Current | Relay output R1, R2, R3 on resistive load, cos phi $=1: 3 \mathrm{~A}$ at $30 \mathrm{~V} D$ <br> Relay output R1, R2, R3 on inductive load, cos phi $=0.4$ and $\mathrm{L} / \mathrm{R}=7 \mathrm{~ms}: 2 \mathrm{~A}$ at 250 <br> V AC <br> Relay output R1, R2, R3 on inductive load, cos phi $=0.4$ and $L / R=7 \mathrm{~ms}: 2 \mathrm{~A}$ at 30 V DC <br> Relay output R1, R2, R3 on resistive load, cos phi $=1: 3 \mathrm{~A}$ at 250 V AC |
| Isolation | Between power and control terminals |
| Maximum Output Frequency | 500 kHz |
| Maximum Input Current | 33.4 A |
| Variable Speed Drive Application Selection | Building - HVAC compressor centrifugal |
| Motor Power Range Ac-3 | 15... 25 kW at $380 \ldots 440 \mathrm{~V} 3$ phases |
| Quantity Per Set | 1 |
| Enclosure Mounting | Wall mounted |

## Environment

| Insulation Resistance | > 1 MOhm 500 V DC for 1 minute to earth |
| :---: | :---: |
| Noise Level | 53.7 dB conforming to $86 / 188 /$ EEC |
| Operating Position | Vertical +/- 10 degree |
| Maximum Thdi | <48 \% from 80... 100 \% of load conforming to IEC 61000-3-12 |
| Electromagnetic Compatibility | Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3 <br> Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4 $1.2 / 50 \mu \mathrm{~s}-8 / 20 \mu \mathrm{~s}$ surge immunity test level 3 conforming to IEC 61000-4-5 Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6 Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2 |
| Pollution Degree | 2 conforming to IEC 61800-5-1 |
| Vibration Resistance | $1 \mathrm{gn}(\mathrm{f}=13 \ldots 200 \mathrm{~Hz}$ ) conforming to IEC 60068-2-6 1.5 mm peak to peak ( $\mathrm{f}=2 \ldots 13 \mathrm{~Hz}$ ) conforming to IEC 60068-2-6 |
| Shock Resistance | 15 gn for 11 ms conforming to IEC 60068-2-27 |
| Relative Humidity | $5 . . .95 \%$ without condensation conforming to IEC 60068-2-3 |
| Ambient Air Temperature For Operation | $40 \ldots 50^{\circ} \mathrm{C}$ (with derating factor) <br> $-15 . .40^{\circ} \mathrm{C}$ (without derating) |
| Ambient Air Temperature For Storage | $-40 \ldots .70^{\circ} \mathrm{C}$ |
| Operating Altitude | $1000 . . .4800 \mathrm{~m}$ with current derating $1 \%$ per 100 m <= 1000 m without derating |
| Product Certifications | CSA <br> Bureau Veritas TÜV <br> ATEX INERIS DNV-GL ABS |
| Marking | CE |
| Standards | IEC 61800-3 <br> IEC 61800-3 environment 1 category C2 <br> EN/IEC 61800-3 environment 2 category C3 <br> IEC 61800-5-1 <br> IEC 61000-3-12 <br> IEC 60721-3 <br> IEC 61508 <br> IEC 13849-1 <br> UL 508C |


| Overvoltage Category | III |
| :--- | :--- |
| Regulation Loop | Adjustable PID regulator |
| Noise Level | 53.7 dB |
| Pollution Degree | 3 |
| Packing Units | PCE |
| Unit Type Of Package 1 | 1 |
| Number Of Units In Package 1 | 75.0 cm |
| Package 1 Height | 60.0 cm |
| Package 1 Width | 80.0 cm |
| Package 1 Length | 31.5 kg |

## Sustainability

Green Premium ${ }^{\text {TM }}$ label is Schneider Electric's commitment to delivering products with best-inclass environmental performance. Green Premium promises compliance with the latest regulations, transparency on environmental impacts, as well as circular and low- $\mathrm{CO}_{2}$ products.
Guide to assessing product sustainability is a white paper that clarifies global eco-label standards and how to interpret environmental declarations.
Learn more about Green Premium >
Guide to assess a product's sustainability >


Transparency RoHS/REACh

## Resource performance

Upgraded Components Available

Well-being performance
(V) Mercury Free
(V) Rohs Exemption Information

Yes

Certifications \& Standards
Reach Regulation REACh Declaration

| Eu Rohs Directive | Pro-active compliance (Product out of EU RoHS legal scope) |
| :--- | :--- |
| China Rohs Regulation | China RoHS declaration |
| Environmental Disclosure | Product Environmental Profile |
| Weee | The product must be disposed on European Union markets following specific waste <br> collection and never end up in rubbish bins |
| Circularity Profile | End of Life Information |

## California Proposition 65

WARNING: This product can expose you to chemicals including: Lead and lead compounds, which is known to the State of California to cause cancer and birth defects or other reproductive harm. For more information go to www.P65Warnings.ca.gov

Dimensions Drawings

Dimensions

Front and Left Views

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mm

(a) $=299 \mathrm{~mm}$ (11.8 in.)

Mounting and Clearance

Clearances


## Product data sheet

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## Connections and Schema

## Three-Phase Power Supply with Upstream Breaking via Line Contactor

Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1

(1) Line choke if used
(2) Use relay R1 set to operating state Fault to switch Off the product once an error is detected.

A1: Drive
KM1 : Line Contactor
Q2, Q3 : Circuit breakers
S1, S2 : Pushbuttons
T1 : Transformer for control part

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## Three-Phase Power Supply with Downstream Breaking via Contactor

Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1

(1) Line choke if used
(2) Use relay R1 set to operating state Fault to switch Off the product once an error is detected.

A1 : Drive
KM1 : Contactor

## Control Block Wiring Diagram


(1) Safe Torque Off
(2) Analog Output
(3) Digital Input
(4) Reference potentiometer
(5) Analog Input

R1A, R1B, R1C : Fault relay
R2A, R2C : Sequence relay
R3A, R3C : Sequence relay

## Sensor Connection

It is possible to connect either 1 or 3 sensors on terminals AI2 or Al3.


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The switch is used to adapt the operation of the logic inputs to the technology of the programmable controller outputs.

- Set the switch to Source (factory setting) if using PLC outputs with PNP transistors.
- Set the switch to Ext if using PLC outputs with NPN transistors.

Switch Set to SRC (Source) Position Using the Output Power Supply for the Digital Inputs


Switch Set to SRC (Source) Position and Use of an External Power Supply for the DIs


Switch Set to SK (Sink) Position Using the Output Power Supply for the Digital Inputs


Switch Set to EXT Position Using an External Power Supply for the DIs


Performance Curves

Derating Curves

$-40^{\circ} \mathrm{C}\left(104^{\circ} \mathrm{F}\right)$
-
$-50^{\circ} \mathrm{C}\left(122^{\circ} \mathrm{F}\right)$
In : Nominal Drive Current
SF: Switching Frequency

