

Product data sheet

Specifications



enclosed variable speed drive ATV71 Plus - 400 kW - 400V - IP54 - ready to use

ATV71ES5C40N4

⚠ Discontinued - Service only

⚠ Discontinued on: Mar 12, 2021

⚠ To be end-of-service on: Dec 31, 2028

Main

Range Of Product	Altivar 71 Plus
Product Or Component Type	Variable speed drive
Device Short Name	ATV71 Plus
Product Destination	Asynchronous motors Synchronous motors
Product Specific Application	Complex, high-power machines
Assembly Style	In floor-standing enclosure with separate air flows Ready to use
Product Composition	A wired ready-assembled Sarel Spacial 6000 enclosure An IP65 remote mounting kit for graphic display terminal ATV71HC40N4 drive on heatsink Circuit breaker Motor terminals A DC choke A plinth
Emc Filter	Integrated
Network Number Of Phases	3 phases
Rated Supply Voltage	380...415 V +/- 10 %
Supply Voltage Limits	342...457 V
Supply Frequency	50...60 Hz +/- 5 %
Network Frequency	47.5...63 Hz
Motor Power Kw	400 kW at 380...415 V
Line Current	675 A for 400 V / 400 kW

Complementary

Apparent Power	467 kVA for 400 V / 400 kW
Prospective Line Isc	50 kA with external fuses
Continuous Output Current	759 A at 2.5 kHz, 400 V / 400 kW
Maximum Transient Current	1139 A for 60 s / 400 kW / 600 hp 1252 A for 2 s / 400 kW / 600 hp
Speed Drive Output Frequency	0.1...500 Hz
Nominal Switching Frequency	2.5 kHz
Switching Frequency	2...8 kHz adjustable 2.5...8 kHz with derating factor

Disclaimer: This documentation is not intended as a substitute for and is not to be used for determining suitability or reliability of these products for specific user applications

Speed Range	1...1000 for asynchronous motor in closed-loop mode with encoder feedback 1...100 for asynchronous motor in open-loop mode, without speed feedback 1...50 for synchronous motor in open-loop mode, without speed feedback
Speed Accuracy	+/- 0.01 % of nominal speed in closed-loop mode with encoder feedback 0.2 Tn to Tn +/- 10 % of nominal slip without speed feedback 0.2 Tn to Tn
Torque Accuracy	+/- 5 % in closed-loop mode with encoder feedback +/- 15 % in open-loop mode, without speed feedback
Transient Overtorque	170 % of nominal motor torque +/- 10 % for 60 s 220 % of nominal motor torque +/- 10 % for 2 s
Braking Torque	30 % without braking resistor ≤ 150 % with braking or hoist resistor
Asynchronous Motor Control Profile	Flux vector control without sensor, standard Voltage/frequency ratio, 2 points Flux vector control with sensor, standard Flux vector control without sensor, 2 points Voltage/frequency ratio, 5 points Voltage/frequency ratio - Energy Saving, quadratic U/f Flux vector control without sensor, ENA (energy Adaptation) system
Synchronous Motor Control Profile	Vector control with sensor, standard Vector control without sensor, standard
Regulation Loop	Adjustable PI regulator
Motor Slip Compensation	Adjustable Automatic whatever the load Suppressable Not available in voltage/frequency ratio (2 or 5 points)
Overvoltage Category	Class 3 conforming to EN 50178
Local Signalling	LCD display unit for operation function, status and configuration
Output Voltage	≤ supply voltage
Isolation	Electrical between power and control
Type Of Cable For External Connection	IEC cable at 40 °C, copper 70 °C / PVC UL 508 cable at 40 °C, copper 75 °C / PVC
Electrical Connection	Terminal - 2.5 mm ² / AWG 14 (R1A, R1B, R1C, R2A, R2B) bottom entry Screw clamp terminals - 1.5 mm ² (AI1-/AI1+, AI2, AO1, LI1...LI6, PWR) bottom entry Bar M12 - 4 x 300 mm ² (L1/R, L2/S, L3/T) bottom entry Bar M12 - 4 x 240 mm ² (U/T1, V/T2, W/T3) bottom entry
Motor Recommended Cable Cross Section	3 (3 x 185) mm ²
Short-Circuit Protection	1000 A fuse protection type gI - power supply upstream
Supply	External supply: 24 V DC (19...30 V), <1 A Internal supply for reference potentiometer: 10 V DC (10...11 V), <10 mA Internal supply: 24 V DC (21...27 V), <100 mA
Analogue Input Number	2
Analogue Input Type	AI2 software-configurable voltage: 0...10 V DC, 24 V max, impedance: 30000 Ohm, sampling time: 1.5...2.5 ms, resolution: 11 bits AI1-/AI1+ bipolar differential voltage: +/- 10 V DC, 24 V max, sampling time: 1.5...2.5 ms, resolution: 11 bits + sign AI2 software-configurable current: 0...20 mA/4...20 mA, impedance: 250 Ohm, sampling time: 1.5...2.5 ms, resolution: 11 bits
Analogue Output Number	1
Analogue Output Type	Software-configurable voltage: (AO1) 0...10 V DC - 470 Ohm - sampling time: 1.5...2.5 ms - resolution: 10 bits Software-configurable current: (AO1) 0...20 mA/4...20 mA - 500 Ohm - sampling time: 1.5...2.5 ms - resolution: 10 bits
Discrete Output Number	2
Discrete Output Type	Configurable relay logic: (R1A, R1B, R1C)NO/NC - 6.5...7.5 ms - 100000 cycles Configurable relay logic: (R2A, R2B)NO - 6.5...7.5 ms - 100000 cycles
Minimum Switching Current	3 mA at 24 V DC (configurable relay logic)

Maximum Switching Current	5 A at 250 V AC on resistive load - cos phi = 1 (R1, R2) 5 A at 30 V DC on resistive load - L/R = 0 ms (R1, R2) 2 A at 250 V AC on inductive load - cos phi = 0.4 (R1, R2) 2 A at 30 V DC on inductive load - L/R = 7 ms (R1, R2)
Discrete Input Number	7
Discrete Input Type	Programmable (LI1...LI5) at 24 V DC <= 30 V level 1 PLC 3.5 kOhm (duration=1.5...2.5 ms) Switch-configurable (LI6) at 24 V DC <= 30 V level 1 PLC 1.5 kOhm (duration=1.5...2.5 ms) Safety input (PWR) at 24 V DC <= 30 V 1.5 kOhm
Discrete Input Logic	Positive logic (source) (LI1...LI6), 0...5 V (state 0), 11...30 V (state 1) Negative logic (sink) (LI1...LI6), 16...30 V (state 0), 0...10 V (state 1) Positive logic (source) (PWR), 0...2 V (state 0), 17...30 V (state 1)
Acceleration And Deceleration Ramps	S, U or customized Linear adjustable separately from 0.01 to 9000 s
Braking To Standstill	By DC injection
Protection Type	Overheating protection: drive Thermal protection: drive Short-circuit between motor phases: drive Input phase breaks: drive Overcurrent between output phases and earth: drive Overvoltages on the DC bus: drive Break on the control circuit: drive Against exceeding limit speed: drive Line supply undervoltage: drive Line supply overvoltage: drive Against input phase loss: drive Thermal protection: motor Motor phase break: motor Power removal: motor
Dielectric Strength	3535 V DC between earth and power terminals 5092 V DC between control and power terminals
Insulation Resistance	> 1 mOhm 500 V DC for 1 minute to earth
Frequency Resolution	Display unit: 0.1 Hz Analog input: 0.024/50 Hz
Communication Port Protocol	Modbus CANopen
Connector Type	1 RJ45 (on front face) for Modbus 1 RJ45 (on terminal) for Modbus Male SUB-D 9 on RJ45 for CANopen
Physical Interface	2-wire RS 485 for Modbus
Transmission Frame	RTU for Modbus
Transmission Rate	9600 bps, 19200 bps for Modbus on front face 4800 bps, 9600 bps, 19200 bps, 38.4 Kbps for Modbus on terminal 20 kbps, 50 kbps, 125 kbps, 250 kbps, 500 kbps, 1 Mbps for CANopen
Data Format	8 bits, 1 stop, even parity for Modbus on front face 8 bits, odd even or no configurable parity for Modbus on terminal
Type Of Polarization	No impedance for Modbus
Number Of Addresses	1...247 for Modbus 1...127 for CANopen
Method Of Access	Slave CANopen
Operating Position	Vertical +/- 10 degree
Colour Of Enclosure	Light grey (RAL 7035)
Colour Of Base Of Enclosure	Dark grey (RAL 7022)
Height	2362 mm
Width	1400 mm

Depth	642 mm
Net Weight	765 kg

Environment

Electromagnetic Compatibility	Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6 Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3 Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4 1.2/50 µs - 8/20 µs surge immunity test level 3 conforming to IEC 61000-4-5 Voltage dips and interruptions immunity test conforming to IEC 61000-4-11
Pollution Degree	2 conforming to EN/IEC 61800-5-1
Ip Degree Of Protection	IP54
Vibration Resistance	1.5 mm peak to peak (f= 3...10 Hz) conforming to EN/IEC 60068-2-6 0.6 gn (f= 10...200 Hz) conforming to EN/IEC 60068-2-6 3M3 conforming to EN/IEC 60721-3-3
Shock Resistance	4 gn for 11 ms conforming to EN/IEC 60068-2-27 3M2 conforming to EN/IEC 60721-3-3
Noise Level	73 dB conforming to 86/188/EEC
Environmental Characteristic	Without condensation: 3C2 conforming to IEC 60721-3-3 Without condensation: 3S2 conforming to IEC 60721-3-3 Without condensation: 3K3 conforming to IEC 60721-3-3
Relative Humidity	0...95 %
Ambient Air Temperature For Operation	0...40 °C (without derating) 40...50 °C (with current derating of 1.2 % per °C)
Ambient Air Temperature For Storage	-25...70 °C
Volume Of Cooling Air	2300 m3/h
Operating Altitude	<= 1000 m without derating 1000...3000 m with current derating 1 % per 100 m
Standards	EN 55011 class A group 2 EN/IEC 61800-5-1 EN/IEC 61800-3 EN 61800-3 environments 1 category C3 EN 61800-3 environments 2 category C3
Product Certifications	GOST ATEX
Marking	CE

Packing Units

Unit Type Of Package 1	PCE
Number Of Units In Package 1	1
Package 1 Height	240.0 cm
Package 1 Width	62.0 cm
Package 1 Length	142.0 cm
Package 1 Weight	765.0 kg
Unit Type Of Package 2	CAR
Number Of Units In Package 2	1
Package 2 Height	260.0 cm
Package 2 Width	90.0 cm
Package 2 Length	160.0 cm

Package 2 Weight	765.0 kg
------------------	----------

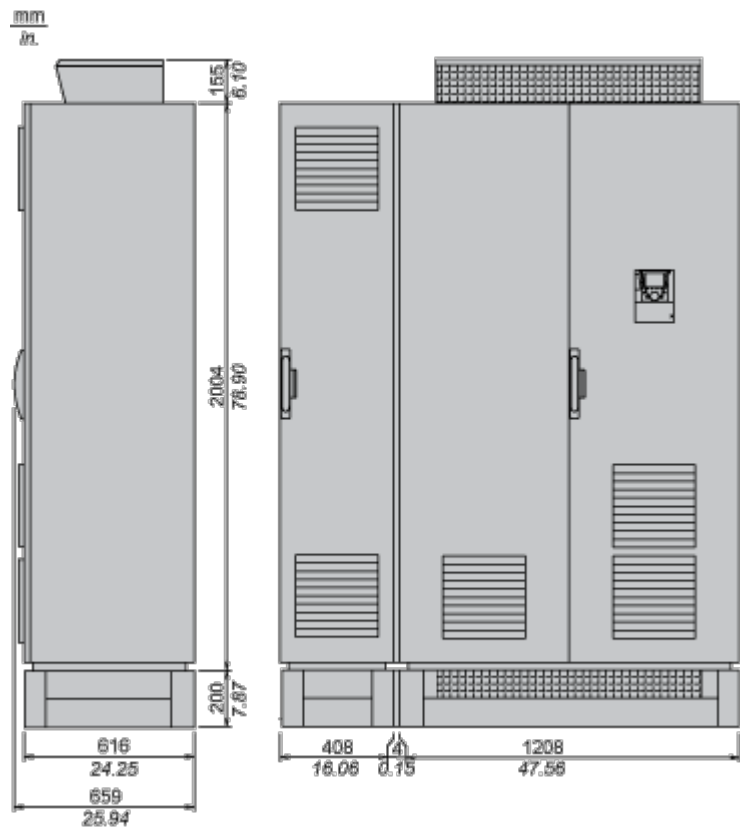
Contractual warranty

Warranty	18 months
----------	-----------

Dimensions Drawings

Ready to Use IP 54 Enclosure

Dimensions

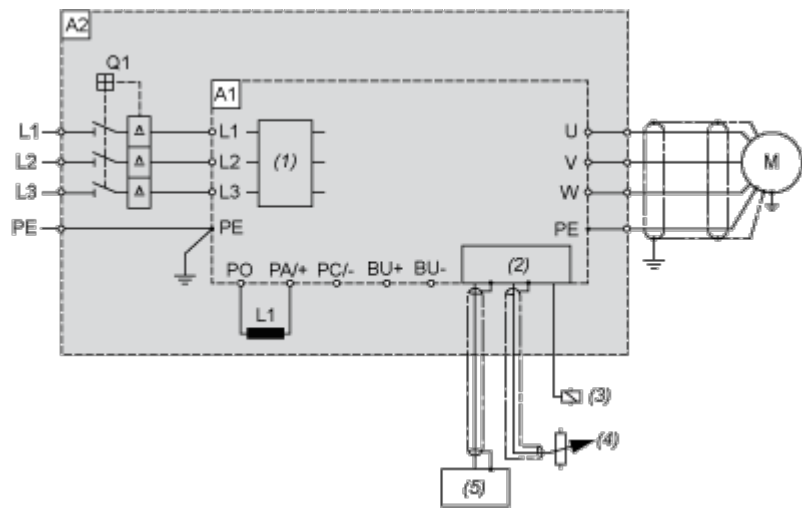


NOTE: For each floor-standing enclosure added, allow a 4 mm/0.15 in. space for the seal.

Connections and Schema

Ready to Use IP 54 Enclosure

Wiring Diagram



- A1 Drive
- A2 Enclosure
- L1 DC choke
- M Motor
- Q1 Circuit breaker
- (1) Filter
- (2) Control
- (3) Relay control
- (4) Reference potentiometer
- (5) PLC

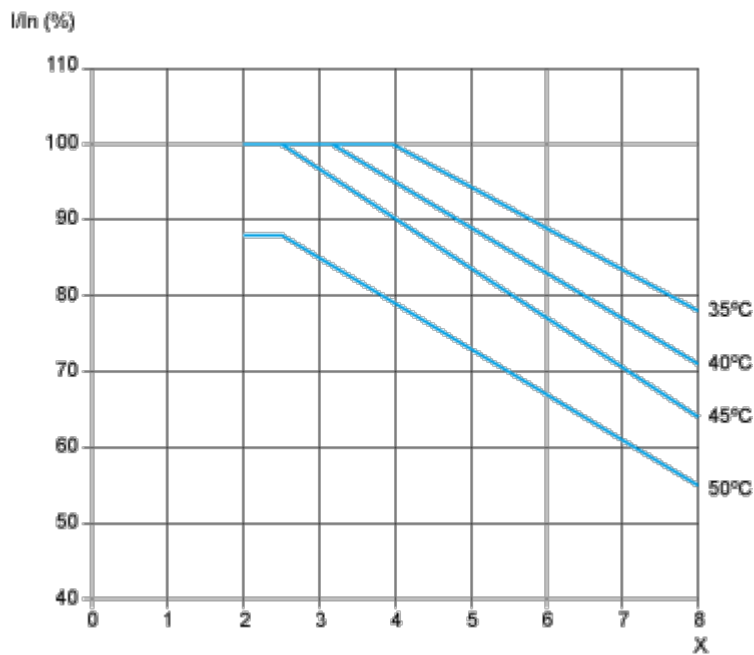
Performance Curves

Ready to Use IP 54 Enclosure

Derating Curves

The derating curves for the drive nominal current (In) are dependent on the temperature and switching frequency. For intermediate temperatures, interpolate between 2 curves.

NOTE: The drive will reduce the switching frequency automatically in the event of excessive temperature rise.



X Switching frequency (kHz)

NOTE: The temperatures shown correspond to the temperature of the air entering the enclosure.